# **Network Compression**

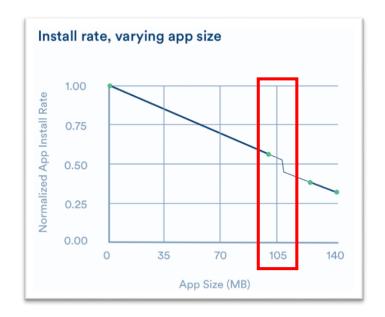
EE807: Recent Advances in Deep Learning
Lecture 16

Slide made by

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KAIST EE

- Deploying deep neural networks (DNNs) has been increasingly difficult
  - Constraints on power consumption, memory usage, inference overhead, ...
- Inference with a large-scale network consumes huge costs
- In mobile apps, such issues become more serious
  - "The dreaded 100MB effect"
- Can we make DNNs to perform inferences more efficiently?







### 1. Network Pruning and Re-wiring

- Optimal brain damage
- Pruning modern DNNs
- Dense-Sparse-Dense training flow

### 2. Sparse Network Learning

- Structured sparsity learning
- Sparsification via variational dropout
- Variational information bottleneck

# 3. Weight Quantization

- Deep compression
- Binarized neural networks

### 4. Summary

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### 3. Weight Quantization

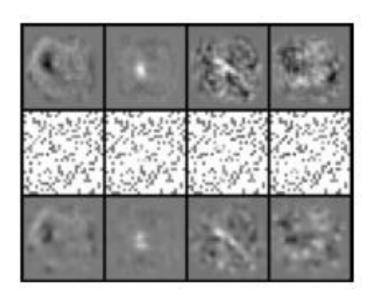
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- Binarized neural networks

### 4. Summary

### Redundancies in Deep Neural Networks [Denil et al., 2013]

- DNNs include a significant number of redundant parameters
- Denil et al. (2013): Predicting > 95% of weights from < 5%</li>
  - A simple kernel ridge regression is sufficient
  - ... without any drop in accuracy!
  - Many of the weights need not be learned at all

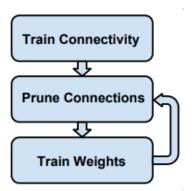
- (a) Original weights
- (b) Randomly selected
- (c) Predicted from (b)



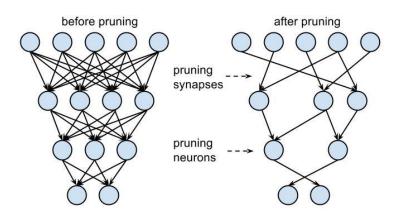
Such redundancy can be exploited via network pruning

#### **Network Pruning**

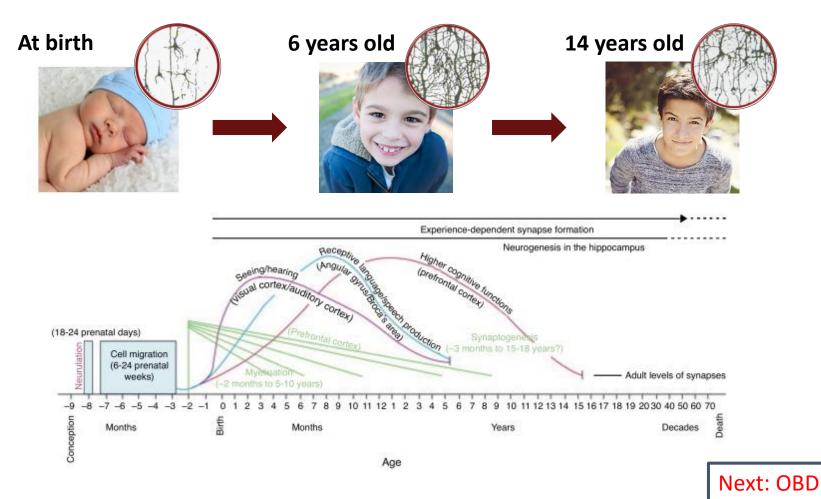
- Determining low-saliency parameters, given a pre-trained network
- Follows the framework proposed by LeCun et al. (1990):
  - **Train** a deep model until convergence
  - **Delete** "unimportant" connections w.r.t. a certain criteria
  - **Re-train** the network
  - **Iterate** to step 2, or stop



- Defining which connection is unimportant can vary
  - Weight magnitudes (L<sup>2</sup>, L<sup>1</sup>, ...)
  - Mean activation [Molchanov et al., 2016]
  - Avg. % of Zeros (APoZ) [Hu et al., 2016]
  - Low entropy activation [Luo et al., 2017]



- Human brains are also using pruning schemes as well
- Synaptic pruning removes redundant synapses in the brain during lifetime



### Optimal Brain Damage (OBD) [LeCun et al., 1990]

- Network pruning **perturbs weights W** by **zeroing** some of them
- How the loss L would be changed when  $\mathbf{W}$  is perturbed?
- **OBD** approximates L by the  $2^{nd}$  order Taylor series:

$$\delta L \simeq \underbrace{\sum_{i} \frac{\partial L}{\partial w_{i}} \delta w_{i}}_{\text{1st order}} + \underbrace{\frac{1}{2} \sum_{i} \frac{\partial^{2} L}{\partial w_{i}^{2}} \delta w_{i}^{2} + \frac{1}{2} \sum_{i,j} \frac{\partial^{2} L}{\partial w_{i} \partial w_{j}} \delta w_{i} \delta w_{j}}_{\text{2nd order}} + O(||\delta \mathbf{W}||^{3})$$

- **Problem:** Computing  $H=\left(\frac{\partial L}{\partial w_i\partial w_j}\right)_{i=1}$  is usually intractable
  - Requires  $O(n^2)$  on # weights
  - Neural networks usually have enormous number of weights
    - e.g. AlexNet: **60M** parameters  $\Rightarrow H$  consists  $\approx 3.6 \times 10^{15}$  elements

### Optimal Brain Damage (OBD) [LeCun et al., 1990]

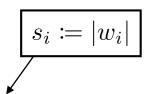
- **Problem:** Computing  $H=\left(\frac{\partial L}{\partial w_i\partial w_j}\right)_{i,j}$  is usually intractable
- Two additional assumptions for tractability
  - **1. Diagonal** approximation:  $H = \frac{\partial^2 L}{\partial w_i \partial w_j} = 0$  if  $i \neq j$
  - **2. Extremal** assumption:  $\frac{\partial L}{\partial w_i} = 0 \quad \forall i$ 
    - W would be in a local minima if it's pre-trained
- Now we get:  $\delta L \simeq \frac{1}{2} \sum_i \frac{\partial^2 L}{\partial w_i^2} \delta w_i^2 + O(||\delta \mathbf{W}||^3)$ 
  - It only needs  $\operatorname{diag}^{i}(H) \coloneqq \left(\frac{\partial^{2} L}{\partial w_{i}^{2}}\right)_{i}$
- diag(H) can be computed in O(n), allowing a backprop-like algorithm
  - For details, see [LeCun et al., 1987]

### Optimal Brain Damage (OBD) [LeCun et al., 1990]

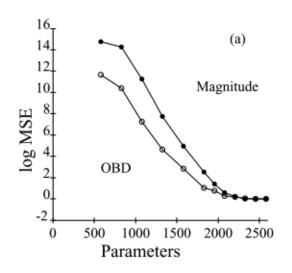
How the loss L would be changed when W is perturbed?

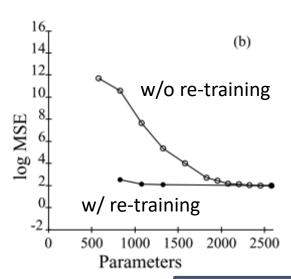
$$L(\delta \mathbf{W}) \simeq \frac{1}{2} \sum_{i} \frac{\partial^{2} L}{\partial w_{i}^{2}} \delta w_{i}^{2} =: \sum_{i} \frac{1}{2} h_{ii} \delta w_{i}^{2}$$

• The **saliency** for each weight  $\Rightarrow s_i \coloneqq \frac{1}{2} h_{ii} |w_i|^2$ 



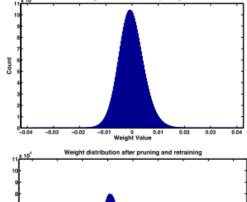
- OBD shows robustness on pruning compared to magnitude-based deletion
- After re-training, the original test accuracy is recovered

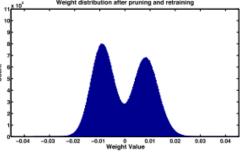




Next: Pruning modern DNNs

- Han et al. (2015): Pruning larger DNNs
  - LeNet, AlexNet, VGG-16, ... on ImageNet
  - Highlights the practical efficiency of pruning
- OBD introduces extra computation on larger models
  - It requires an additional, separated backward pass
- The simple magnitude-based pruning works very well as long as the network is re-trained





#### Comparison with other model reduction methods on AlexNet

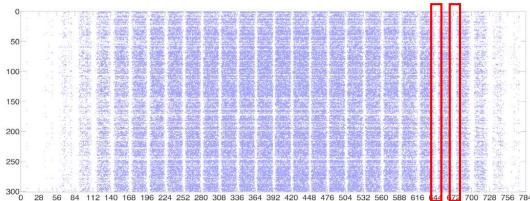
Network	Top-1 Error	Top-5 Error	Parameters	Compression Rate
Baseline Caffemodel [26]	42.78%	19.73%	61.0M	1×
Data-free pruning [28]	44.40%	-	39.6M	1.5×
Fastfood-32-AD [29]	41.93%	-	32.8M	$2\times$
Fastfood-16-AD [29]	42.90%	-	16.4M	3.7×
Collins & Kohli [30]	44.40%	-	15.2M	$4\times$
Naive Cut	47.18%	23.23%	13.8M	4.4×
SVD [I2]	44.02%	20.56%	11.9M	$5 \times$
Network Pruning	42.77%	19.67%	6.7M	9×

- Han et al. (2015): Pruning larger DNNs
  - Highlights the practical efficiency of pruning
- The magnitude-based pruning works well as long as the network is re-trained

Network	Top-1 Error	Top-5 Error	Parameters	Compression Rate
LeNet-300-100 Ref	1.64%	-	267K	
LeNet-300-100 Pruned	1.59%	-	22K	12×
LeNet-5 Ref	0.80%	-	431K	
LeNet-5 Pruned	0.77%	-	36K	12×
AlexNet Ref	42.78%	19.73%	61M	
AlexNet Pruned	42.77%	19.67%	6.7M	9×
VGG-16 Ref	31.50%	11.32%	138M	
VGG-16 Pruned	31.34%	10.88%	10.3M	13×

Network pruning detects visual attention regions





- The magnitude-based pruning works well as long as the network is re-trained
- Mittal et al. (2018): In fact, pruning criteria are not that important
  - ... as long as the re-training phase exists
- Many strategies cannot even beat random pruning after fine-tuning

Heuristic	25 %	50%	75%
Random	0.650	0.569	0.415
Mean Activation	0.652	0.570	0.409
Entropy	0.641	0.549	0.405
Scaled Entropy	0.637	0.550	0.401
$l_1$ -norm	0.667	0.593	0.436
APoZ	0.647	0.564	0.422
Sensitivity	0.636	0.543	0.379

Table 1: Comparison of different filter pruning strategies on VGG-16.

Heuristics	#Layers Pruned	25 %	50%	75%
Random	16	0.722	0.683	0.617
$l_1$ -norm	16	0.714	0.677	0.610
Random	32	0.696	0.637	0.518
$l_1$ -norm	32	0.691	0.633	0.514

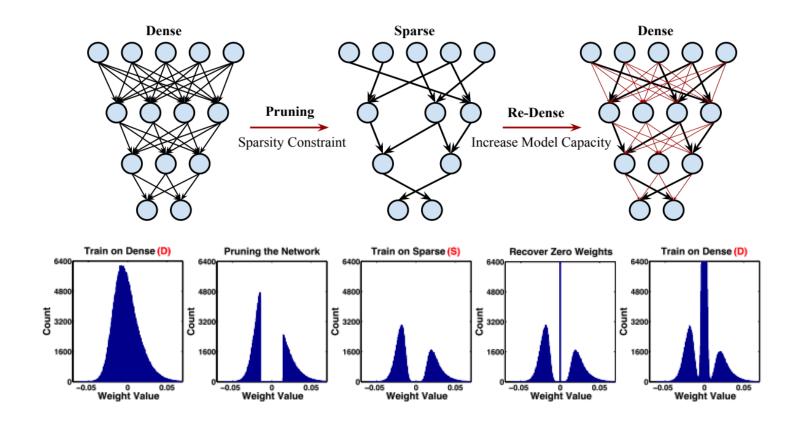
Table 3: Comparison of different filter pruning strategies on ResNet (Top-1 accuracy of unpruned network is 0.745)

- The compressibility of DNNs are NOT due to the specific criterion
  - ... but due to the inherent plasticity of DNNs

Next: Dense-Sparse-Dense

### **Network Re-wiring: Dense-Sparse-Dense Training Flow**

- Network pruning preserves accuracy of the original network
- Han et al. (2017): Re-wiring the pruned connections improves DNNs further
  - "Dense-Sparse-Dense" training flow



### **Network Re-wiring: Dense-Sparse-Dense Training Flow**

- Network pruning preserves accuracy of the original network
- Han et al. (2017): Re-wiring the pruned connections improves DNNs further
  - "Dense-Sparse-Dense" training flow
- Pruning discovers better optimum that the current training cannot find

Neural Network	Domain	Dataset	Type	Baseline	DSD	Abs. Imp.	Rel. Imp.
GoogLeNet	Vision	ImageNet	CNN	$31.1\%^{1}$	30.0%	1.1%	3.6%
VGG-16	Vision	ImageNet	CNN	$31.5\%^{1}$	27.2%	4.3%	13.7%
ResNet-18	Vision	ImageNet	CNN	$30.4\%^{1}$	29.2%	1.2%	4.1%
ResNet-50	Vision	ImageNet	CNN	$24.0\%^{1}$	22.9%	1.1%	4.6%
NeuralTalk	Caption	Flickr-8K	LSTM	$16.8^{2}$	18.5	1.7	10.1%
DeepSpeech	Speech	WSJ'93	RNN	$33.6\%^{3}$	31.6%	2.0%	5.8%
DeepSpeech-2	Speech	WSJ'93	RNN	14.5% <sup>3</sup>	13.4%	1.1%	7.4%

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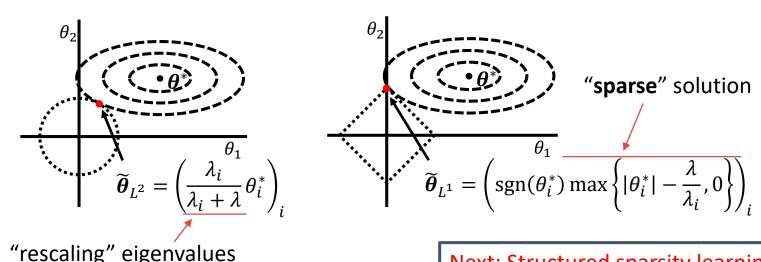
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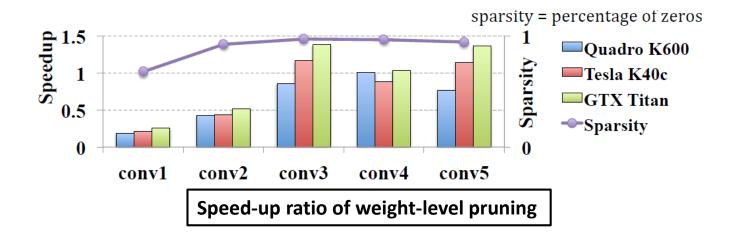
### **Sparse Network Learning**

- The performance of pruning depends on the initial training scheme
  - e.g. Which regularization to use:  $L^2$  or  $L^1$ ?
- Which training scheme will maximize the pruning performance?
  - We still don't know about the optimal points of a DNN
- One prominent way: Sparse network learning
  - Inducing to a sparse solution from training a network
  - Weights with value 0 can safely be removed ⇒ it **does not** require re-training
- **Example**:  $L^1$ -regularization



Next: Structured sparsity learning

- "Un-structured" weight-level pruning may not engage a practical speed-up
  - Despite of extremely high sparsity, actual speed-ups in GPU is limited



### Non-structured sparsity (poor data pattern)



### Structured sparsity (regular data pattern)



5× speedup after concatenation of nonzero rows and columns

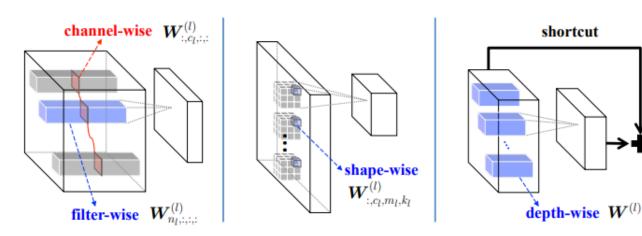
$$\min_{\mathbf{W}} \mathcal{L}(\mathbf{W}) + \lambda \sum_{l=1}^{L} R_g(\mathbf{W}^{(l)}), \ R_g(\mathbf{w}) = \sum_{g=1}^{G} \|\mathbf{w}^{(g)}\|_2$$

Filter-wise and channel-wise: # filters # channels  $R_g(\mathbf{W}^{(l)}) = \sum_{n_l=1}^{N_l} \|\mathbf{W}_{n_l,:,:,:}^{(l)}\|_2 + \sum_{c_l=1}^{C_l} \|\mathbf{W}_{:,c_l,:,:}^{(l)}\|_2$ 

**Shape-wise** sparsity: sparsity: width height  $R_g(\mathbf{W}^{(l)}) = \sum_{c_l=1}^{C_l} \sum_{m_l=1}^{M_l} \sum_{k_l=1}^{K_l} \|\mathbf{W}^{(l)}_{::c_l,m_l,k_l}\|_2$ 

**Depth-wise** sparsity (applicable only for ResNet):

$$R_g(\mathbf{W}^{(l)}) = \|\mathbf{W}^{(l)}\|_2$$



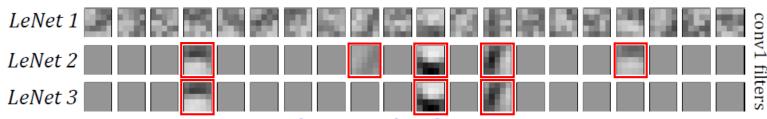
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• Filter-wise and channel-wise: # filters # channels  $R_g(\mathbf{W}^{(l)}) = \sum_{n_l=1}^{N_l} \|\mathbf{W}_{n_l,:,:,:}^{(l)}\|_2 + \sum_{c_l=1}^{C_l} \|\mathbf{W}_{:,c_l,:,:}^{(l)}\|_2$ 

Table 1: Results after penalizing unimportant filters and channels in *LeNet* 

LeNet #	Error	Filter#§	Channel # §	FLOP §	Speedup §
1 (baseline)	0.9%	20—50	1—20	100%—100%	$1.00 \times -1.00 \times $
2	0.8%	5—19	1—4	25%—7.6%	$1.64 \times -5.23 \times $
3	1.0%	3—12	1—3	15%—3.6%	$1.99 \times -7.44 \times $

<sup>§</sup>In the order of conv1—conv2



Fewer but smoother feature extractors

$$\min_{\mathbf{W}} \mathcal{L}(\mathbf{W}) + \lambda \sum_{l=1}^{L} R_g(\mathbf{W}^{(l)}), \ R_g(\mathbf{w}) = \sum_{g=1}^{G} \|\mathbf{w}^{(g)}\|_2$$

**Shape-wise** sparsity:

sparsity: width height  $R_g(\mathbf{W}^{(l)}) = \sum_{c_l=1}^{C_l} \sum_{m_l=1}^{M_l} \sum_{k_l=1}^{K_l} \|\mathbf{W}^{(l)}_{:,c_l,m_l,k_l}\|_2$ 

Table 2: Results after learning filter shapes in *LeNet* 

LeNet#	Error	Filter size §	Channel #	FLOP	Speedup
1 (baseline)	0.9%	25—500	1—20	100%—100%	1.00×—1.00×
4	0.8%	21—41	1—2	8.4%—8.2%	2.33×—6.93×
5	1.0%	7—14	1—1	1.4%—2.8%	5.19×—10.82×

<sup>§</sup> The sizes of filters after removing zero shape fibers, in the order of conv1—conv2

Learned shapes of conv1 filters:





LeNet 1 LeNet 4

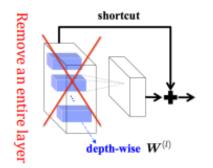
LeNet 5

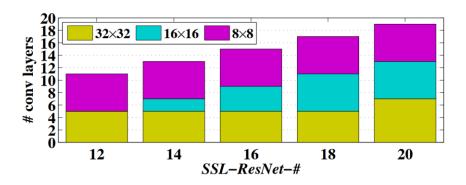
$$\min_{\mathbf{W}} \mathcal{L}(\mathbf{W}) + \lambda \sum_{l=1}^{L} R_g(\mathbf{W}^{(l)}), \ R_g(\mathbf{w}) = \sum_{g=1}^{G} \|\mathbf{w}^{(g)}\|_2$$

• **Depth-wise** sparsity:  $R_g(\mathbf{W}^{(l)}) = \|\mathbf{W}^{(l)}\|_2$ 

ResNet-20/32: baseline with 20/32 layers SSL-ResNet-#: Ours with # layers after learning depth of ResNet-20

	# layers	error	# layers	error
ResNet	20	8.82%	32	7.51%
SSL-ResNet	14	8.54%	18	7.40%





Next: Sparsification via variational dropout

- Variational dropout (VD) allows to learn the dropout rates separately
- Unlike dropout, VD imposes noises on weights  $\theta$ :

$$w_i := \theta_i \cdot \xi_i, \quad \text{where} \quad p_{\alpha_i}(\xi_i) = \mathcal{N}(1, \alpha_i)$$

- A Bayesian generalization of Gaussian dropout [Srivastava et al., 2014]
- $\mathbf{w} = (w_i)_i$  is adapted to data in Bayesian sense by optimizing  $\boldsymbol{\alpha}$  and  $\boldsymbol{\theta}$
- Re-parametrization trick allows w to be learned via minibatch-based gradient estimation methods [Kingma & Welling, 2013]
  - $\alpha$  and  $\theta$  can be optimized separated from noises

$$w_i = \theta_i + (\theta_i \sqrt{\alpha_i}) \cdot \varepsilon_i, \quad \text{where} \quad \varepsilon_i \sim \mathcal{N}(0, 1)$$

### Variational Dropout Sparsifies DNNs [Molchanov et al., 2017]

• VD imposes noises on weights  $\theta$ :

$$w_i := \theta_i \cdot \xi_i, \quad \text{where} \quad p_{\alpha_i}(\xi_i) = \mathcal{N}(1, \underline{\alpha_i})$$

- The original VD set a constraint  $\alpha_i \leq 1$  for technical reasons
  - It corresponds to  $p \le 0.5$  in binary dropout

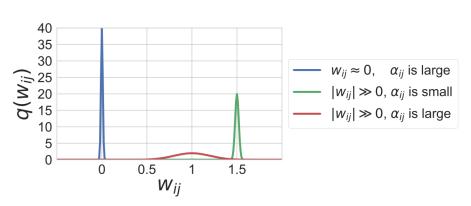
# Q. What if $\alpha_i > 1$ ? What happens when $\alpha_i \to \infty$ ?

- $p(w_i) = \theta_i \cdot p(\xi_i) = \mathcal{N}(\theta_i, \alpha_i \theta_i^2)$
- $w_i$  will be completely random as  $\alpha_i \to \infty$
- Such  $w_i$  will **corrupt** the expected log likelihood
- ... except that  $\theta_i \to 0$  as well!

$$\theta_{ij} \to 0, \quad \alpha_{ij}\theta_{ij}^2 \to 0$$

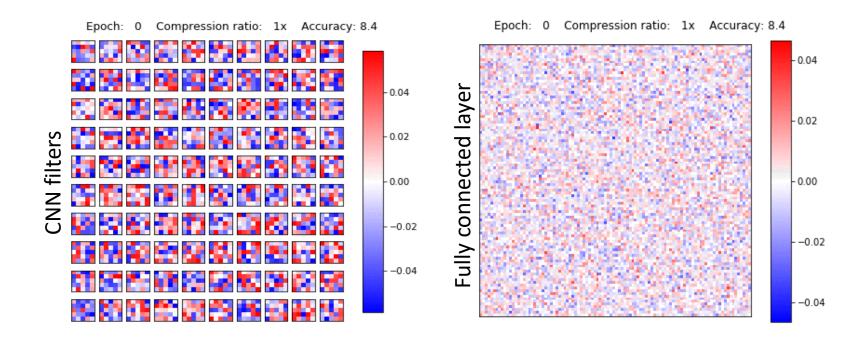
$$\downarrow \downarrow$$

$$q(w_{ij} \mid \theta_{ij}, \alpha_{ij}) \to \mathcal{N}(w_{ij} \mid 0, 0) = \delta(w_{ij})$$



#### Variational Dropout Sparsifies DNNs [Molchanov et al., 2017]

- **Q.** What if  $\alpha_i > 1$ ? What happens when  $\alpha_i \to \infty$ ?
  - It will **corrupt** the expected log likelihood except that  $\theta_i \to 0$  as well
- Molchanov et al. (2017): Extending VD for  $\alpha_i > 1 \Rightarrow$  Super sparse solutions
  - Weights with  $\log \alpha > 3$  are pruned away during training



#### Variational Dropout Sparsifies DNNs [Molchanov et al., 2017]

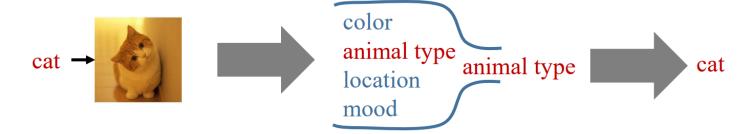
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Network	Method	Error %	Sparsity per Layer %	$\frac{ \mathbf{W} }{ \mathbf{W}_{\neq 0} }$	<del></del> [
	Original	1.64		1	
	Pruning	1.59	92.0 - 91.0 - 74.0	12	[Han et al., 2015]
LeNet-300-100	DNS	1.99	98.2 - 98.2 - 94.5	56	
	SWS	1.94		23	
(ours)	Sparse VD	1.92	98.9 - 97.2 - 62.0	68	
	Original	0.80		1	
	Pruning	0.77	34 - 88 - 92.0 - 81	12	[Han et al., 2015]
LeNet-5-Caffe	DNS	0.91	86 - 97 - 99.3 - 96	111	
	SWS	0.97		200	
(ours)	Sparse VD	0.75	67 - 98 - 99.8 - 95	280	_

Next: Variational information bottleneck

Motivation: Markov chain interpretation of DNN [Tishby & Zaslavsky, 2015]

$$egin{aligned} m{y} 
ightarrow m{x} = m{h}_0 
ightarrow m{h}_1 
ightarrow \cdots 
ightarrow m{h}_{l-1} 
ightarrow m{h}_i 
ightarrow \cdots 
ightarrow m{h}_L 
ightarrow m{\hat{y}} \ p(m{h}_i | m{h}_{l-1}) & ext{Approximate } p(m{y} | m{h}_L) \ ext{via tractable } p(\hat{m{y}} | m{h}_L) \end{aligned}$$



- **1.** Maximize  $I(h_i; y)$  for high-accuracy prediction
- 2. Minimize  $I(h_i; h_{i-1})$  for compression  $\Rightarrow$  "information bottleneck"
- Layer-wise losses become:

$$\mathcal{L}_i = \gamma_i I(m{h}_i; m{h}_{i-1}) - I(m{h}_i; m{y})$$

The relative strength of bottleneck

#### Variational Information Bottleneck [Dai et al., 2018]

- Layer-wise losses become  $\mathcal{L}_i = \gamma_i I(m{h}_i; m{h}_{i-1}) I(m{h}_i; m{y})$
- **Problem**: Computing  $I(\cdot;\cdot)$  is usually intractable
- Instead, we minimize variational upper bound of it

$$\mathcal{L}_i \leq \tilde{\mathcal{L}}_i = \gamma_i \mathbb{E}[\mathrm{KL}(p(\boldsymbol{h}_i|\boldsymbol{h}_{i-1})||q(\boldsymbol{h}_i))] - \mathbb{E}[\log q(\boldsymbol{y}|\boldsymbol{h}_L)]$$
 variational approx. of  $p(\boldsymbol{h}_i)$  variational approx. of  $p(\boldsymbol{y}|\boldsymbol{h}_L)$  
$$\begin{cases} \mathbf{multinomal} \text{ for classification } \\ \mathbf{Gaussian} \text{ for regression} \end{cases}$$

Variational Information Bottleneck (VIB) model

$$p(\boldsymbol{h}_i|\boldsymbol{h}_{i-1})\coloneqq f_i(\boldsymbol{h}_{i-1})\odot\mathcal{N}(\boldsymbol{h}_i|\boldsymbol{\mu}_i,\operatorname{diag}(\boldsymbol{\sigma}_i^2))$$
 
$$q(\boldsymbol{h}_i)\coloneqq\mathcal{N}(\boldsymbol{h}_i|\boldsymbol{0},\operatorname{diag}(\boldsymbol{\xi}_i))$$
 
$$q(\boldsymbol{h}_i)\coloneqq\mathcal{N}(\boldsymbol{h}_i|\boldsymbol{0},\operatorname{diag}(\boldsymbol{\xi}_i))$$
 Reparametrization trick 
$$\text{[Kingma \& Welling, 2013]}$$
 
$$q(\boldsymbol{h}_i)\coloneqq\mathcal{N}(\boldsymbol{h}_i|\boldsymbol{0},\operatorname{diag}(\boldsymbol{\xi}_i))$$

#### Variational Information Bottleneck [Dai et al., 2018]

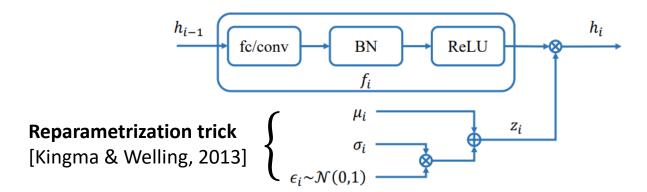
ullet We minimize variational upper bound of  $\mathcal{L}_i$ 

$$\mathcal{L}_i \leq \tilde{\mathcal{L}}_i = \gamma_i \mathbb{E}[\mathrm{KL}(p(\boldsymbol{h}_i|\boldsymbol{h}_{i-1})||q(\boldsymbol{h}_i))] - \mathbb{E}[\log q(\boldsymbol{y}|\boldsymbol{h}_L)]$$

Final variational objective function (VIBNet):

$$\tilde{\mathcal{L}} = \underbrace{\sum_{i=1}^{L} \gamma_i \sum_{j} \log \left( 1 + \frac{\mu_{ij}^2}{\sigma_{ij}^2} \right)}_{\text{regularization}} - \underbrace{\frac{\mu_{ij}^2}{L \cdot \mathbb{E}[\log q(\boldsymbol{y}|\boldsymbol{h}_L)]}_{\text{data-fit}}}_{\text{data-fit}}$$

- Pruning criteria:  $\alpha_{ij}\coloneqq \frac{\mu_{ij}^2}{\sigma_{ij}^2}\to 0$ 
  - Neurons with low value of  $\alpha_{ij}$ 's are pruned after training



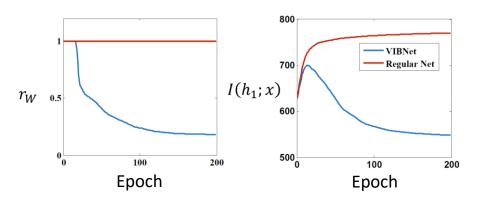
#### Variational Information Bottleneck [Dai et al., 2018]

# VIBNet outperforms various methods by large margins

- $r_W(\%)$ : ratio of # parameters
- $r_N(\%)$ : ratio of memory footprint

Method	$r_W(\%)$	$r_N(\%)$	error(%)	Pruned Model
VD	25.28	58.95	1.8	512-114-72
BC-GNJ	10.76	32.85	1.8	278-98-13
<b>BC-GHS</b>	10.55	34.71	1.8	311-86-14
L0	26.02	45.02	1.4	219-214-100
L0-sep	10.01	32.69	1.8	266-88-33
DN	23.05	57.94	1.8	542-83-61
VIBNet	3.59	16.98	1.6	97-71-33

Table 1. Compression results on MNIST using LeNet-300-100.



After fine-tuning

				`
Method	$r_W(\%)$	FLOP(Mil)	$r_N(\%)$	error(%)
BC-GNJ	6.57	141.5	81.68	8.6
<b>BC-GHS</b>	5.40	121.9	74.82	9.0
VIBNet	5.30	70.63	49.57	8.8 ( <b>8.5</b> )
PF	35.99	206.3	83.97	6.6
SBP	7.01	136.0	80.72	7.5
SBPa	5.78	99.20	66.46	9.0
VIBNet	5.45	86.82	57.86	6.5 (6.1)
NS-Single	11.50	195.5	-	6.2
NS-Best	8.60	147.0	-	5.9
VIBNet	5.79	116.0	59.60	6.2 ( <b>5.8</b> )

Table 3. Compression results on CIFAR10 using VGG-16.

Method	$r_W(\%)$	FLOP(Mil)	$r_N(\%)$	error(%)
RNP	-	160	-	38.0
VIBNet	22.75	133.6	59.80	37.6 ( <b>37.4</b> )
NS-Single	24.90	250.5	-	26.5
NS-Best	20.80	214.8	-	26.0
VIBNet	15.08	203.1	73.80	25.9 ( <b>25.7</b> )

Table 4. Compression results on CIFAR100 using VGG-16.

#### **Table of Contents**

### 1. Network Pruning and Re-wiring

- Optimal brain damage
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# 2. Sparse Network Learning

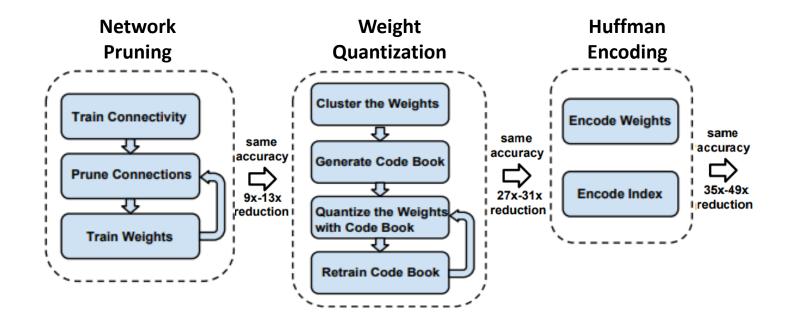
- Structured sparsity learning
- Sparsification via variational dropout
- Variational information bottleneck

# 3. Weight Quantization

- Deep compression
- Binarized neural networks

# 4. Summary

- Quantizing weights can further compress the pruned networks
  - Weights are clustered into discrete values
  - The network is represented only with several centroid values
- Han et al. (2015): Pruning DNNs ⇒ 9x-13x reduction
- Han et al. (2016): Pruning + Quantization + Huffman ⇒ 35x-49x reduction

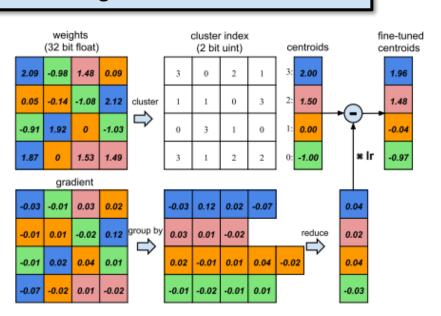


- Quantizing weights can further compress the pruned networks
  - Weights are clustered into discrete values
  - The network is represented only with several centroid values
    - 1. Train a deep model until convergence
    - **2.** Find *k* clusters that minimizes within-cluster sum of squares (WCSS):

$$\operatorname{argmin}_C \sum_{i=1}^k \sum_{w \in c_i} |w - c_i|^2$$

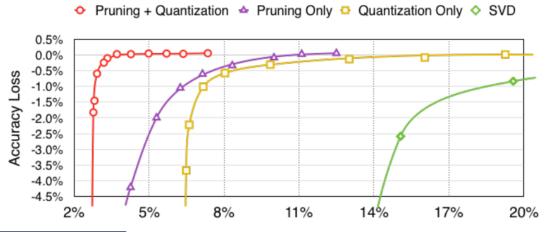
- **3.** Quantize with the cluster C via weight sharing
- **4. Fine-tune** the network with the shared weights
- In the **fine-tuning** phase, gradients in each cluster are **aggregated**:

$$\frac{\partial \mathcal{L}}{\partial C_k} = \sum_{i,j} \frac{\partial \mathcal{L}}{\partial W_{ij}} \frac{\partial W_{ij}}{\partial C_k}$$
$$= \sum_{i,j} \frac{\partial \mathcal{L}}{\partial W_{ij}} \mathbf{1}(W_{ij} \in C_k)$$



# • **Deep compression** reduces the model size significantly

Network	Original Size	Compressed Size	Compression Ratio	Original Accuracy (%)	Compressed Accuracy (%)
LeNet-300	1070KB —	→ 27KB	40x	98.36 —	→ 98.42
LeNet-5	1720KB —	→ 44KB	39x	99.20 —	→ 99.26
AlexNet	240MB —	→ 6.9MB	35x	80.27 —	→ 80.30
VGGNet	550MB —	→ 11.3MB	49x	88.68 —	→ 89.09
GoogLeNet	28MB —	→ 2.8MB	10x	88.90 —	→ 88.92
SqueezeNet	4.8MB —	→ 0.47MB	10x	80.32 —	→ 80.35

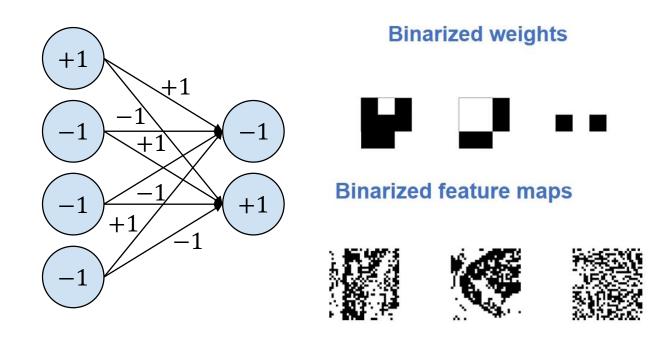


Next: Binarized neural networks

Model Size Ratio after Compression

<sup>\*</sup>source : Han et al., "Deep Compression - Compressing Deep Neural Networks with Pruning, Trained Quantization and Huffman Coding", ICLR 2016

- Neural networks can be even **binarized** (**+1** or **-1**)
  - DNNs trained to use binary weights and binary activations
- Expensive **32-bit MAC** (Multiply-**AC**cumulate) ⇒ Cheap **1-bit XNOR-Count** 
  - "MAC == XNOR-Count": when the weights and activations are  $\pm 1$ # 1s in bits



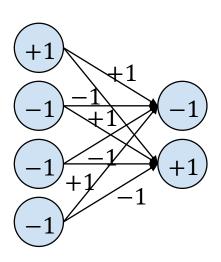
### Binarized Neural Networks [Hubara et al., 2016]

- Idea: Training real-valued nets  $(W_r)$  treating binarization  $(W_b)$  as noise
  - Training  $W_r$  is done by **stochastic gradient descent**
- Binarization  $(W_r \to W_b)$  occurs for each forward propagation
  - On each of weights:  $W_b = \operatorname{sign}(W_r)$
  - ... also on each **activation**:  $a_b = \operatorname{sign}(a_r)$
- Gradients for  $W_r$  is estimated from  $\frac{\partial L}{\partial W_h}$  [Bengio et al., 2013]
  - "Straight-through estimator": Ignore the binarization during backward!

$$\frac{\partial L}{\partial W_r} = \frac{\partial L}{\partial W_b} \mathbf{1}_{|W_r| \le 1}$$

$$\frac{\partial L}{\partial a_r} = \frac{\partial L}{\partial a_b} \mathbf{1}_{|a_r| \le 1}$$

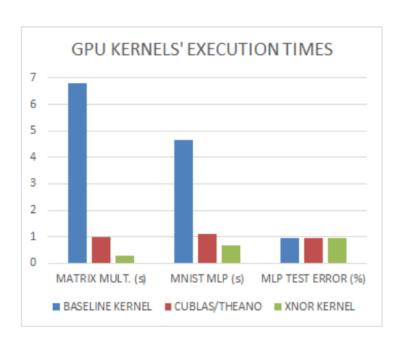
- Cancelling gradients for better performance
  - When the value is too large



#### Binarized Neural Networks [Hubara et al., 2016]

- Neural networks can be even **binarized** (**+1** or **-1**)
  - DNNs trained to use binary weights and binary activations
- BNN yields 32x less memory compared to the baseline 32-bit DNNs
  - ... also expected to reduce energy consumption drastically
- 23x faster on kernel execution times
  - BNN allows us to use XNOR kernels
  - **3.4x** faster than cuBLAS

Operation	MUL	ADD
8bit Integer	0.2pJ	0.03pJ
32bit Integer	3.1pJ	0.1 pJ
<b>16bit Floating Point</b>	1.1pJ	0.4 pJ
32tbit Floating Point	3.7pJ	0.9 pJ



- Neural networks can be even binarized (+1 or -1)
  - DNNs trained to use binary weights and binary activations
- **BNN** achieves comparable error rates over existing DNNs

Data set	MNIST	SVHN	CIFAR-10				
Binarized activations+weights, during training and test							
BNN (Torch7)	1.40%	2.53%	10.15%				
BNN (Theano)	0.96%	2.80%	11.40%				
Committee Machines' Array (Baldassi et al., 2015)	1.35%	-	-				
Binarized weights, during training and test							
BinaryConnect (Courbariaux et al., 2015)	$1.29\pm 0.08\%$	2.30%	9.90%				
Binarized activations+weights, during test							
EBP (Cheng et al., 2015)	$2.2 \pm 0.1\%$	-	-				
Bitwise DNNs (Kim & Smaragdis, 2016)	1.33%	-	-				
Ternary weights, binary activations, during test							
(Hwang & Sung, 2014)	1.45%	-	-				
No binarization (standard results)							
Maxout Networks (Goodfellow et al.)	0.94%	2.47%	11.68%				
Network in Network (Lin et al.)	-	2.35%	10.41%				
Gated pooling (Lee et al., 2015)	-	1.69%	7.62%				

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### 4. Summary

### **Summary**

- Broad economic viability requires energy efficient AI [Welling, 2018]
  - "Energy efficiency of a brain is 100x better than current hardware"
  - "Al algorithms will be measured by the amount of intelligence per kWh"
- Network pruning and re-wiring
  - A simple but effective way to compress DNNs
  - Allow us to find better optimum that the current training cannot
- Sparse network learning
  - Which training scheme will maximize the pruning performance?
  - It has gained significant attention recently
- Various other techniques have been also proposed
  - Weight quantization
  - Anytime/adaptive networks [Huang et al., 2018]
  - ...

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