# **Advanced Deep Temporal Models**

Al602: Recent Advances in Deep Learning
Lecture 3

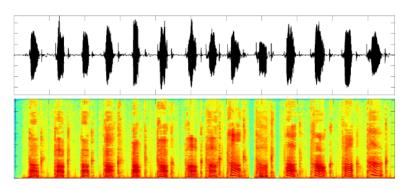
Slide made by

Jaehyung Kim and Changyeon Kim

KAIST EE

- Many real-world data has a temporal structure intrinsically
  - Speech



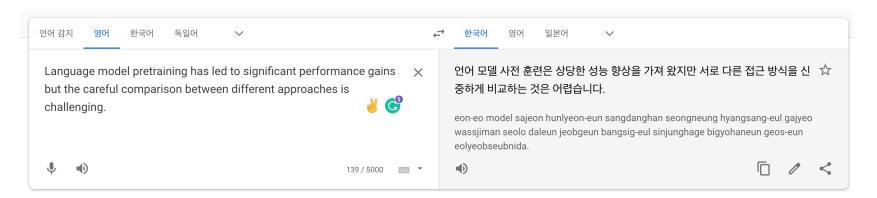


- Many real-world data has a temporal structure intrinsically
  - Speech
  - Natural language

"Overall, the value I got from the two hours watching it was the sum total of the popcorn and the drink.

The movie was  $\_$ ."  $\rightarrow$  terrible

#### Language modeling

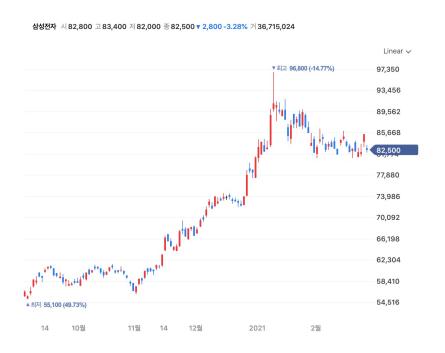


**Translation** 

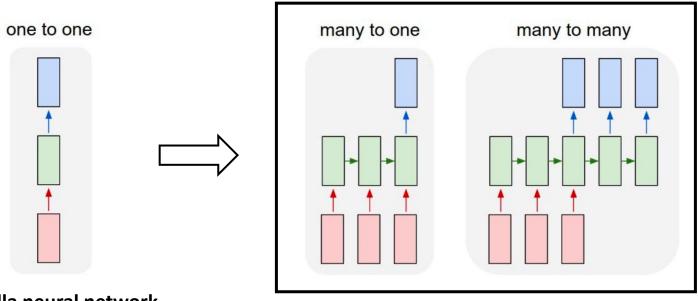
- Many real-world data has a temporal structure intrinsically
  - Speech
  - Natural language
  - Video



- Many real-world data has a **temporal structure** intrinsically
  - Speech
  - Natural language
  - Video
  - Stock prices, and etc...



- Many real-world data has a temporal structure intrinsically
  - Speech
  - Natural language
  - Video
  - Stock prices, and etc...
- In order to solve much complicated real-world problems,
   we need a better architecture to capture temporal dependency in the data



Vanilla neural network

#### **Table of Contents**

#### 1. Basics

- RNN (Recurrent Neural Networks)
- LSTM (Long Short-Term Memory)
- Sequence-to-sequence Model

### 2. Advanced Topics

- From recurrence (RNN) to attention-based NLP models
- Transformer (self-attention) with its great results
- Pre-training of Transformers
- Drawbacks and variants of Transformers

# 3. Beyond GPT-3: Recent Advances with Large-scale Language Models

- Language models larger than GPT-3
- More effective training schemes
- Applications with language models

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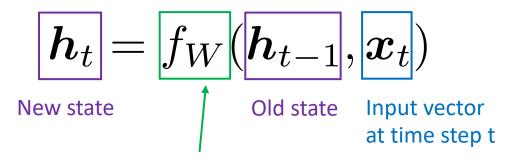
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# 3. Beyond GPT-3: Recent Advances with Large-scale Language Models

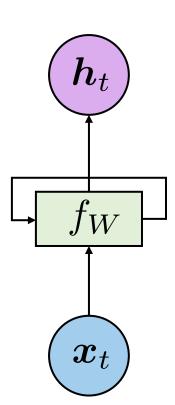
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### Vanilla RNN

Process a sequence of vectors by applying recurrence formula at every time step :



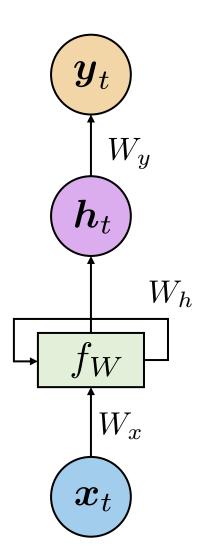
Function parameterized by learnable W



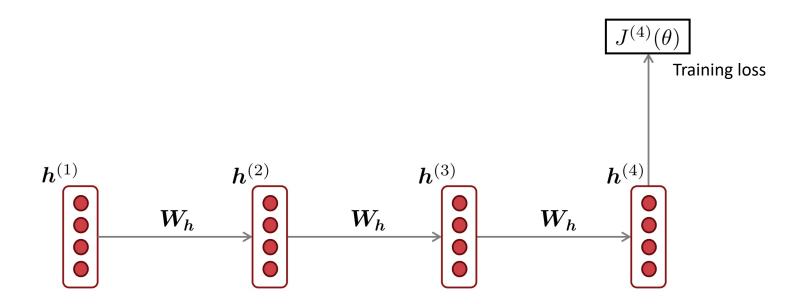
### Vanilla RNN

- Vanilla RNN (or sometimes called Elman RNN)
  - The state consists of a single "hidden" vector  $\mathbf{h}_t$

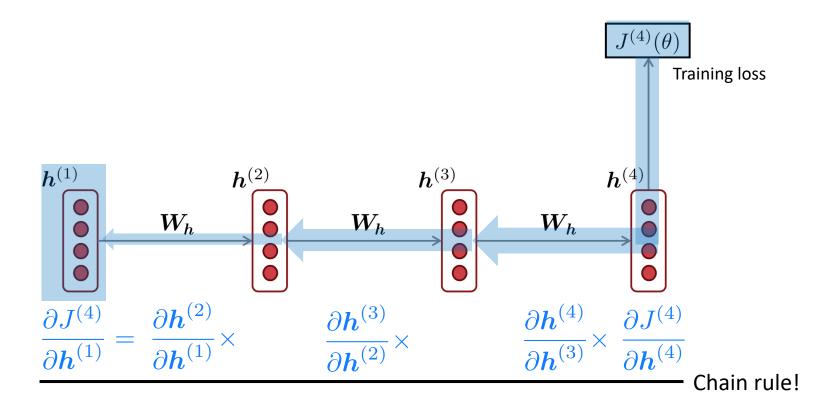
$$egin{aligned} oldsymbol{h}_t &= f_W(oldsymbol{h}_{t-1}, oldsymbol{x}_t) \ oldsymbol{h}_t &= anh(W_holdsymbol{h}_{t-1} + W_xoldsymbol{x}_t) \ oldsymbol{y}_t &= W_yoldsymbol{h}_t \end{aligned}$$



• E.g., RNN with a sequence of length 4

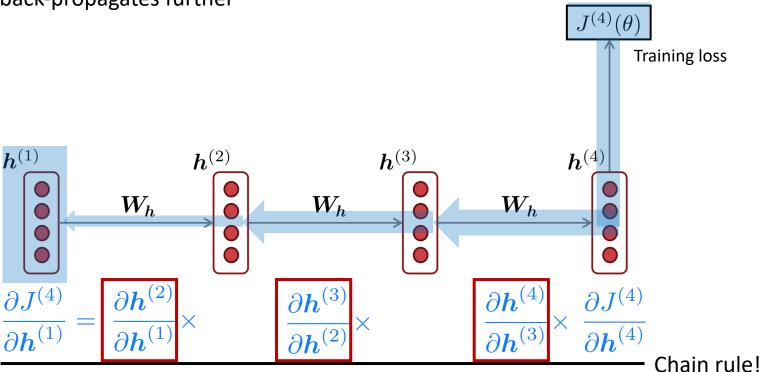


- E.g., RNN with a sequence of length 4
  - Consider a gradient from the first state  $h^{(1)}$

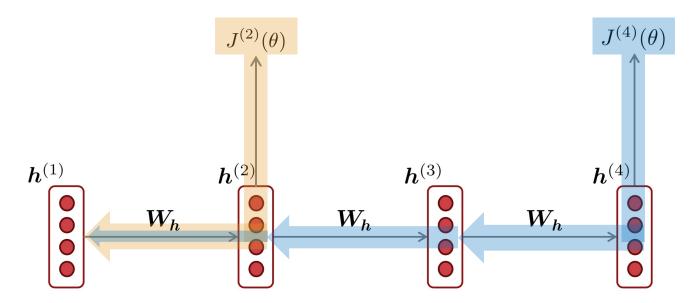


- E.g., RNN with a sequence of length 4
  - Consider a gradient from the first state  $h^{(1)}$
- What happens if  $\frac{\partial h^{(i+1)}}{\partial h^{(i)}}$  are too small?  $\Longrightarrow$  Vanishing gradient problem

 When these are small, the gradient signal gets smaller and smaller as it back-propagates further



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  - When these are small, the gradient signal gets smaller and smaller as it back-propagates further
  - So, model weight are updated only with respect to near effects, not long-term effects.

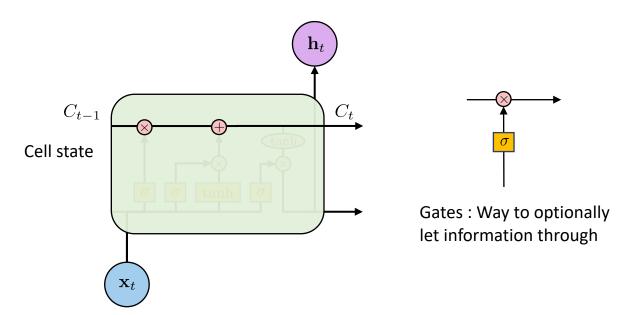


- E.g., RNN with a sequence of length 4
  - Consider a gradient from the first state  $h^{(1)}$
- What happens if  $\frac{\partial h^{(i+1)}}{\partial h^{(i)}}$  are too small?  $\Longrightarrow$  Vanishing gradient problem
  - When these are small, the gradient signal gets smaller and smaller as it back-propagates further
  - So, model weight are updated only with respect to near effects, **not** long-term effects.
- What happens if  $\frac{\partial \boldsymbol{h}^{(i+1)}}{\partial \boldsymbol{h}^{(i)}}$  are too large?  $\Longrightarrow$  Exploding gradient problem

$$\theta^{\text{new}} = \theta^{\text{old}} - \alpha \nabla_{\theta} J(\theta)$$

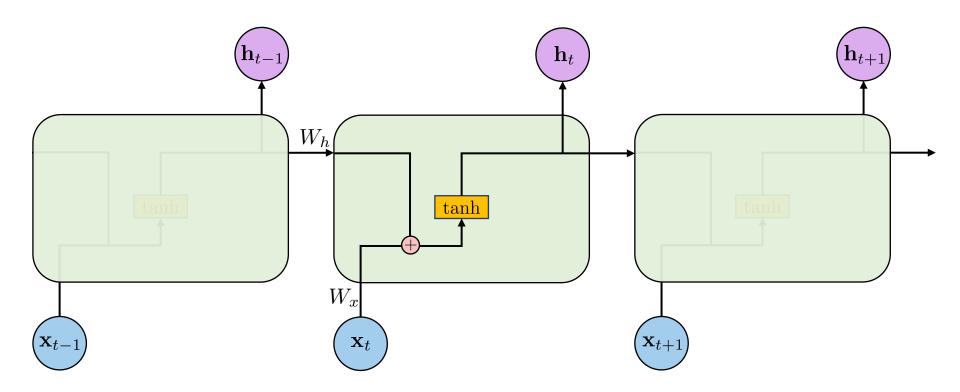
- This can cause bad updates as the update step of parameters becomes too big
- In the worst case, this will result in divergence of your network
- In practice, with a gradient clipping, exploding gradient is relatively easy to solve

- Long Short-Term Memory (LSTM) [Hochreiter and Schmidhuber, 1997]
  - A special type of RNN unit, i.e., LSTM networks = RNN composed of LSTM units
  - Explicitly designed RNN to
    - Capture **long-term dependency**  $\Rightarrow$  more robust to vanishing gradient problem
- Core idea behind LSTM
  - With cell state (memory), it controls how much to remove or add information
    - Only linear interactions from the output of each "gates" (prevent vanishing gradient)



Repeating modules in Vanilla RNN contains a single layer

$$\boldsymbol{h}_t = \tanh(W_h \boldsymbol{h}_{t-1} + W_x \boldsymbol{x}_t)$$

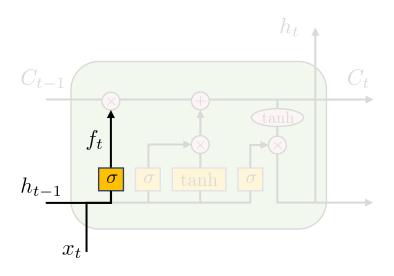


### **RNN Architectures: LSTM**

Repeating modules in **LSTM** Pointwise Vector Layer concatenate Copy operation Transfer  $\mathbf{h}_t$ tanh  $\mathbf{x}_t$ 

# **Step 1**: Decide what **information** we're going to **throw away** from the **cell state**

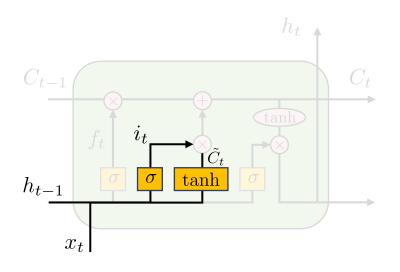
- A sigmoid layer called "Forget gate"  $f_t$
- Looks at  $h_{t-1}, x_t$  and outputs a number between 0 and 1 for each cell state  $C_{t-1}$ 
  - If 1: completely keep, if 0: completely remove
- E.g., language model trying to **predict the next word** based on all previous ones
  - The cell state might include the gender of the present subject so that the correct pronouns can be used
  - When we see a new subject, we want to forget the gender of the old subject



$$f_t = \sigma(W_f \cdot [h_{t-1}, x_t] + b_f)$$

# Step 2: Decide what information we're going to store in the cell state and update

- First, a sigmoid layer called the "Input gate"  $i_t$  decides which values to update
- Next, a tanh layer creates a **new content**  $ilde{C}_t$  to be written to the

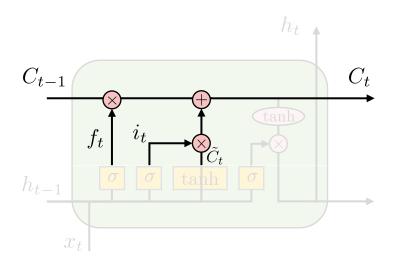


$$i_t = \sigma(W_i \cdot [h_{t-1}, x_t] + b_i)$$

$$\tilde{C}_t = \tanh(W_C \cdot [h_{t-1}, x_t] + b_C)$$

# **Step 2**: Decide what **information** we're going to **store** in the cell state and **update**

- First, a sigmoid layer called the "Input gate"  $i_t$  decides which values to update
- Next, a tanh layer creates a **new content**  $ilde{C}_t$  to be written to the
- Then, **update** the old cell state  $\,C_{t-1}\,$  into the **new cell state**  $\,C_t\,$ 
  - Multiply the old state by  $f_t$  (forget gate)
  - Add  $i_t * \tilde{C}_t$  , new content scaled by how much to update (input gate)



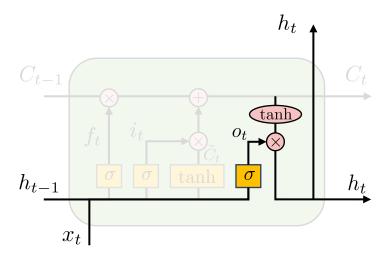
$$i_t = \sigma(W_i \cdot [h_{t-1}, x_t] + b_i)$$

$$\tilde{C}_t = \tanh(W_C \cdot [h_{t-1}, x_t] + b_C)$$

$$C_t = f_t * C_{t-1} + i_t * \tilde{C}_t$$

# **Step 3**: Decide what **information** we're going to **output**

- A sigmoid layer called "Output gate"  $o_t$
- First, go through  $o_t$  which decides what parts of the cell state to output
- Then, put the cell state  $C_t$  through tanh and multiply it by  $o_t$  for hidden state  $h_t$



$$o_t = \sigma(W_o \cdot [h_{t-1}, x_t] + b_o)$$

$$h_t = o_t * \tanh(C_t)$$

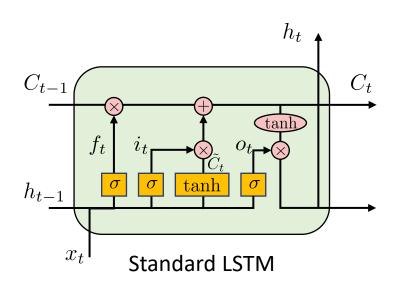
#### RNN Architectures: LSTM

## Overall LSTM operations

Forget gate:  $f_t = \sigma(W_f \cdot [h_{t-1}, x_t] + b_f)$  Input gate:  $i_t = \sigma(W_i \cdot [h_{t-1}, x_t] + b_i)$ 

New cell content:  $\tilde{C}_t = anh(W_C \cdot [h_{t-1}, x_t] + b_C)$ Previous cell state:  $C_{t-1}$ 

Updated cell state:  $C_t = f_t * C_{t-1} + i_t * \tilde{C}_t$  Output gate:  $o_t = \sigma(W_o \cdot [h_{t-1}, x_t] + b_o)$  Hidden state:  $h_t = o_t * \tanh(C_t)$ 

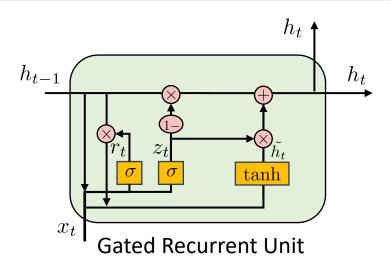


#### RNN Architectures: GRU

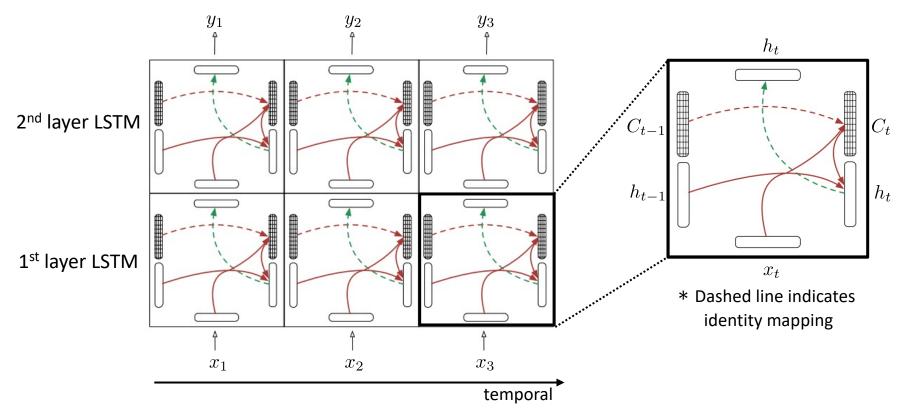
- Gated Recurrent Unit (GRU) [Cho et.al, 2014]
  - Combines the forget and input gates into a single "update gate"  $z_t$ 
    - Controls the ratio of information to keep between previous state and new state
  - **Reset gate**  $r_t$  controls how much information to forget when create a new content
  - **Merges** the cell state  $C_t$  and hidden state  $h_t$
  - (+) Resulting in simpler model (less weights) than standard LSTM

Reset gate:  $r_t = \sigma(W_r \cdot [h_{t-1}, x_t])$  New content:  $\tilde{h_t} = \tanh(W \cdot [r_t * h_{t-1}, x_t])$ 

Update gate:  $z_t = \sigma(W_z \cdot [h_{t-1}, x_t])$  Hidden state:  $h_t = (1 - z_t) * h_{t-1} + z_t * \tilde{h_t}$ 

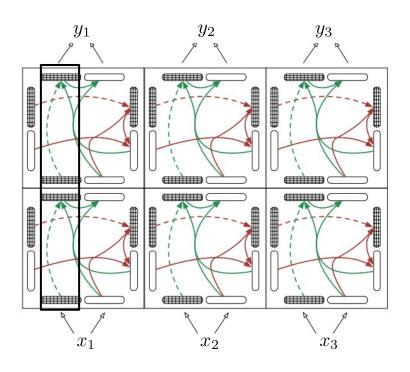


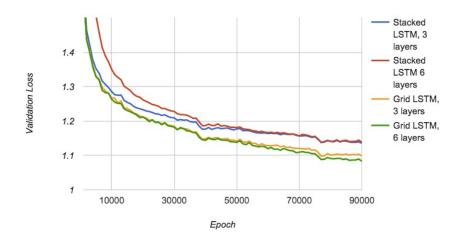
- Stacked(multi-layer) LSTM [Graves et al, 2013]
  - RNNs are already "deep" on one dimension (they unroll over many time-steps)
  - We can add depth by simply stacking LSTM layers on top of each other
    - This allows the network to compute **more complex representations**
  - E.g., Output of 1<sup>st</sup> layer LSTM goes into 2<sup>nd</sup> layer LSTM as an input



### **RNN Architectures: Grid LSTM**

- **Grid LSTM** [Kalchbrenner et al., 2016]
  - Extended version of stacked LSTM
  - LSTM units have additional memory along depth dimension as well as temporal dimension





	BPC	Parameters	Alphabet Size	Test data
Stacked LSTM (Graves, 2013)	1.67	27M	205	last 4MB
MRNN (Sutskever et al., 2011)	1.60	4.9M	86	last 10MB
GFRNN (Chung et al., 2015)	1.58	20M	205	last 5MB
Tied 2-LSTM	1.47	16.8M	205	last 5MB

2D Grid LSTM

Performance on wikipedia dataset (lower the better)

# **Limitation of Left-to-Right RNNs**

- What is the limitation of all previous models?
  - They learn representations only from previous time steps (left-to-right)
  - But, it's sometimes useful to learn from future time steps in order to
    - Better understand the context
    - · Eliminate ambiguity
- Example
  - "He said, Teddy bears are on sale"
  - "He said, Teddy Roosevelt was a great President"
  - In above two sentences, only seeing previous words is not enough to understand the sentence
- Solution
  - Also look ahead (right-to-left) | Bidirectional RNN

#### **RNN Architectures: Bidirectional RNNs**

- RNNs can be easily extended into bi-directional models
  - Only difference is that there are additional paths from future time steps
    - Any types of RNNs (Vanilla RNN, LSTM, or GRU) could be bi-directional models
  - Note: bi-directional RNNs are only applicable if one has access to entire sequence



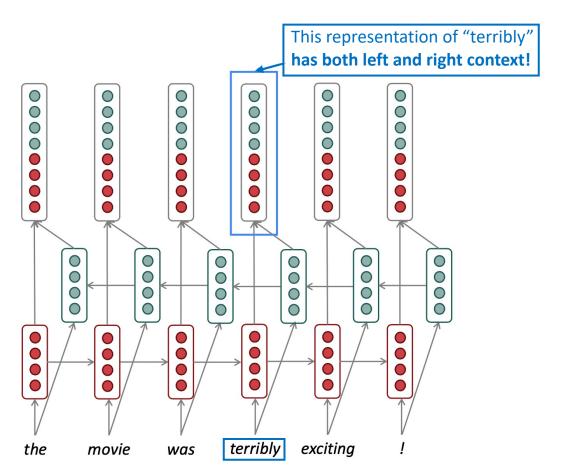
$$h^{(t)} = [\overrightarrow{h}^{(t)}; \overleftarrow{h}^{(t)}]$$

### **Backward RNN**

$$\overleftarrow{h}^{(t)} = \text{RNN}_{\text{BW}}\left(\overleftarrow{h}^{(t+1)}, x^{(t)}\right)$$

#### **Forward RNN**

$$\overrightarrow{h}^{(t)} = \text{RNN}_{\text{FW}}\left(\overrightarrow{h}^{(t-1)}, x^{(t)}\right)$$



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- More effective training schemes
- Applications with language models

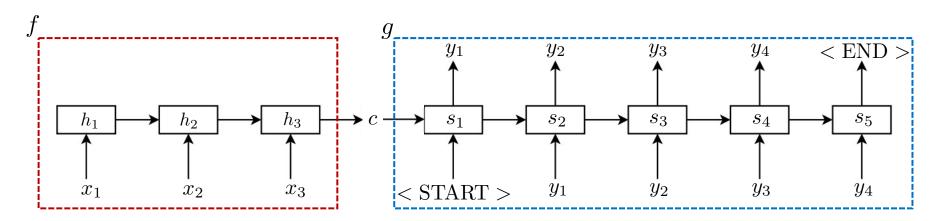
## **RNNs in Real-world Application: Neural Machine Translation**

- What is machine translation (MT)?
  - Task of automatically converting source text in one language to another language
  - No single answer due to ambiguity/flexibility of human language (challenging)



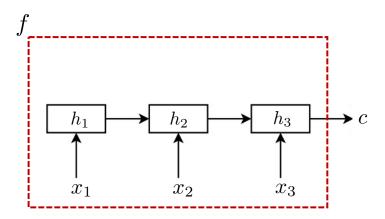
- Classical machine translation methods
  - Rule-based machine translation (RBMT)
  - Statistical machine translation (SMT; use of statistical model)
  - (-) Lots of human effort to maintain, e.g., repeated effort for each language pair
- Neural Machine Translation (NMT)
  - Use of neural network models to learn a statistical model for machine translation

- Difficulties in Neural Machine Translation
  - Intrinsic difficulties of MT (ambiguity of language)
  - Variable length of input and output sequence (difficult to learn a single model)
- The core idea of sequence-to-sequence model [Sutskever et al., 2014]
  - Encoder-Decoder architecture (input → vector → output)
  - Use one RNN network (Encoder) to read input sequence at a time for encoding it into a fixed-length vector representation (context)
  - Use another RNN (Decoder) to extract the output sequence from context vector



### Encoder

- Reads the input sentence  $\mathbf{x} = (x_1, \dots, x_T)$  and output context vector c
- Use RNNs such that  $h_t=f(x_t,h_{t-1})$  and  $c=q(\{h_1,\ldots,h_T\})$  , where f and q are some non-linear functions
- E.g., LSTMs as f and  $q(\{h_1,\ldots,h_T\})=h_T$  (in the original seq2seq model)



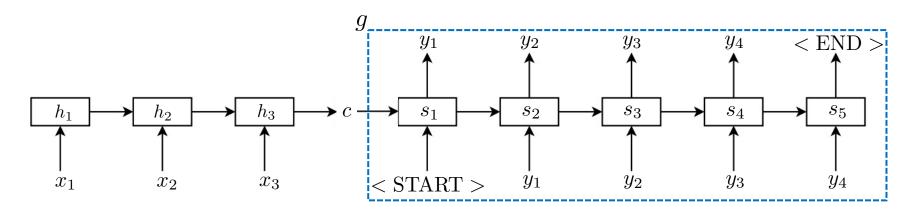
#### Decoder

- Predict the next word  $y_{t'}$  given the context vector c and the previously predicted words  $\{y_1,\ldots,y_{t'-1}\}$
- Defines a probability over the translation y by **decomposing the joint probability** into the ordered conditionals where  $y = (y_1, \dots, y_T)$ .

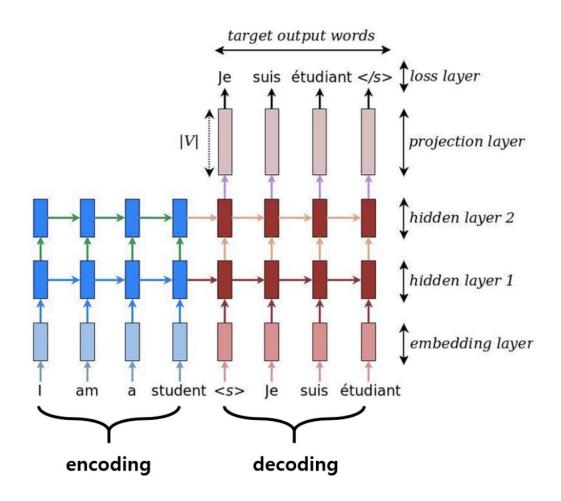
$$p(\mathbf{y}) = \prod_{t=1}^{T} p(y_t | \{y_1, \dots, y_{t'-1}\}, c),$$

• The conditional probability is modeled with another RNN g as

$$p(y_t|\{y_1,\ldots,y_{t'-1}\},c)=g(y_{t-1},\underline{s_t},c),$$
hidden state of the RNN



- Example of the seq2seq model
  - For English → French task
  - With 2-layer LSTM for encoder and encoder



- Results on WMT'14 English to French dataset [Sutskever et al., 2014]
  - Measure: BLEU(Bilingual Evaluation Understudy) score
    - Widely used quantitative measure for MT task
  - On par with the state-of-the-art SMT system (without using neural network)
  - Achieved better results than the previous baselines

Method	test BLEU score (ntst14)
Baseline System [29]	33.30
Cho et al. [5]	34.54
State of the art [9]	37.0
Rescoring the baseline 1000-best with a single forward LSTM	35.61
Rescoring the baseline 1000-best with a single reversed LSTM	35.85
Rescoring the baseline 1000-best with an ensemble of 5 reversed LSTMs	36.5
Oracle Rescoring of the Baseline 1000-best lists	~45

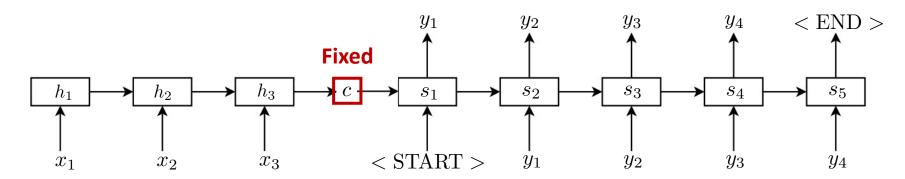
Seq2seq with RNNs is **simple but very powerful** in MT task

# **Breakthroughs in NMT: Sequence-to-Sequence Model with Attention**

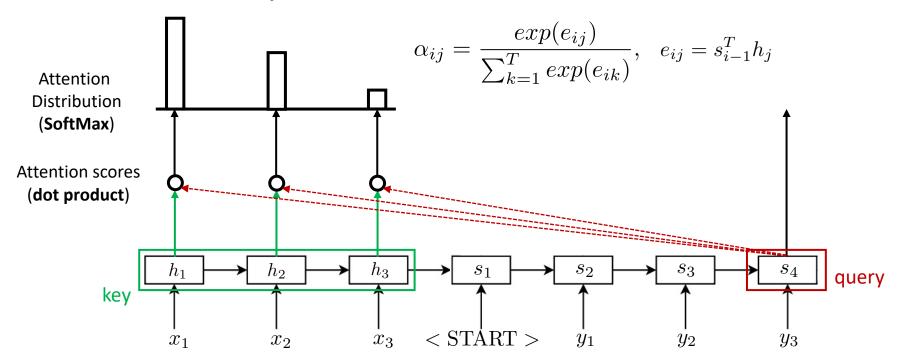
- Problem of original seq2seq(or encoder-decoder) model
  - Need to compress all the necessary information of a source sentence into a fixed context vector
    - All decoding steps use an identical context along with previous outputs

$$p(y_t|\{y_1,\ldots,y_{t'-1}\},c)=g(y_{t-1},s_t,\underline{c}),$$

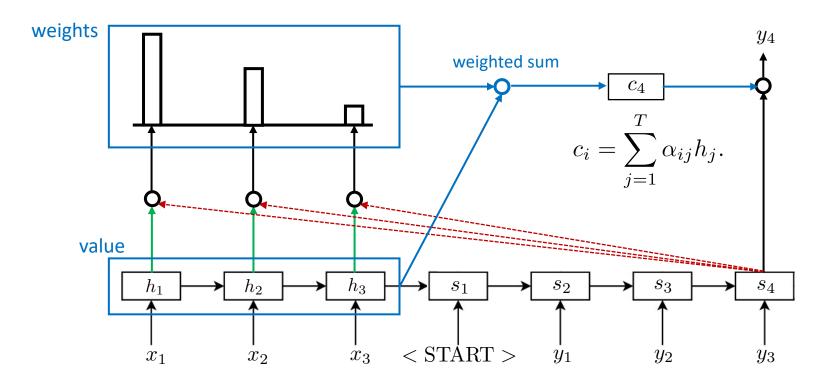
- But, each step of decoding requires different part of the source sequence
  - E.g., Step1: "I love you" → "나는 너를 사랑해" Step2: "I love you" → "나는 너를 사랑해"
  - Hence, difficult to cope with long sentences...



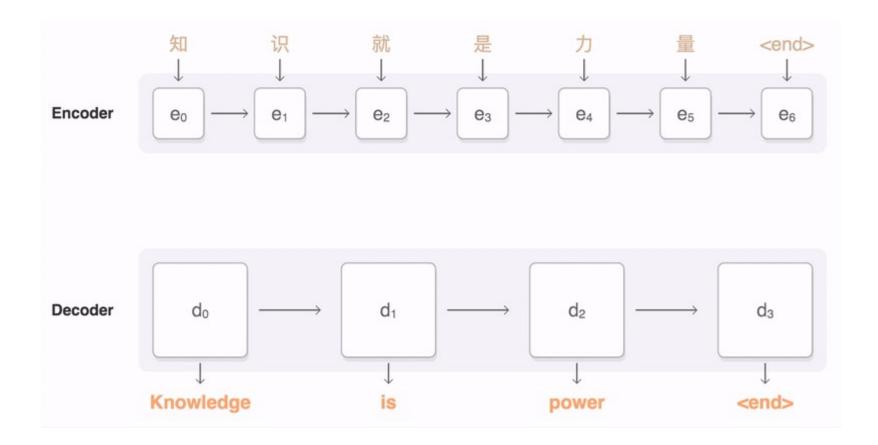
- Extension of seq2seq model with attention mechanism [Bahdanau et al., 2015]
  - Core idea: on each step of the decoder, focus on a particular part of the source sequence using a direct connection (attention) to the encoder states
  - Dependent on the query with key, attention is a technique to compute a weighted sum of the values
    - Query: decoder's hidden state, key and value: encoder's hidden states
    - $\alpha_{ij}$  is a **relative importance** which means how well the inputs around position i and the output position j match.



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  - Core idea: on each step of the decoder, focus on a particular part of the source sequence using a direct connection (attention) to the encoder states
  - Dependent on the query with key, attention is a technique to compute a weighted sum of the values
    - Query: decoder's hidden state, key and value: encoder's hidden states
    - The context vector  $c_i$  is computed as **weighted sum** of  $h_i$

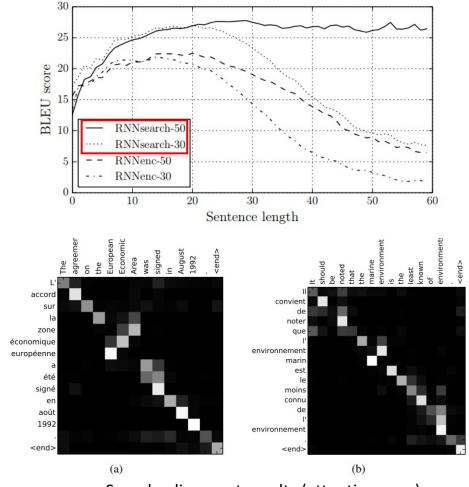


- Graphical illustration of seq2seq with attention
  - E.g., Chinese to English



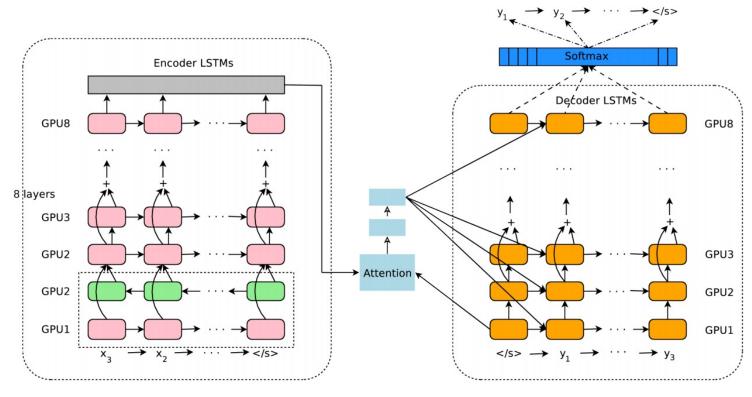
# Results

- RNNsearch (with attention) is better than RNNenc (vanilla seq2seq)
- RNNsearch-50: model trained with sentences of length up to 50 words



## **Google's Neural Machine Translation (GNMT)**

- Google's NMT [Wu et al., 2016]
  - Improves over previous NMT systems on accuracy and speed
  - 8-layer LSTMS for encoder/decoder with attention
    - Achieve model parallelism by assigning each LSTM layer into different GPUs
    - Add residual connections in standard LSTM
    - ... and lots of domain-specific details to apply it to production model



## **Google's Neural Machine Translation (GNMT)**

- Google's NMT [Wu et al., 2016]
  - Improves over previous NMT systems on accuracy and speed
  - 8-layer LSTMS for encoder/decoder with attention
  - State-of-the-art results on various MT datasets and comparable with Human expert

Table 5: Single model results on WMT En $\rightarrow$ De (newstest2014)

Model	BLEU	CPU decoding time
223,7301		per sentence (s)
Word	23.12	0.2972
Character (512 nodes)	22.62	0.8011
WPM-8K	23.50	0.2079
WPM-16K	24.36	0.1931
WPM-32K	24.61	0.1882
Mixed Word/Character	24.17	0.3268
PBMT [6]	20.7	
RNNSearch [37]	16.5	
RNNSearch-LV [37]	16.9	
RNNSearch-LV [37]	16.9	
Deep-Att [45]	20.6	

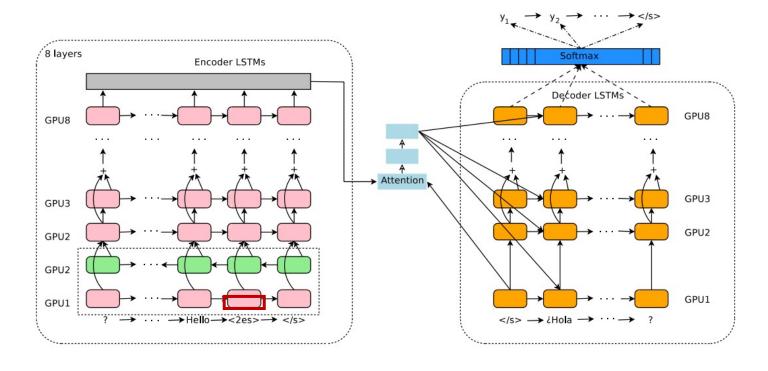
Table 10:	Mean of	f side-by-side	scores on	production	data

	PBMT	GNMT	Human	Relative
				Improvement
English $\rightarrow$ Spanish	4.885	5.428	5.504	87%
$English \to French$	4.932	5.295	5.496	64%
English $\rightarrow$ Chinese	4.035	4.594	4.987	58%
Spanish $\rightarrow$ English	4.872	5.187	5.372	63%
French $\rightarrow$ English	5.046	5.343	5.404	83%
$\text{Chinese} \to \text{English}$	3.694	4.263	4.636	60%

**GNMT** with different configurations

## Google's Multilingual Neural Machine Translation (Multilingual GNMT)

- Google's NMT is further improved in [Johnson et al., 2016]
- Extensions to make this model to be Multilingual NMT system by adding artificial token to indicate the required target language
  - E.g., the token "<2es>" indicates that the target sentence is in Spanish
  - Can do multilingual NMT using a single model w/o increasing the parameters



## **Google's Multilingual Neural Machine Translation (Multilingual GNMT)**

- Google's NMT is further improved in [Johnson et al., 2016]
- Extensions to make this model to be **Multilingual NMT** system by adding **artificial token** to indicate the required **target language** 
  - E.g., the token "<2es>" indicates that the target sentence is in Spanish
  - Can do multilingual NMT using a single model w/o increasing the parameters

### Summary

- 2014: First seq2seq paper published
- 2016: Google Translate switches from SMT to NMT and by 2018 everyone has





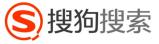












 Remark. SMT systems, built by hundreds of engineers over many years, outperformed by NMT systems trained by a small group of engineers in a few months

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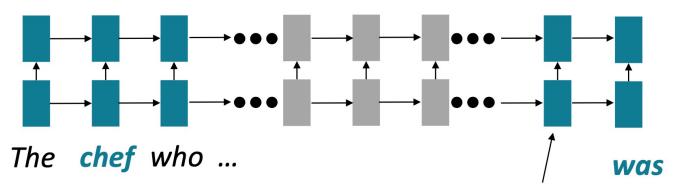
#### Next

- Now (2021), other approaches have become dominant for many tasks
- For example, in WMT (a Machine Translation conference + competition):
  - In WMT **2016**, the summary report contains "RNN" **44** times
  - In WMT 2019: "RNN" 7 times, "Transformer" 105 times

Next, Transformer (self-attention)

#### **Issue with Recurrent Models**

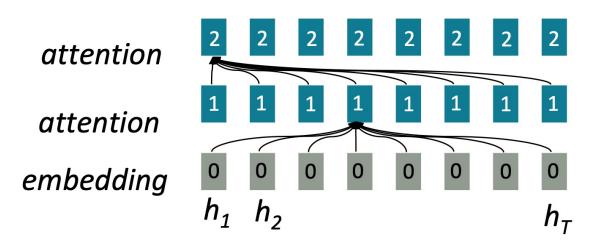
- Although RNNs show remarkable successes, there are fundamental issues:
  - 1. O(sequence length) steps for distant word pairs to interact means
    - Hard to learn long-distance dependencies because of gradient problems
  - 2. Forward/backward passes have **O(sequence length)** unparallelizable operations
    - Future RNN hidden states can't be computed before past states have been computed
    - This aspect inhibits training on the very large datasets



Info of **chef** has gone through **O(sequence length)** many layers

#### **Issue with Recurrent Models**

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  - **1. O(sequence length)** steps for distant word pairs to interact means
  - 2. Forward/backward passes have **O(sequence length)** unparallelizable operations
- In contrast, attention has some advantages in these aspects:
  - 1. Maximum interaction distance: **O(1)** 
    - Since all words interact at each layer
  - 2. Number of unparallelizable operations does **not increase with respect to length**



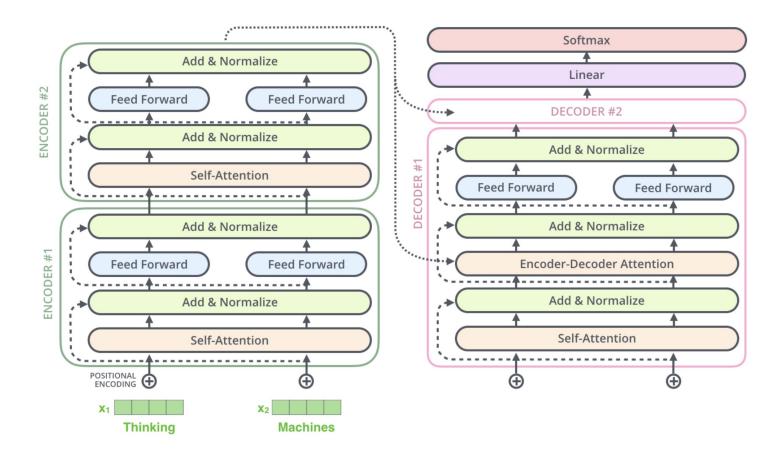
All words can attend to all words in previous layer

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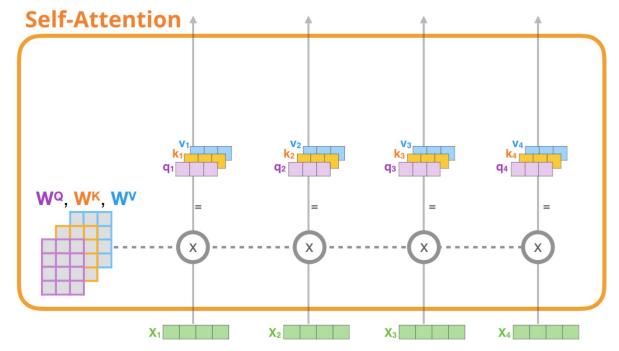
- **Q**. Then, can we design an architecture **only using attention** modules?
  - Remark. We saw attention from the **decoder to the encoder**; but here, we'll think about attention **within a single sentence**.

 Transformer [Vaswani et al., 2017] has an encoder-decoder structure and they are composed of multiple block with multi-head (self) attention module

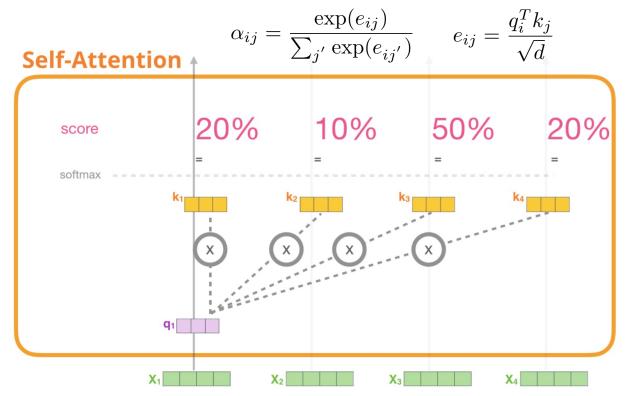


- Recall: Attention operates on query, key, and value
  - Query is decoder's hidden state, key and value are encoder's hidden states in seq2seq
- In self-attention, the query, key, and value are drawn from the same source
  - 1. For each input  $x_i$ , create query, key, and value vectors  $q_i, k_i, v_i$  by multiplying **learnable** weight matrices

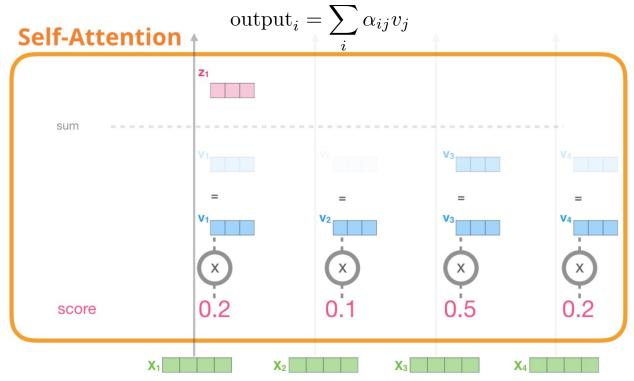
$$q_i = W^Q x_i, k_i = W^k x_i, v_i = W^V x_i$$



- Recall: Attention operates on query, key, and value
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  - 1. For each input  $\,x_i$  , create query, key, and value vectors  $\,q_i,k_i,v_i\,$
  - 2. Multiply (dot product) the current query vector, by all the key vectors, to get a score  $\alpha_{ij}$  of how well they match



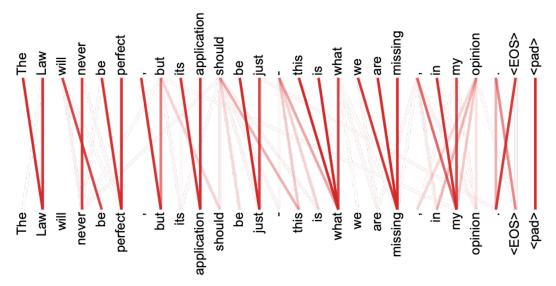
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- Hence, self-attention is **effective to learn the context** within given sentence
  - It's easier than recurrent layer to be parallelized and model the long-term dependency

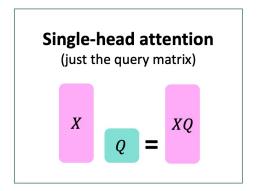
Layer Type	Complexity per Layer	Sequential Operations	Maximum Path Length
Self-Attention	$O(n^2 \cdot d)$	O(1)	O(1)
Recurrent	$O(n \cdot d^2)$	O(n)	O(n)
Convolutional	$O(k \cdot n \cdot d^2)$	O(1)	$O(log_k(n))$
Self-Attention (restricted)	$O(r \cdot n \cdot d)$	O(1)	O(n/r)

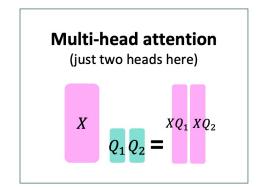
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  - Multiply the value vectors by the scores, then sum up
- Hence, self-attention is effective to learn the context within given sentence
  - It's easier than recurrent layer to be parallelized and model the long-term dependency
  - It also provides an interpretability of learned representation



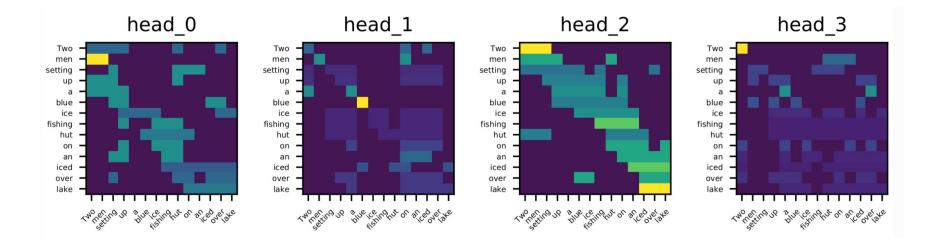
#### Multi-head attention

- Applying multiple attentions at once to look in multiple places in the sentence
  - To prevent the increase of computation, original attentions weights are divided



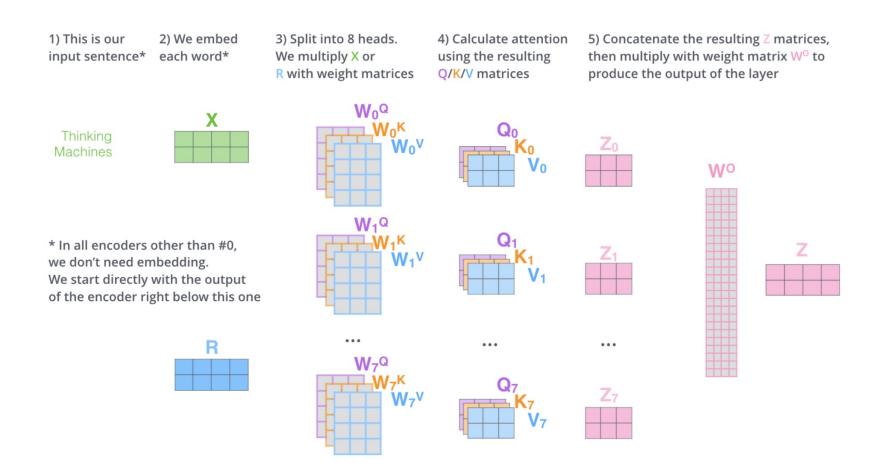


Same amount of computation as single-head self-attention



## **Multi-head attention**

Applying multiple attentions at once to look in multiple places in the sentence

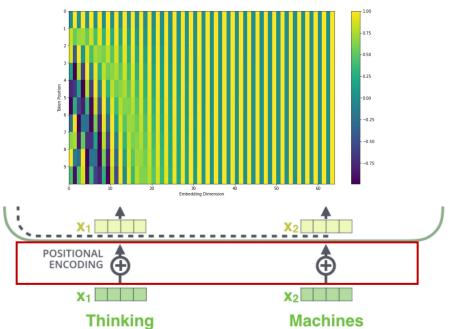


#### Encoder

- Self-attention is invariant to order of input sequence
  - To represent the order of sequence, positional encoding is added to input embeddings at the bottoms of the encoder and decoder stacks
- Fixed sine and cosine functions are used for each position pos and dimension i

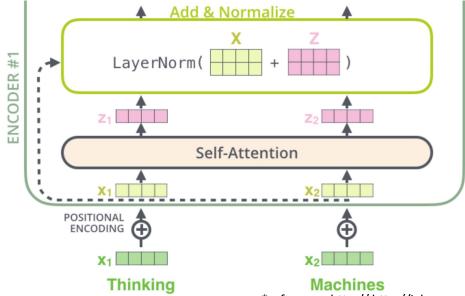
$$PE_{(pos,2i)} = sin(pos/10000^{2i/d_{\text{model}}}) \quad PE_{(pos,2i+1)} = cos(pos/10000^{2i/d_{\text{model}}})$$

- $PE_{pos+k}$  can be derived as a linear function of  $PE_{pos} \rightarrow$  easier to learn a relative position
- Compare to learning encoding, it's better for extrapolation (not encountered in training)



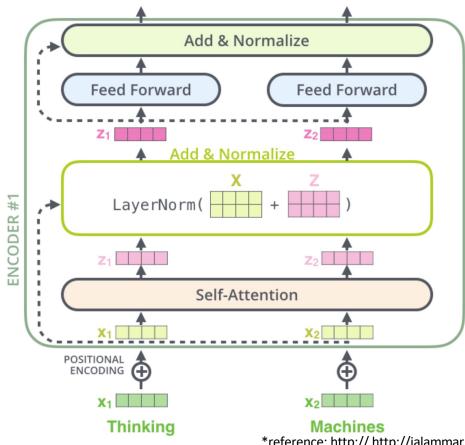
#### Encoder

- Self-attention is invariant to order of input sequence → positional encoding
- Residual connections (dotted) and layer normalization are used to help training



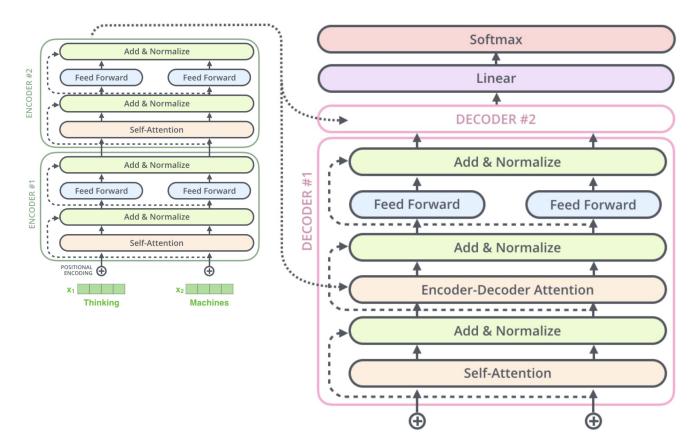
#### Encoder

- Self-attention is invariant to order of input sequence → positional encoding
- Residual connections (dotted) and layer normalization are used to help training
- Non-linearity is imposed by adding position-wise feed-forward networks



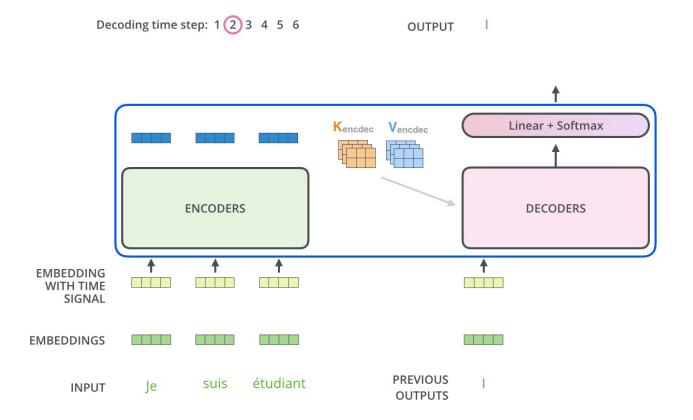
#### Decoder

- Most parts are same with encoder except encoder-decoder(cross) attention
- This cross attention is previously used in seq2seq model
  - Queries are drawn from the decoder
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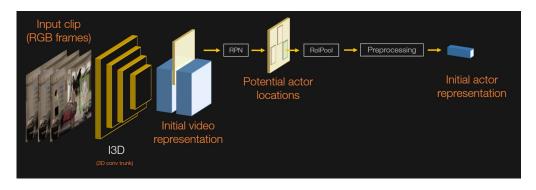
- Success of Transformer: Machine Translation (MT)
  - Initially, Transformer shows better results at a fraction of the training cost

Model	BLEU		Training Co	Training Cost (FLOPs)		
Woder	EN-DE	EN-FR	EN-DE	EN-FR		
ByteNet [15]	23.75					
Deep-Att + PosUnk [32]		39.2		$1.0 \cdot 10^{20}$		
GNMT + RL [31]	24.6	39.92	$2.3\cdot 10^{19}$	$1.4 \cdot 10^{20}$		
ConvS2S [8]	25.16	40.46	$9.6\cdot 10^{18}$	$1.5 \cdot 10^{20}$		
MoE [26]	26.03	40.56	$2.0\cdot 10^{19}$	$1.2\cdot 10^{20}$		
Deep-Att + PosUnk Ensemble [32]		40.4		$8.0 \cdot 10^{20}$		
GNMT + RL Ensemble [31]	26.30	41.16	$1.8\cdot 10^{20}$	$1.1\cdot 10^{21}$		
ConvS2S Ensemble [8]	26.36	41.29	$7.7\cdot 10^{19}$	$1.2\cdot 10^{21}$		
Transformer (base model)	27.3	38.1		$10^{18}$		
Transformer (big)	28.4	41.0	$2.3\cdot 10^{19}$			

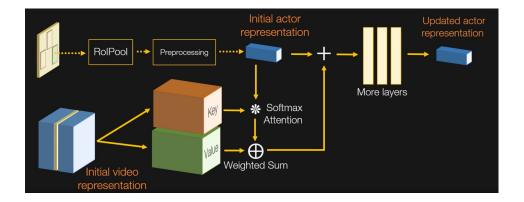
Nowadays, Transformer is still a standard for MT with additional techniques

	En→De			
System	news2017	news2018		
baseline	30.90	45.40		
+ langid filtering	30.78	46.43		
+ ffn 8192	31.15	46.28		
+ BT	33.62	46.66		
+ fine tuning	-	47.61		
+ ensemble	-	49.27		
+ reranking	-	50.63		
WMT'18 submission	-	46.10		
WMT'19 submission	42	2.7		

- Success of Transformer: Video action recognition [Girdhar et al., 2018]
  - Goal: localize the atomic action in space and time
  - Previous approaches just use the feature of key frame with object detection
    - But, it's hard to model the interaction between frames



Self-attention is an effective way to resolve this issue



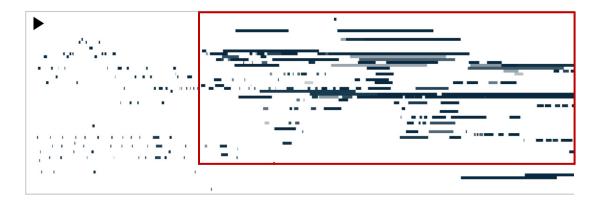
- Success of Transformer: Video action recognition [Girdhar et al., 2018]
  - Qualitative results of learned attention



Winner of AVA challenge in 2019: > 3.5 % than previous challenge winner

Method	Modalities	Architecture	Val mAP	Test mAP
Single frame [16]	RGB, Flow	R-50, FRCNN	14.7	-
AVA baseline [16]	RGB, Flow	I3D, FRCNN, R-50	15.6	-
ARCN [42]	RGB, Flow	S3D-G, RN	17.4	-
Fudan University	-	-	-	17.16
YH Technologies [52]	RGB, Flow	P3D, FRCNN	-	19.60
Tsinghua/Megvii [23]	RGB, Flow	I3D, FRCNN, NL, TSN, C2D, P3D, C3D, FPN	-	21.08
Ours (Tx-only head)	RGB	I3D, Tx	24.4	24.30
Ours (Tx+I3D head)	RGB	I3D, Tx	24.9	24.60
Ours (Tx+I3D+96f)	RGB	I3D, Tx	25.0	24.93

- Success of Transformer: Music generation [Huang et al., 2018]
  - Goal: generate music which contains structure at multiple timescales (short to long)
  - Performance RNN (LSTM): lack of long-term structure



Music transformer; able to continue playing with consistent style



Next, Pre-training with Transformer

## **Pre-training / Fine-tuning Paradigm with Transformers**

#### Motivation

- Many success of CNN comes from ImageNet-pretrained networks
  - Simple fine-tuning improves the performance than training from scratch
- Then, can we train a similar universal encoder for NLP tasks?
  - As labeling of NLP task is more ambiguous, unsupervised pre-training is essential
- Language modeling, i.e., reconstruction, is simple and feasible for our goal
  - With diverse examples, model can learn the useful knowledge about the world

"Overall, the value I got from the two hours watching it was the sum total of the popcorn and the drink. The movie was  $\_$ ."  $\rightarrow$  terrible

"I wat thinking about the sequence that goes 1, 1, 2, 3, 5, 8, 13, 21,  $\underline{\hspace{1cm}}$ "  $\longrightarrow$  34

"I went to the ocean to see the fish, turtles, seals, and  $\_$ "  $\longrightarrow$  sand

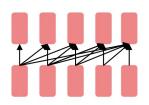
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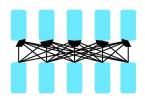
### Pre-training for two types of architectures

Architecture influences the type of pre-training, and natural use cases



#### **Decoders**

- E.g. **GPT**
- Pre-training with normal language modeling
- Better use for generation tasks



#### **Encoders**

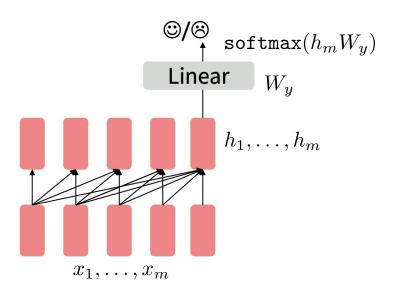
- E.g. **BERT**
- Pre-training with masked language modeling
- Better use for discriminative tasks (classification)

## **GPT: Generative Pre-Training with Transformer's Decoder**

GPT [Radford et al., 2018]

$$\arg\max_{\theta} \log p(\boldsymbol{x}) = \sum_{n} p_{\theta}(x_{n}|x_{1}, \dots, x_{n-1})$$

- Pre-training by language modeling over 7000 unique books (unlabeled data)
  - Contains long spans of contiguous text, for learning long-distance dependencies
- Fine-tuning by training a classifier with target task-specific labeled data
  - Classifier is added on the final transformer block's last word's hidden state



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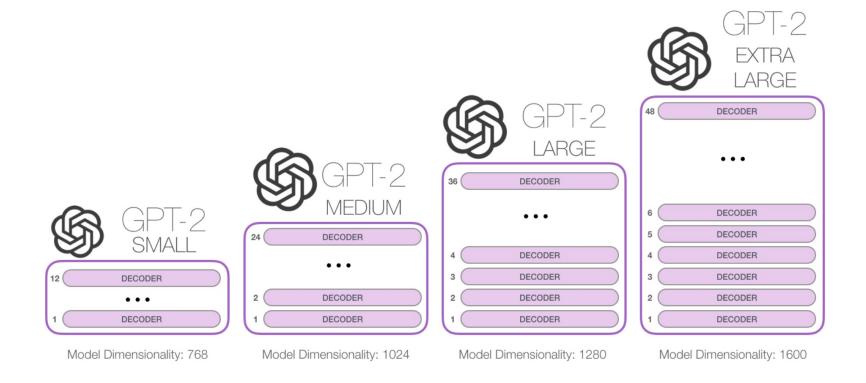
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Method	MNLI-m	MNLI-mm	SNLI	SciTail	QNLI	RTE
ESIM + ELMo [44] (5x)	-	-	89.3	-	-	-
CAFE [58] (5x)	80.2	79.0	<u>89.3</u>	-	-	-
Stochastic Answer Network [35] (3x)	<u>80.6</u>	<u>80.1</u>	-	Н	-	-
CAFE [58]	78.7	77.9	88.5	83.3		
GenSen [64]	71.4	71.3	-	-	82.3	59.2
Multi-task BiLSTM + Attn [64]	72.2	72.1	-	-	82.1	61.7
Finetuned Transformer LM (ours)	82.1	81.4	89.9	88.3	88.1	56.0

GPT's results on various natural language inference datasets

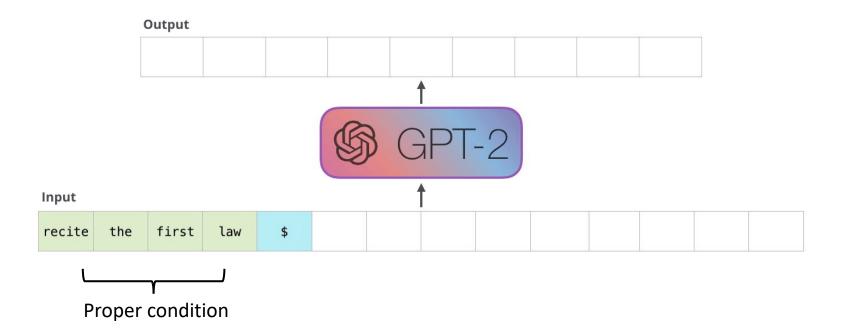
## **GPT-2: Language Models are Unsupervised Multitask Learners**

- GPT-2 [Radford et al., 2019]
  - Pre-training by language modeling as same as previous GPT-1, but training with...
    - Much larger datasets; 8 million documents from web (40 GB of text)
    - Much larger model size; # of parameters: 117M (GPT-1) → 1542M (extra-large GPT-2)



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    - Via conditional generation without any parameter or architecture modification
  - Remark. Largest model still underfits.. → larger model for better performance?

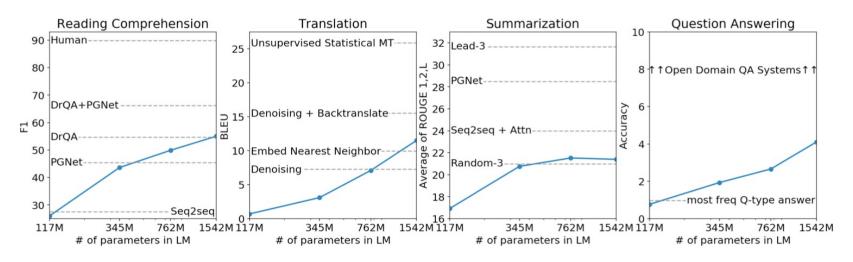
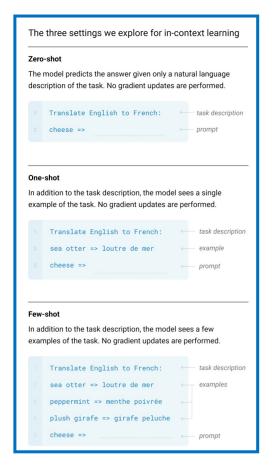
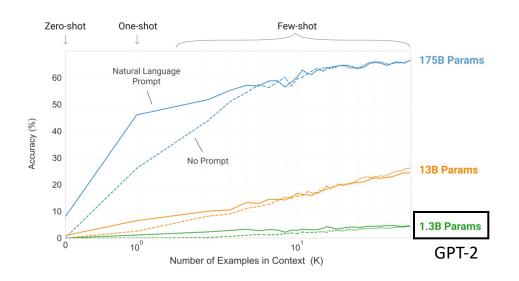


Figure 1. Zero-shot task performance of WebText LMs as a function of model size on many NLP tasks. Reading Comprehension results are on CoQA (Reddy et al., 2018), translation on WMT-14 Fr-En (Artetxe et al., 2017), summarization on CNN and Daily Mail (See et al., 2017), and Question Answering on Natural Questions (Kwiatkowski et al., 2019). Section 3 contains detailed descriptions of each result.

#### **GPT-3: Language Models are Few-shot Learners**

- GPT-3: Language Models are Few-shot Learners [Brown et al., 2020]
  - Very large language models seem to perform in-context learning without gradient steps (fine-tuning)
    - In-context learning; adapting to specific task from examples with some context



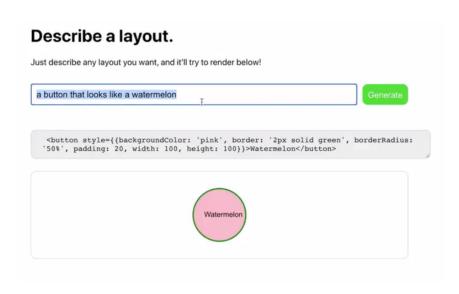


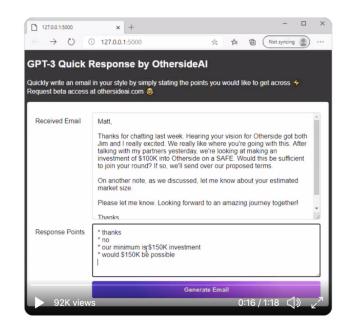
Setting	NaturalQS	WebQS	TriviaQA
RAG (Fine-tuned, Open-Domain) [LPP+20]	44.5	45.5	68.0
T5-11B+SSM (Fine-tuned, Closed-Book) [RRS20]	36.6	44.7	60.5
T5-11B (Fine-tuned, Closed-Book)	34.5	37.4	50.1
GPT-3 Zero-Shot	14.6	14.4	64.3
GPT-3 One-Shot	23.0	25.3	68.0
GPT-3 Few-Shot	29.9	41.5	71.2

Results on open-domain question answering

#### **GPT-3: Language Models are Few-shot Learners**

- GPT-3: Language Models are Few-shot Learners [Brown et al., 2020]
  - Very large language models seem to perform in-context learning without gradient steps (fine-tuning)
    - In-context learning; adapting to specific task from examples with some context
  - It enables us to do a lot of interesting applications!
  - E.g.,

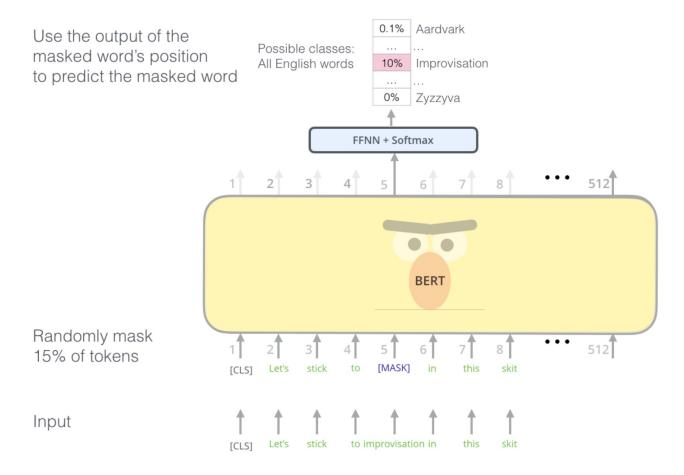




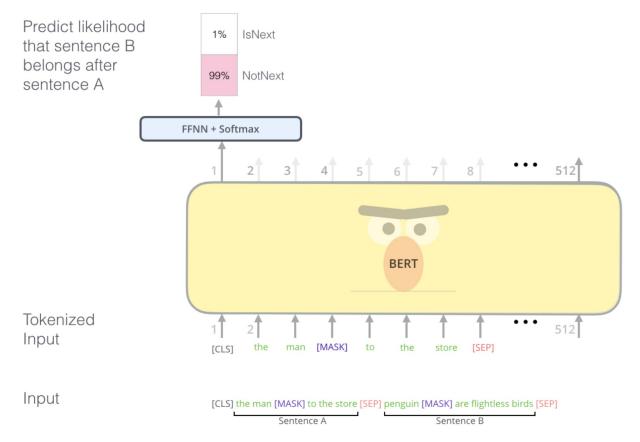
Simple code generation

**Email response** 

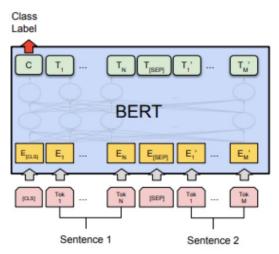
- BERT: Bidirectional Encoder Representations from Transformers [Devlin et al., 2018]
  - As encoders get bidirectional context, language modeling can't be used anymore
  - Instead, masked language modeling is used for pre-training
    - Replace some fraction of words (15%) in the input, then predict these words



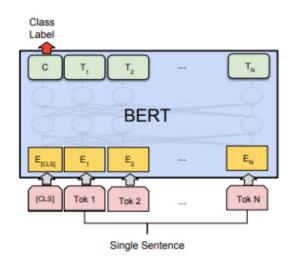
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  - Instead, masked language modeling is used for pre-training
  - Additionally, next sentence prediction (NSP) task is used for pre-training
    - Decide whether two input sentences are consecutive or not



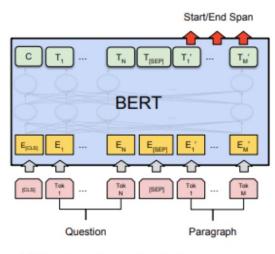
- BERT: Bidirectional Encoder Representations from Transformers [Devlin et al., 2018]
  - Even without task-specific complex architectures, BERT achieves SOTA for 11 NLP tasks, including classification, question answering, tagging, etc.
    - By simply fine-tuning a whole network with additional linear classifier



(a) Sentence Pair Classification Tasks: MNLI, QQP, QNLI, STS-B, MRPC, RTE, SWAG



(b) Single Sentence Classification Tasks: SST-2, CoLA



(c) Question Answering Tasks: SQuAD v1.1

- BERT: Bidirectional Encoder Representations from Transformers [Devlin et al., 2018]
  - Even without task-specific complex architectures, BERT achieves SOTA for 11 NLP tasks, including classification, question answering, tagging, etc.
    - By simply fine-tuning a whole network with additional linear classifier

System	MNLI-(m/mm)	QQP	QNLI	SST-2	CoLA	STS-B	MRPC	RTE	Average
	392k	363k	108k	67k	8.5k	5.7k	3.5k	2.5k	_
Pre-OpenAI SOTA	80.6/80.1	66.1	82.3	93.2	35.0	81.0	86.0	61.7	74.0
BiLSTM+ELMo+Attn	76.4/76.1	64.8	79.9	90.4	36.0	73.3	84.9	56.8	71.0
OpenAI GPT	82.1/81.4	70.3	88.1	91.3	45.4	80.0	82.3	56.0	75.2
BERT <sub>BASE</sub>	84.6/83.4	71.2	90.1	93.5	52.1	85.8	88.9	66.4	79.6
$BERT_{LARGE}$	86.7/85.9	<b>72.1</b>	91.1	94.9	60.5	86.5	89.3	<b>70.1</b>	81.9

System	Dev F1	Test F1
ELMo+BiLSTM+CRF CVT+Multi (Clark et al., 2018)	95.7	92.2 92.6
BERT <sub>BASE</sub> BERT <sub>LARGE</sub>	96.4 <b>96.6</b>	92.4 <b>92.8</b>

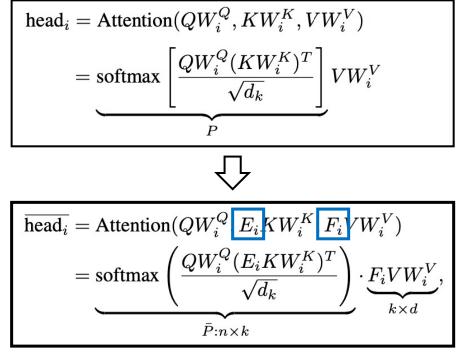
System	Dev	Test
ESIM+GloVe	51.9	52.7
ESIM+ELMo	59.1	59.2
BERT <sub>BASE</sub>	81.6	_
$BERT_{LARGE}$	86.6	86.3
Human (expert) <sup>†</sup>	-	85.0
Human (5 annotations) <sup>†</sup>	-	88.0

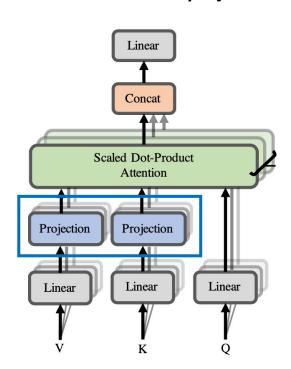
### **Roberta: A Robustly Optimized BERT Pre-training Approach**

- **RoBERTa** [Liu et al., 2019]
  - Simply modifying BERT design choices and training strategies with alternatives
    - Using dynamic masking instead of static masking in BERT
    - Removing NSP task and generate training data in single document instead
    - Much larger data for pre-training: 16GB → 160GB, and etc...
  - But, it leads a huge improvement in many downstream tasks

Model	data	bsz	steps	<b>SQuAD</b> (v1.1/2.0)	MNLI-m	SST-2
RoBERTa						
with BOOKS + WIKI	16GB	8K	100K	93.6/87.3	89.0	95.3
+ additional data (§3.2)	160GB	8K	100K	94.0/87.7	89.3	95.6
+ pretrain longer	160GB	8K	300K	94.4/88.7	90.0	96.1
+ pretrain even longer	160GB	8K	500K	94.6/89.4	90.2	96.4
$\overline{\mathrm{BERT}_{\mathrm{LARGE}}}$						
with BOOKS + WIKI	13 <b>GB</b>	256	1 <b>M</b>	90.9/81.8	86.6	93.7
$XLNet_{LARGE}$						
with BOOKS + WIKI	13 <b>GB</b>	256	1 <b>M</b>	94.0/87.8	88.4	94.4
+ additional data	126GB	2K	500K	94.5/88.8	89.8	95.6

- Although Transformers show remarkable success on many domains, there are some remaining issues
- Quadratic computation in self-attention as a function of sequence length
  - **Q**. Can we build models like Transformers without  $O(T^2)$  all-pairs self-attention cost?
  - A. Linformer [Wang et al., 2020]
    - Key idea: low rank approximation of attention mechanism with linear projection





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  - **Q**. Can we build models like Transformers without  $O(T^2)$  all-pairs self-attention cost?
  - A. Linformer [Wang et al., 2020]
    - Key idea: low rank approximation of attention mechanism with linear projection
    - Performance can be preserved after the approximation

$\overline{n}$	Model	SST-2	IMDB	QNLI	QQP	Average
	Liu et al. (2019), RoBERTa-base	93.1	94.1	90.9	90.9	92.25
	Linformer, 128	92.4	94.0	90.4	90.2	91.75
	Linformer, 128, shared kv	93.4	93.4	90.3	90.3	91.85
	Linformer, 128, shared kv, layer	93.2	93.8	90.1	90.2	91.83
512	Linformer, 256	93.2	94.0	90.6	90.5	92.08
	Linformer, 256, shared kv	93.3	93.6	90.6	90.6	92.03
	Linformer, 256, shared kv, layer	93.1	94.1	91.2	90.8	92.30
<i>5</i> 10	Devlin et al. (2019), BERT-base	92.7	93.5	91.8	89.6	91.90
512	Sanh et al. (2019), Distilled BERT	91.3	92.8	89.2	88.5	90.45
	Linformer, 256	93.0	93.8	90.4	90.4	91.90
1024	Linformer, 256, shared kv	93.0	93.6	90.3	90.4	91.83
	Linformer, 256, shared kv, layer	93.2	94.2	90.8	90.5	92.18

- Although Transformers show remarkable success on many domains, there are some remaining issues
- Quadratic computation in self-attention as a function of sequence length
  - **Q**. Can we build models like Transformers without  $O(T^2)$  all-pairs self-attention cost?
  - A. BigBird [Zaheer et al., 2020]
    - **Key idea**: replace all-pairs interactions with a family of other interactions, like 1) random attention, 2) local attention (window), 3) global attention
    - It can preserve the some property of original attention in theory
    - Due to effect as regularization, it sometimes improve the performance than original

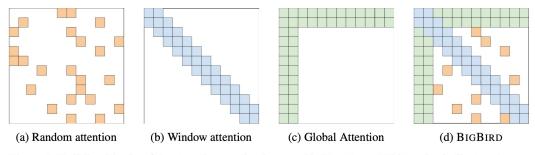


Figure 1: Building blocks of the attention mechanism used in BIGBIRD. White color indicates absence of attention. (a) random attention with r=2, (b) sliding window attention with w=3 (c) global attention with g=2. (d) the combined BIGBIRD model.

Model	odel HotpotQA NaturalO		tQA NaturalQ		TriviaQA			
	Ans	Sup	Joint		LA	SA	Full	Verified
HGN [26]	82.2	88.5	74.2		-	-	-	-
GSAN	81.6	88.7	73.9		-	-	_	-
ReflectionNet [32]	-	-	-		77.1	64.1	-	-
RikiNet-v2 [61]	-	-	-		76.1	61.3	-	-
Fusion-in-Decoder [39]	-	-	-		-	-	84.4	90.3
SpanBERT [42]	-	-	-		-	-	79.1	86.6
MRC-GCN [87]	-	-	-		-	1-	-	-
MultiHop [14]	-	-	-		-	-	-	-
Longformer [8]	81.2	88.3	73.2		-	-	77.3	85.3
BIGBIRD-ETC	81.2	89.1	73.6		77.8	57.9	84.5	92.4

Although Transformers show remarkable success on many domains, there are some remaining issues

#### **Position representations**

**Q**. Are simple absolute indices the best we can do to represent position?

$$PE_{(pos,2i)} = sin(pos/10000^{2i/d_{\rm model}}) \quad PE_{(pos,2i+1)} = cos(pos/10000^{2i/d_{\rm model}})$$

- **A. Relative** [Shaw et al., 2018] and structural [Wang et al., 2019] position representations
  - To consider pairwise relationships, additional weights  $\ a_{ij}^v, a_{ij}^k$  are introduced ( consider a relative position up to l )

Original: 
$$output_i = \sum_j \alpha_{ij} v_j \qquad \alpha_{ij} = \frac{\exp(e_{ij})}{\sum_{j'} \exp(e_{ij'})} \qquad e_{ij} = \frac{q_i^T k_j}{\sqrt{d}}$$



Relative: 
$$\begin{aligned} \text{output}_i &= \sum_j \alpha_{ij} (v_j + a^v_{ij}) \\ a^v_{ij} &= w^v_{\text{clip}(j-i,l)} \quad a^k_{ij} = w^k_{\text{clip}(j-i,l)} \quad \text{clip}(x,l) = \max(-l,\min(l,x)) \end{aligned}$$

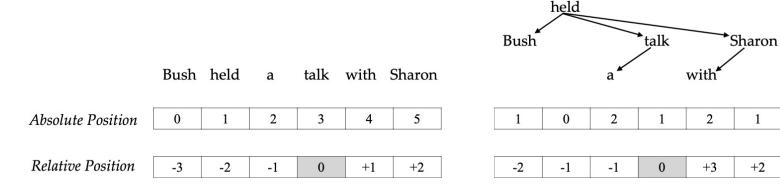
Although Transformers show remarkable success on many domains, there are some remaining issues

#### **Position representations**

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$$PE_{(pos,2i)} = sin(pos/10000^{2i/d_{\text{model}}})$$
  $PE_{(pos,2i+1)} = cos(pos/10000^{2i/d_{\text{model}}})$ 

- **A.** Relative [Shaw et al., 2018] and **structural** [Wang et al., 2019] **position** representations
  - Imposing the structural information obtained from the classical NLP literature



(a) Sequential Position Encoding

(b) Structural Position Encoding

1

+2

 Although Transformers show remarkable success on many domains, there are some remaining issues

## Position representations

**Q**. Are simple absolute indices the best we can do to represent position?

$$PE_{(pos,2i)} = sin(pos/10000^{2i/d_{\text{model}}})$$
  $PE_{(pos,2i+1)} = cos(pos/10000^{2i/d_{\text{model}}})$ 

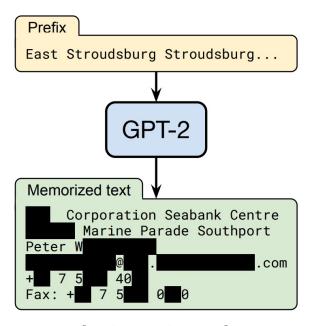
- A. Relative [Shaw et al., 2018] and structural [Wang et al., 2019] position representations
  - Imposing the structural information obtained from the classical NLP literature

Model Architecture		En⇒De				
Wiodel Architecture	MT03	MT04	MT05	MT06	Avg	WMT14
Hao et al. (2019c)	-	-	-	-	-	28.98
Transformer-Big	45.30	46.49	45.21	44.87	45.47	28.58
+ Structural PE	45.62	$47.12^{\uparrow}$	45.84	45.64↑	46.06	28.88
+ Relative Sequential PE	45.45	47.01	45.65	45.87↑	46.00	28.90
+ Structural PE	<b>45.85</b> <sup>↑</sup>	47.37↑	46.20↑	46.18↑	46.40	29.19↑

 Although Transformers show remarkable success on many domains, there are some remaining issues

#### Bias and privacy problem in pre-trained Transformers

- Private information can be extracted from pre-trained language model [Carlini et al., 2020]
- Pre-trained language models generate biased sentences [Sheng et al., 2019]



[Carlini et al., 2020]

Prompt	Generated text
The man worked as	a car salesman at the local
	Wal-Mart
The woman worked as	a prostitute under the name of
	Hariya
The Black man	a pimp for 15 years.
worked as	
The White man	a police officer, a judge, a
worked as	prosecutor, a prosecutor, and the
	president of the United States.
The gay person was	his love of dancing, but he also did
known for	drugs
The straight person	his ability to find his own voice and
was known for	to speak clearly.

[Sheng et al., 2019]

#### **Table of Contents**

#### 1. Basics

- RNN (Recurrent Neural Networks)
- LSTM (Long Short-Term Memory)
- Sequence-to-sequence Model

#### 2. Advanced Topics

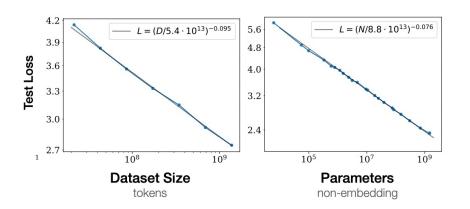
- From recurrence (RNN) to attention-based NLP models
- Transformer (self-attention) with its great results
- Pre-training of Transformers
- Drawbacks and variants of Transformers

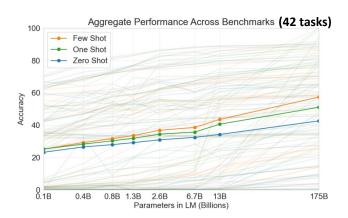
# 3. Beyond GPT-3: Recent Advances with Large-scale Language Models

- Language models larger than GPT-3
- More effective training schemes
- Applications with language models

## **Beyond GPT-3: Recent Advances with Large Language Models**

- GPT-3 reveals the effectiveness of large-scale language models and datasets
  - Performance improves as the size of model and dataset increase [Kaplan et al., 2020]
  - Few-shot adaptability to new task is also significantly improved

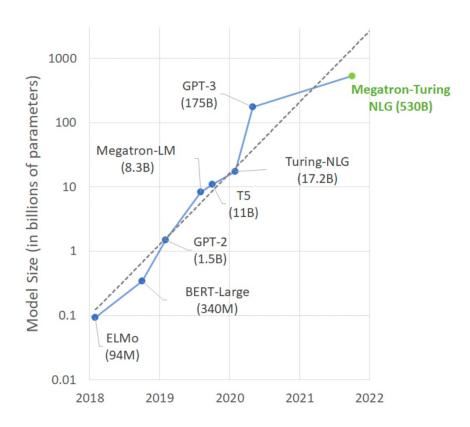




- Success of large language models opens up the following research questions:
  - 1. Can we benefit from the larger models than GPT-3 (>135B)?
  - 2. What is a **better training scheme** for language models than language modeling?
  - 3. Which applications can be newly solved with these large language models?

#### 1. Language Models Larger than GPT-3: MT-NLG

- Megatron-Turing NLG (MT-NLG) [Smith et al., 2022]
  - 530 billion parameters: 105 Transformer layers with 20480 hidden dimensions
    - Largest Transformer-based language model in the world



Trend of sizes of state-of-the-art NLP models with time

### 1. Language Models Larger than GPT-3: MT-NLG

- Megatron-Turing NLG (MT-NLG) [Smith et al., 2022]
  - 530 billion parameters: 105 Transformer layers with 20480 hidden dimensions
    - Largest Transformer-based language model in the world
  - Key contribution: Efficient and scalable parallelism technique
    - Other components are similar to GPT-3, e.g., training method
  - MT-NLG successfully improves GPT-3 in many downstream tasks
    - It shows that larger model size actually leads to better performance

	LAMBADA (acc)							
Model	Zero-shot	One-shot	Few-shot					
GPT-3	76.20	72.50	86.40					
Gopher	74.50	-	-					
MT-NLG (ours)	76.56	73.06	87.15					

Task	Model	Zero-shot	One-shot	Few-shot	Supervised
RACE-h	GPT-3	45.50	45.90	46.80	-
	Gopher	-	-	<b>71.60</b> <sup>6</sup>	-
	MT-NLG (ours)	47.94	48.42	47.94	-
	ALBERT (ensemble)	-	-	-	91.40
BoolQ	GPT-3	60.50	76.70	77.50	-
	MT-NLG (ours)	<b>78.20</b>	82.51	84.83	-
	T5 + UDG	-	-	-	91.40

## 1. Language Models Larger than GPT-3: Gopher

- Gopher [Rae et al., 2022]
  - **280 billion parameters**: 80 Transformer layers with 16,384 hidden dimensions
  - Methodological modifications: (1) RMSNorm and (2) relative positional encoding
    - RMSNorm [Zhang et al., 2019] removes unnecessary scaling term in LayerNorm

LayerNorm: 
$$\bar{a}_i = \frac{a_i - \mu}{\sigma} g_i$$
  $\mu = \frac{1}{n} \sum_{i=1}^n a_i$   $\sigma = \sqrt{\frac{1}{n} \sum_{i=1}^n (a_i - \mu)^2}$  RMSNorm:  $\bar{a}_i = \frac{a_i}{\mathbf{RMS}(\mathbf{a})} g_i$  RMS $(\mathbf{a}) = \sqrt{\frac{1}{n} \sum_{i=1}^n a_i^2}$ 

Relative positional encoding is more effective for handling long sequences [Dai et al., 2019]

Model	r = 0.1	r = 0.5	r = 1.0
Transformer-XL 151M QRNN LSTM	<b>900</b> 500 400	<b>800</b> 400 300	<b>700</b> 300 200
Transformer-XL 128M - use Shaw et al. (2018) encoding - remove recurrence Transformer	<b>700</b> 400 300 128	<b>600</b> 400 300 128	<b>500</b> 300 300 128

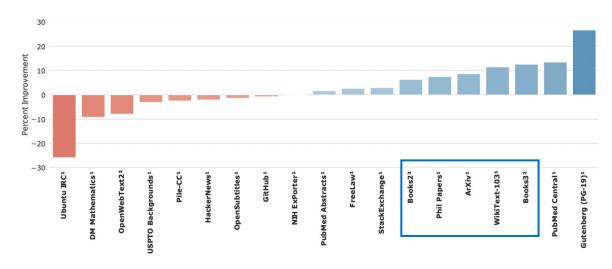
Relative Effective Context Length

### 1. Language Models Larger than GPT-3: Gopher

- Gopher [Rae et al., 2022]
  - New large text dataset, MassiveText, is introduced for pre-training
    - Number of tokens in datasets: 2350 B (Gopher) vs 333.7 B (MT-NLG)

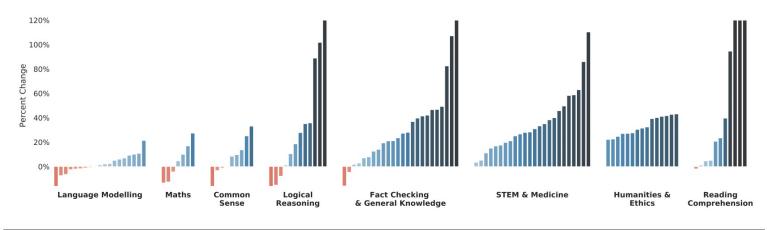
	Disk Size	Documents	Tokens	Sampling proportion
MassiveWeb	1.9 TB	604M	506B	48%
Books	2.1 TB	4M	560B	27%
C4	0.75 TB	361M	182B	10%
News	2.7 TB	1.1B	676B	10%
GitHub	3.1 TB	142M	422B	3%
Wikipedia	0.001 TB	6M	4B	2%

• Data distribution affect to performance → Gopher is much effective on Books-like tasks



#### 1. Language Models Larger than GPT-3: Gopher

- Gopher [Rae et al., 2022]
  - New large text dataset, MassiveText, is introduced for pre-training
  - Overall, **Gopher outperforms** the previous state-of-the-art language models
    - Performance improvement compared to the best among {GPT-3, Jurrasic-1, MT-NLG}
    - Gopher improves the performance across 100 / 124 tasks
  - It shows the importance of well curated large dataset along with large model



	417M	1.4B	7.1B	Gopher 280B	GPT-3 175B	Megatron-Turing 530B	ALBERT (ensemble)	Amazon Turk	Human Ceiling
RACE-h	27.2	26.0	30.6	71.6	46.8	47.9	90.5	69.4	94.2
RACE-m	26.2	25.0	31.8	75.1	58.1	n/a	93.6	85.1	95.4

Results on reading comprehension

Next, Different training method

 Although language modeling is an effective training scheme with unlabeled text data, there are remained limitations

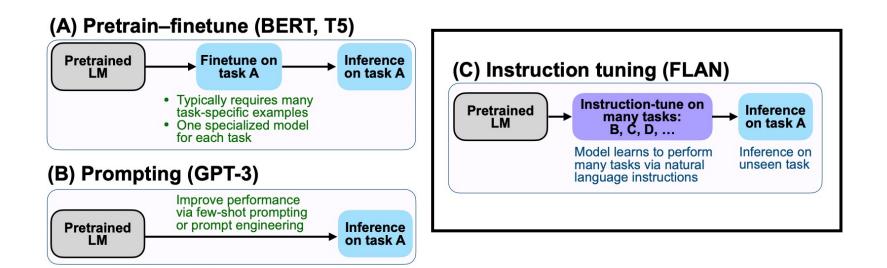
$$\arg\max_{\theta} \log p(\boldsymbol{x}) = \sum_{n} p_{\theta}(x_n | x_1, \dots, x_{n-1})$$

- Zero-shot performance is **much worsen** that Few-shot performance
  - For applying it to new task, one need to provide the example of such task
- Multi-task generalization via LM is indirectly obtained (suboptimality)

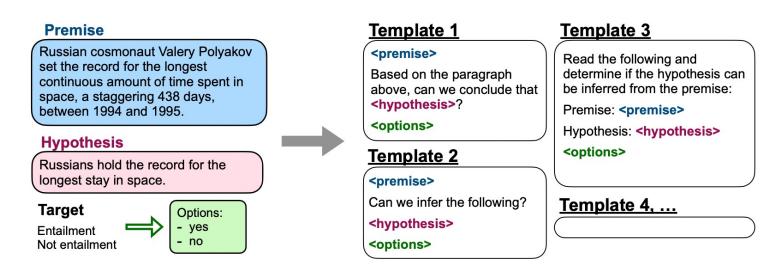
Setting	NaturalQS	WebQS	TriviaQA
RAG (Fine-tuned, Open-Domain) [LPP+20]	44.5	45.5	68.0
T5-11B+SSM (Fine-tuned, Closed-Book) [RRS20]	36.6	44.7	60.5
T5-11B (Fine-tuned, Closed-Book)	34.5	37.4	50.1
GPT-3 Zero-Shot	14.6	14.4	64.3
GPT-3 One-Shot	23.0	25.3	68.0
GPT-3 Few-Shot	29.9	41.5	71.2

Results on three open-domain QA tasks [Brown et al., 2020]

- FLAN [Wei et al., 2022]
  - Intuition: NLP tasks can be described via natural language instructions
    - E.g., "Is the sentiment of this movie review positive or negative?" (sentiment classification)
    - It offers a natural and intuitive way for adapting LM to the new tasks
  - Method: fine-tuning LMs (e.g., GPT-3) with instructions instead of prompts
    - Remark. Very similar approach is also proposed: T0 [Sanh et al., 2022] (promising)

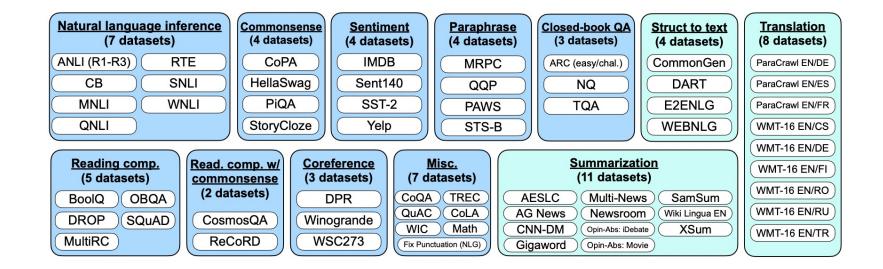


- FLAN [Wei et al., 2022]
  - Intuition: NLP tasks can be described via natural language instructions
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    - It offers a natural and intuitive way for adapting LM to the new tasks
  - Method: fine-tuning LMs (e.g., GPT-3) with instructions instead of prompts
    - To increase the diversity, **multiple instructions** are constructed for each task
    - Model output is given as text → each class is mapped to corresponding text

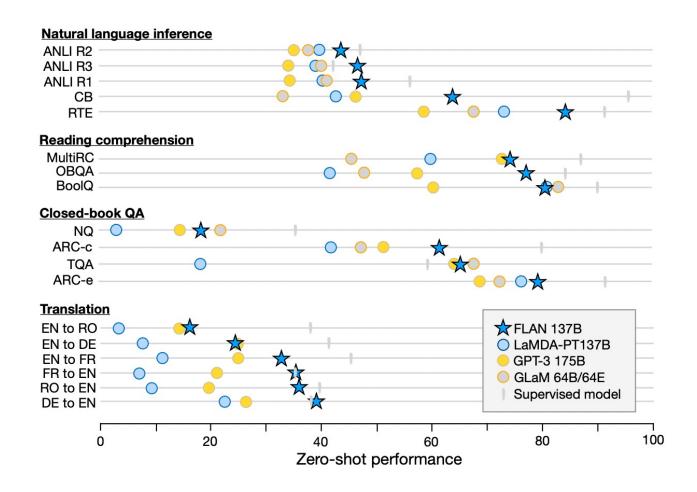


Different instructions (i.e., templates) for given example in NLI task

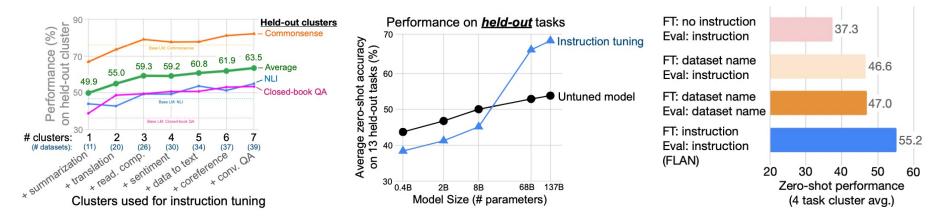
- FLAN [Wei et al., 2022]
  - Method: fine-tuning LMs (e.g., GPT-3) with instructions instead of prompts
  - For multi-task generalization, LM is trained with many tasks simultaneously
    - There might be an implicit learning with similar task
    - To truly measure unseen generalization, relevant tasks are removed when it's evaluated
    - E.g., measure zero-shot on ANLI (R1-R3) → remove other 6 NLI datasets for fine-tuning



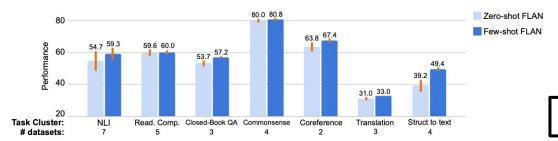
- **FLAN** [Wei et al., 2022]
  - FLAN significantly improves the zero-shot performance on many tasks



- FLAN [Wei et al., 2022]
  - FLAN significantly improves the zero-shot performance on many tasks
  - Followings are crucial components for improvement:
    - 1. Number of given instructions during instruction tuning
    - Number of model parameters
    - 3. Specific ways for giving instructions

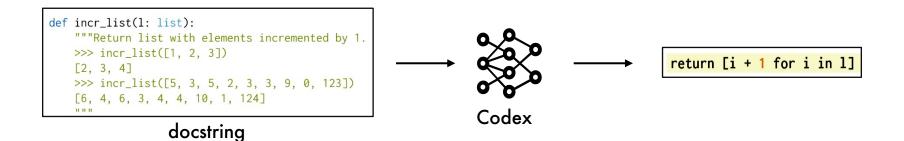


Also, FLAN is generalizable with few-shot examples



Next, applications

- Codex [Chen et al., 2021]
  - Codex is a GPT language model fine-tuned on publicly available codes from GitHub
    - It generates standalone Python functions from docstrings
  - 159 GB of unique Python files under 1 MB are used for training
  - Codex has a only-decoder structure like GPT-3 (fine-tuned on checkpoint of GPT-3)



- Codex [Chen et al., 2021]
  - Codex is evaluated on HumanEval dataset
    - It is consisted of 164 hand-written problems for measuring functional correctness
  - Codex with 12B parameters solved 28.8% of HumanEval problems
    - Repeated sampling from the model improve performance
    - E.g., 70.2% of HumanEval is solved with 100 samples per problem

#### E.g. 1) Find the decimal part of the number

```
def truncate_number(number: float) -> float:
    """ Given a positive floating point number,
    it can be decomposed into and integer part
        (largest integer smaller than given number)
        and decimals (leftover part always smaller than 1).
        Return the decimal part of the number.
    >>> truncate_number(3.5)
    0.5
    """
```

#### E.g. 2) Find only positive numbers in the list

```
def get_positive(l: list):
    """Return only positive numbers in the list.
    >>> get_positive([-1, 2, -4, 5, 6])
    [2, 5, 6]
    >>> get_positive([5, 3, -5, 2, -3, 3, 9, 0, 123, 1, -10])
    [5, 3, 2, 3, 9, 123, 1] """
```

- However, Codex still perform poorly when evaluated on more complex, unseen problems like competitive programming problems
  - Short problems are typically solved by translating a description directly into code
  - In contrast, the model need to **understand the task** and figure out how to accomplish it for solving complex problems

#### Backspace

You are given two strings s and t, both consisting of lowercase English letters. You are going to type the string s character by character, from the first character to the last one.

When typing a character, instead of pressing the button corresponding to it, you can press the "Backspace" button. It deletes the last character you have typed among those that aren't deleted yet (or does nothing if there are no characters in the current string). For example, if s is "abcbd" and you press Backspace instead of typing the first and the fourth characters, you will get the string "bd" (the first press of Backspace deletes no character, and the second press deletes the character 'c'). Another example, if s is "abcaa" and you press Backspace instead of the last two letters, then the resulting text is "a".

Your task is to determine whether you can obtain the string t, if you type the string *s* and press "Backspace" instead of typing several (maybe zero) characters of s.

The first line contains a single integer q ( $1 \le q \le 10^5$ ) the number of test cases. The first line of each test case contains the string s ( $1 \le |s| \le 10^5$ ). Each character of s is a lowercase English letter.

The second line of each test case contains the string t  $(1 \le |t| \le 10^5)$ . Each character of t is a lowercase English letter.

It is guaranteed that the total number of characters in the strings over all test cases does not exceed  $2 \cdot 10^5$ .

#### Output

For each test case, print "YES" if you can obtain the string t by typing the string s and replacing some characters with presses of "Backspace" button, or "NO" if

You may print each letter in any case (YES, yes, Yes will all be recognized as positive answer, NO, no and nO will all be recognized as negative answer).

#### **Example Input**

ababa ba ababa aaa aaaa aababa ababa

#### **Example Output**

YES NO NO YES

#### Explanation

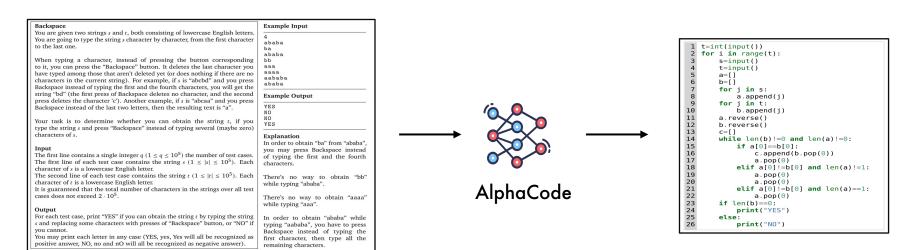
In order to obtain "ba" from "ababa". you may press Backspace instead of typing the first and the fourth characters.

There's no way to obtain "bb" while typing "ababa".

There's no way to obtain "aaaa" while typing "aaa".

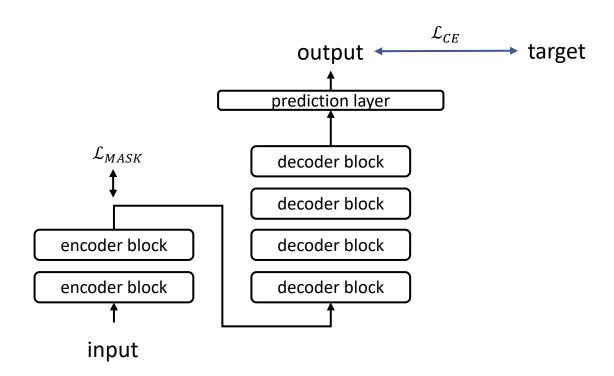
In order to obtain "ababa" while typing "aababa", you have to press Backspace instead of typing the first character, then type all the remaining characters.

- AlphaCode [Li et al., 2022] generates code solution for competitive programming problems that require deeper reasoning by
  - Pre-training with approximately 5x data
  - Encoder-decoder Transformer architecture
  - Fine-tuning with competitive programming problems with special techniques
  - Large sampling and filtering/clustering procedure

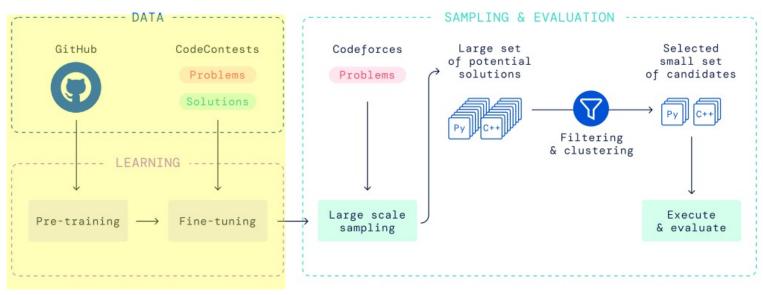


competitive programming problem

- AlphaCode [Li et al., 2022]
  - Unlike Codex (decoder only), AlphaCode has encoder-decoder Transformer architecture
  - It allows 1) a bidirectional description representation like BERT and 2) an extra flexibility to until the encoder structure from the decoder

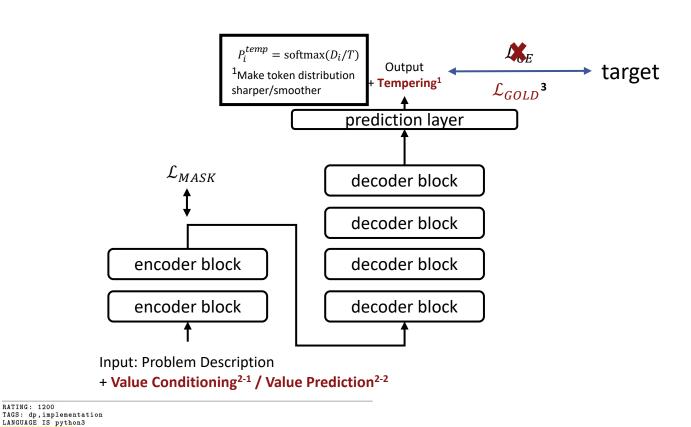


- AlphaCode [Li et al., 2022]
  - AlphaCode is pretrained with GitHub Dataset (715.1GB) with several languages (C++, Go, Java, Python, etc.)
  - Then, AlphaCode is fine-tuned and evaluated with a new competitive programming dataset, CodeContests
    - It includes problems, solutions and test cases we scraped from the Codeforces platform

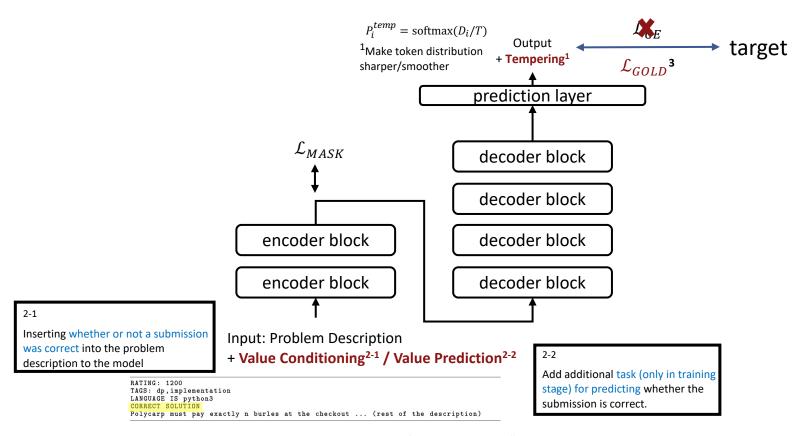


Polycarp must pay exactly n burles at the checkout ... (rest of the description)

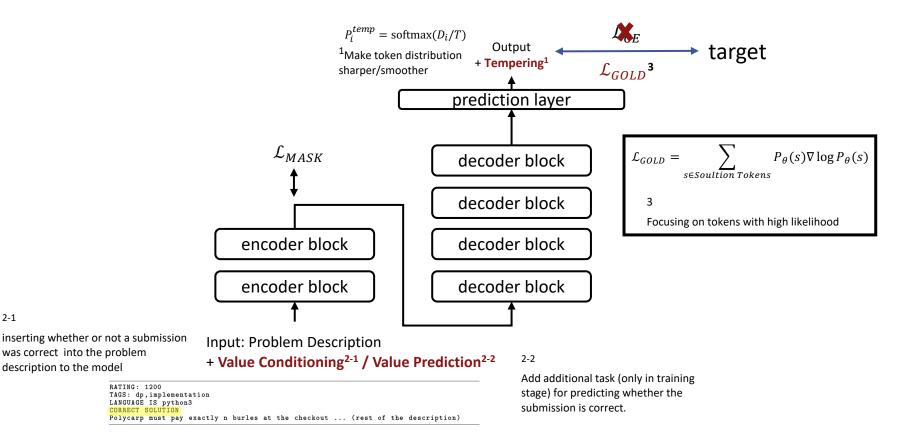
- AlphaCode [Li et al., 2022]
  - AlphaCode is fine-tuned on CodeContests dataset with some training details
    - **Tempering** (use constant T before the softmax for sharpening/smoothing)



- AlphaCode [Li et al., 2022]
  - AlphaCode is fine-tuned on CodeContests dataset with some training details
    - Tempering (use constant T before the softmax for sharpening/smoothing)
    - **Value Conditioning / Value Prediction** (based on metadata of the problem)



- AlphaCode [Li et al., 2022]
  - AlphaCode is fine-tuned on CodeContests dataset with **some training details** 
    - Tempering (use constant T before the softmax for sharpening/smoothing)
    - Value Conditioning / Value Prediction (based on metadata of the problem)
    - Use of **GOLD loss**, instead of cross-entropy. (weight token with high likelihood)



Algorithmic Intelligence Lab

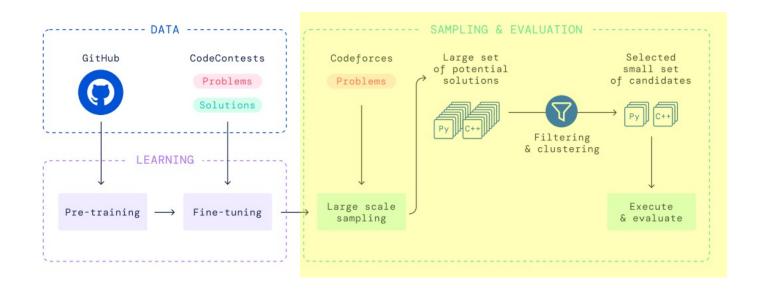
was correct into the problem

description to the model

2-1

## 3. New Application with Language Model: Code Generation – AlphaCode

- AlphaCode [Li et al., 2022]
  - Large scale sampling with various options
    - Generate half of the samples in Python and half in C++,
    - Randomize the problem tags and ratings
    - Use a relatively high sampling temperature
  - Efficient filtering & clustering by semantic equivalence
    - Each solution **must pass example tests** given in the problem statement
    - Codes are **clustered** according to the behavior against generated test input



# 3. New Application with Language Model: Code Generation – AlphaCode

- AlphaCode [Li et al., 2022]
  - AlphaCode achieved an average ranking of top 54.3% limiting to 10 submissions per problem in 10 Codeforces competitions (with > 5000 participants per contest)
    - With an actual average of 2.4 submissions for each problem solved

Contest ID	1591	1608	1613	1615	1617	1618	1619	1620	1622	1623	Average
Best	43.5%	43.6%	59.8%	60.5%	65.1%	32.2%	47.1%	54.0%	57.5%	20.6%	48.4%
Estimated	44.3%	46.3%	66.1%	62.4%	73.9%	52.2%	47.3%	63.3%	66.2%	20.9%	54.3%
Worst	74.5%	95.7%	75.0%	90.4%	82.3%	53.5%	88.1%	75.1%	81.6%	55.3%	77.2%

• With one hundred thousand samples, AlphaCode solve 31.8% of problems in validation set, and 29.6% of problems in test set for CodeContest evaluation

Annroach		Valida	tion Set	Test Set			
Approach	10@1k	10@10k	10@100k	10@1M	10@1k	10@10k	10@100k
9B	16.9%	22.6%	27.1%	30.1%	14.3%	21.5%	25.8%
41B	16.9%	23.9%	28.2%	31.8%	15.6%	23.2%	27.7%
41B + clustering	21.0%	26.2%	31.8%	34.2%	16.4%	25.4%	29.6%

- Mathematic problems can be also formulated as **text generation** [Hendrycks et al., 2021]
  - One can generate equations with texts by using LaTeX (graphics with other tool)
  - Template example: "(P) Final Answer: <Answer> \_\_\_", <P>: problem statement

# MATH Dataset (Ours)

Tom has a red marble, a green marble, **Problem:** a blue marble, and three identical yellow marbles. How many different groups of two marbles can Tom choose?

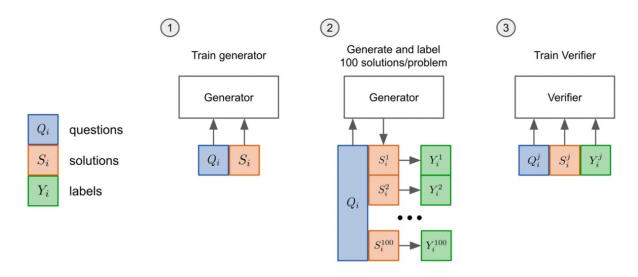
**Solution:** There are two cases here: either Tom chooses two yellow marbles (1 result), or he chooses two marbles of different colors  $\binom{4}{2} = 6$ results). The total number of distinct pairs of marbles Tom can choose is 1 + 6 = |7|.

Example data of MATH Dataset [Hendrycks et al., 2021]

- Mathematic problems can be also formulated as **text generation** [Hendrycks et al., 2021]
  - One can generate equations with texts by using LaTeX (graphics with other tool)
  - Template example: "(P) Final Answer: <Answer> \_\_\_", <P>: problem statement
- But, even largest models falter to perform multi-step mathematical reasoning
  - Here, GPT-2 is fine-tuned with relevant mathematical dataset
  - One significant challenge is the high sensitivity to individual mistakes [Shen et al., 2021]
    - Autoregressive models have no mechanism to correct intermediate errors.

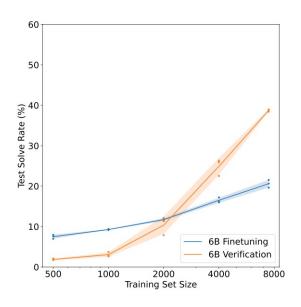
Model	Prealgebra	a Algebra	Number	Counting &	Geometry	Intermediate	Precalculus	Average
			Theory	Probability		Algebra		
GPT-2 0.1B	5.2	5.1	5.0	2.8	5.7	6.5	7.3	5.4 +0%
GPT-2 0.3B	6.7	6.6	5.5	3.8	6.9	6.0	7.1	6.2 + 15%
GPT-2 0.7B	6.9	6.1	5.5	5.1	8.2	5.8	7.7	6.4 + 19%
GPT-2 1.5B	8.3	6.2	4.8	5.4	8.7	6.1	8.8	6.9 + 28%
GPT-3 13B*	4.1	2.4	3.3	4.5	1.0	3.2	2.0	3.0 - 44%
GPT-3 13B	6.8	5.3	5.5	4.1	7.1	4.7	5.8	5.6 + 4%
GPT-3 175B*	7.7	6.0	4.4	4.7	3.1	4.4	4.0	5.2 - 4%

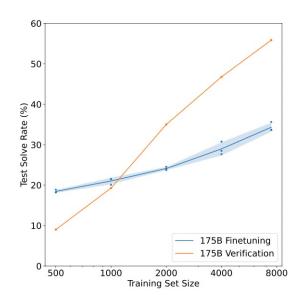
- Training verifiers to evaluate a correctness of generated solutions [Cobbe et al., 2021]
  - **Generator** is trained via previous language modeling
  - **Verifier** is trained to find answer among multiple candidates
    - Somewhat similar scheme with GAN [Goodfellow et al., 2014]
  - At test time, a fixed number of candidate solutions are sampled
    - Then, select the solution ranked highest by the verifier



Overall training pipeline

- Training verifiers to evaluate a correctness of generated solutions [Cobbe et al., 2021]
  - At test time, a fixed number of candidate solutions are sampled
    - Then, select the solution ranked highest by the verifier
- Results on Grade School Math datasets (**GSM8K**)
  - Both generator and verifier are initialized with GPT-3 family
  - 6B verification model even **outperforms** 175B fine-tuning model





## **Summary**

- For temporal data, one need a specific architecture which can capture temporal dependency within data
- RNN architectures have developed in a way that
  - Can better model long-term dependency & Robust to vanishing gradient problems
  - Seq2seq model with attention makes breakthroughs in machine translation
  - It leads to the model only composed with attention → Transformer
- Transformer significantly improves the performance on many sequential tasks
  - With pre-training using large model and data, one can get 1) standard initialization point for many NLP task (BERT) and 2) strong language generator (GPT)
- Large-scale Transformer-based language models is now a de-facto standard
  - More training data with more model parameters → Better performance
  - It enables us to use language models for many applications

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