Confident Multiple Choice Learning

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Korea Advanced Institute of Science and Technology (KAIST)

ICML 2017, Sydney

KAIST Algorithmic Intelligence Lab

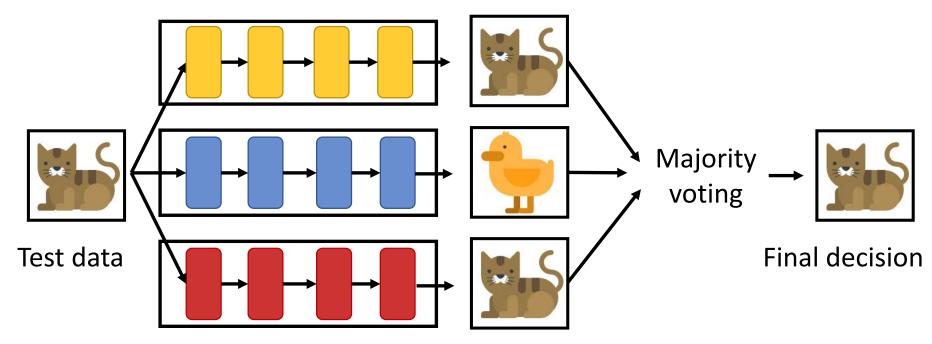
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Outline

- Summary
 - Motivation
 - Main contribution
- Confident multiple choice learning (CMCL)
 - Preliminaries
 - Confident oracle loss
 - Feature sharing
 - Random labeling
- Experimental results
 - Image classification
 - Foreground-background segmentation

What is Ensemble Learning ?

- Train multiple models to try and solve the same problem
- Combine the outputs of them to obtain the final decision



 Bagging [Breiman' 96], boosting [Freund' 99] and mixture of experts [Jacobs' 91]

[Freund' 99] Freund, Yoav, Schapire, Robert, and Abe, N. A short introduction to boosting. Journal-Japanese Society For Arti- ficial Intelligence, 14(771-780):1612, 1999. [Breiman' 96] Breiman, Leo. Bagging predictors. Machine learning, 24 (2):123–140, 1996. [Jacobs' 91] Jacobs, Robert A, Jordan, Michael I, Nowlan, Steven J, and Hinton, Geoffrey E. Adaptive mixtures of local experts. Neural computation, 1991.

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Successes of Ensemble Methods

 Ensemble methods have been successfully applied to enhancing performance in many machine learning applications

ImageNet 2017 – Object Detection

Rank	Team name	Entry description	Mean AP	# of categories won		
1	BDAT	Submission4	0.732227	65		
2	NUS-Qihoo_DPNs (DET)	Ensemble of DPN models	0.656932	9		
3	KAISTNIA_ETRI	Ensemble Model 5	0.61022	1		

* Table is from http://image-net.org/challenges/LSVRC/2017/results

WMT 2016 competition results

Rank	System	Submitter BLEU		System Notes
1	Uedin-nmt- <mark>ensemble</mark>	University of Edinburgh	34.8	~. Ensemble of 4, reranked with right-to-~
2	Metamind-ensemble	Salesforce metamind	32.8	~. Ensemble of 3 checkpoints ~
3	Uedin-nmt-single	University of Edinburgh	32.2	~. Single model

* Table is from http://cs224d.stanford.edu/lectures/CS224d-Lecture9.pdf

High-performance teams employ ensemble methods !

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Main Contribution

Problem

- Simple ensemble methods have been of typical choice for most applications involving deep neural networks
 - Relatively slow progress on developing more advanced ensembles specialized for deep neural networks

Main contributions

- We propose a new ensemble method specialized for deep neural networks based on advanced collaboration of ensemble members
- For Image classification,
 - Our method using residual networks provides 14.05% and 6.60% relative reductions in their errors from standard ensemble method on CIFAR and SVHN datasets, respectively
- For foreground-background segmentation,
 - Our method using fully convolutional networks achieve up to 6.77% relative reduction in their errors from standard ensemble method on iCoseg dataset

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- Independent Ensemble (IE) [Ciregan' 12]
 - Independently train each model with random initialization

$$L_E(\mathcal{D}) = \sum_{i=1}^{N} \sum_{m \in [M]} \ell(y_i, f_m(\mathbf{x}_i)).$$

$$Var \qquad Definition \\ \mathcal{D} = \{(\mathbf{x}_i, y_i)\} & \text{training data} \\ (f_1, \dots, f_M) & M \text{ models} \\ \ell(y_i, f(\mathbf{x})) & \text{task-specific loss} \end{cases}$$

- IE generally improves the performance by reducing the variance
- However, IE does not produce diverse solution well

[Ciregan' 12] Ciregan, D., Meier, U. and Schmidhuber, J. Multi-column deep neural networks for image classification. In CVPR, 2012.

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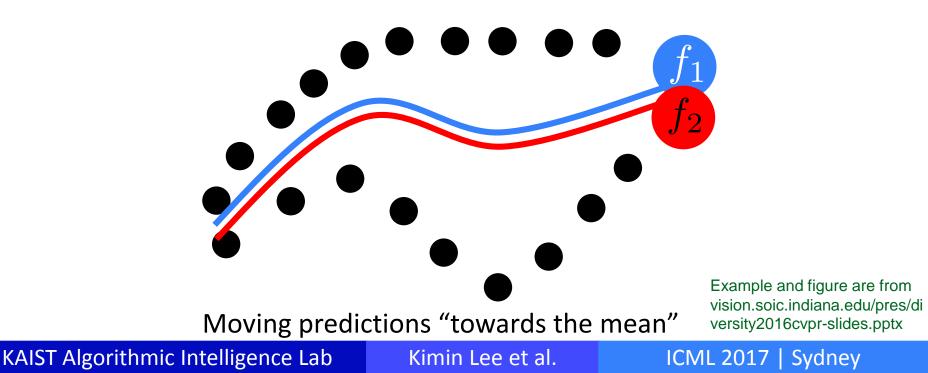


- Independent Ensemble (IE) [Ciregan' 12]
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\end{cases}$$

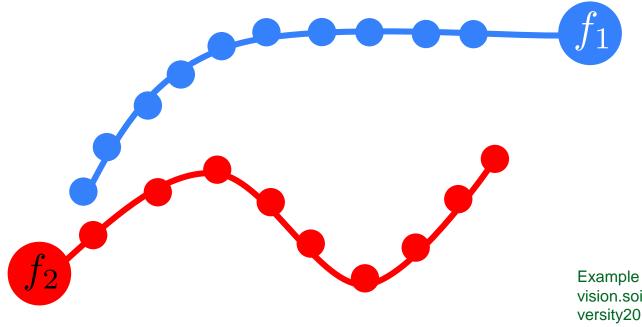
• Toy example: regression using 2 models with mean squared error



- Multiple choice learning (MCL) [Guzman' 12]
 - Making each model specialized for certain subset of data

$$L_{O}\left(\mathcal{D}\right) = \sum_{i=1}^{N} \min_{m \in [M]} \ell\left(y_{i}, f_{m}\left(\mathbf{x}_{i}\right)\right),$$

• Toy example: regression using 2 models with mean squared error



Example and figure are from vision.soic.indiana.edu/pres/di versity2016cvpr-slides.pptx

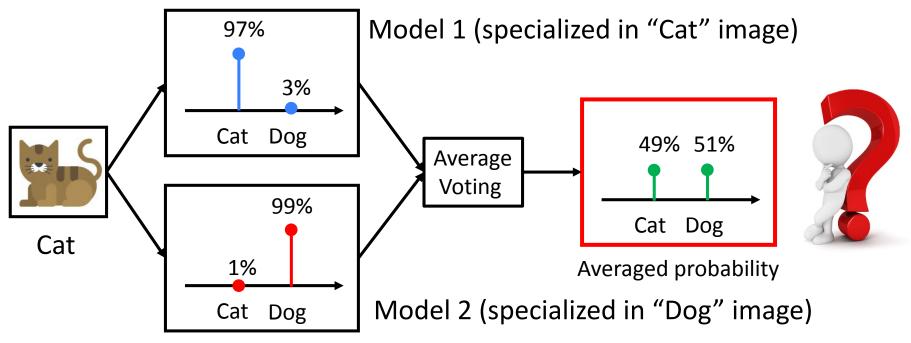
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- Multiple choice learning (MCL) [Guzman' 12]
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$$L_{O}\left(\mathcal{D}\right) = \sum_{i=1}^{N} \min_{m \in [M]} \ell\left(y_{i}, f_{m}\left(\mathbf{x}_{i}\right)\right),$$

Overconfidence issues of MCL



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Confident Multiple Choice Learning (CMCL)

- Making the specialized models with confident predictions
- Main components of our contributions

New loss: confident oracle loss

New architecture: feature sharing

New training method: random labeling

Experiments on CIFAR-10 using 5 CNNs (2 Conv + 2 FC)

Ensemble	Feature	Stochastic	Top-1
Method	Sharing	Labeling	Error Rate
IE	-	-	15.34%
MCL	-	-	60.40%
	-	-	15.65%
CMCL	\checkmark	-	14.83%
	\checkmark	\checkmark	14.78%

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Confident oracle loss

$$L_{C}(\mathcal{D}) = \min_{v_{i}^{m}} \sum_{i=1}^{N} \sum_{m=1}^{M} \left(v_{i}^{m} \ell\left(y_{i}, P_{\theta_{m}}\left(y_{i} \mid \mathbf{x}_{i}\right)\right) + \beta\left(1 - v_{i}^{m}\right) D_{KL}\left(\mathcal{U}\left(y\right) \parallel P_{\theta_{m}}\left(y \mid \mathbf{x}_{i}\right)\right) \right)$$

$$(1a)$$

$$u_{i}^{m} \in \{0, 1\}, \quad \forall i, m$$

$$(1b)$$

$$(1c)$$

• Generating confident predictions by minimizing the KL divergence

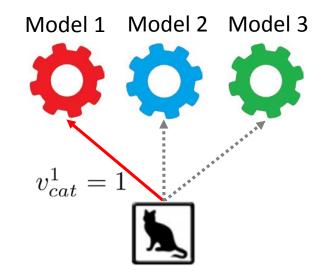
 D_{KL} : the KullbackLeibler (KL) divergence $\mathcal{U}(y)$: the uniform distribution v_i^m : a flag variable to decide the assignment of \mathbf{x}_i to the *m*-th model β : a penalty parameter θ_m : model parameters $P_{\theta_m}(y \mid \mathbf{x})$: Predictive distribution of *m*-th model

• Confident oracle loss

$$L_{C}(\mathcal{D}) = \min_{v_{i}^{m}} \sum_{i=1}^{N} \sum_{m=1}^{M} \left(v_{i}^{m} \ell\left(y_{i}, P_{\theta_{m}}\left(y_{i} \mid \mathbf{x}_{i}\right)\right) + \beta\left(1 - v_{i}^{m}\right) D_{KL}\left(\mathcal{U}\left(y\right) \parallel P_{\theta_{m}}\left(y \mid \mathbf{x}_{i}\right)\right) \right)$$
(1a)
subject to
$$\sum_{m=1}^{M} v_{i}^{m} = 1, \quad \forall i, \qquad (1b)$$
$$v_{i}^{m} \in \{0, 1\}, \quad \forall i, m \qquad (1c)$$

• Interpretation

$$P_{\theta}(y|\mathbf{x}) \to P(y|\mathbf{x})$$
Data distribution
$$f = y$$
[Target data $(v_i = 1)$]



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• Confident oracle loss

$$L_{C}(\mathcal{D}) = \min_{v_{i}^{m}} \sum_{i=1}^{N} \sum_{m=1}^{M} \left(v_{i}^{m} \ell\left(y_{i}, P_{\theta_{m}}\left(y_{i} \mid \mathbf{x}_{i}\right)\right) + \beta\left(1 - v_{i}^{m}\right) D_{KL}\left(\mathcal{U}\left(y\right) \parallel P_{\theta_{m}}\left(y \mid \mathbf{x}_{i}\right)\right) \right)$$
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$$v_{i}^{m} \in \{0, 1\}, \quad \forall i, m \qquad (1c)$$

• Interpretation

$$P_{\theta}(y|\mathbf{x}) \rightarrow P(y|\mathbf{x}) \qquad P_{\theta}(y|\mathbf{x}) \rightarrow \mathcal{U}(y)$$
Data distribution
$$P_{\theta}(y|\mathbf{x}) \rightarrow \mathcal{U}(y)$$
Uniform distribution
$$v_{cat}^{1} = 1$$

$$v_{cat}^{2} = 0$$

$$v_{cat}^{2} = 0$$

$$v_{cat}^{3} = 0$$

Model 1 Model 2 Model 3

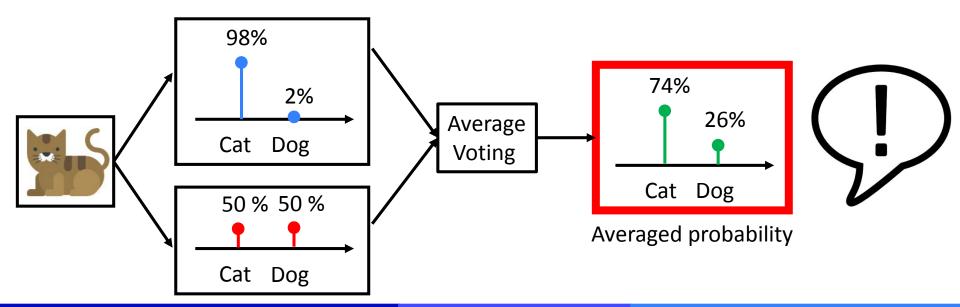
• Confident oracle loss

$$L_{C}(\mathcal{D}) = \min_{v_{i}^{m}} \sum_{i=1}^{N} \sum_{m=1}^{M} \left(v_{i}^{m} \ell\left(y_{i}, P_{\theta_{m}}\left(y_{i} \mid \mathbf{x}_{i}\right)\right) + \beta\left(1 - v_{i}^{m}\right) D_{KL}\left(\mathcal{U}\left(y\right) \parallel P_{\theta_{m}}\left(y \mid \mathbf{x}_{i}\right)\right) \right)$$

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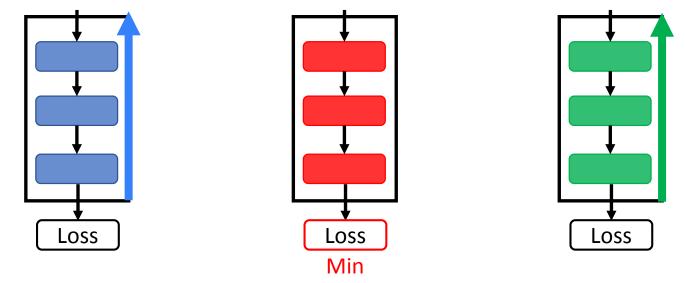


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Algorithm Description

- Stochastic alternating procedure based on [Lee' 16]
 - Assumption: models are trained by stochastic gradient
 - For each batch
 - Compute the confident oracle loss of each model
 - Most accurate model trains the task-specific loss
 - Other models minimize the KL divergence loss
 - Repeat until convergence



[Lee' 16] Lee, S., Prakash, S.P.S., Cogswell, M., Ranjan, V., Crandall, D. and Batra, D. Stochastic multiple choice learning for training diverse deep ensembles. In NIPS, 2016.

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• Experiments on CIFAR-10 using 5 CNNs (2 Conv + 2 FC)

Class-wise test set accuracy

_																	
Airplane	0.0 %	0.0 %	93.6 %	0.0 %	0.0 %		95.8%		4.4%	12.2%	2.2%		86.6%	85.5%	86.4%	85.7%	86.0%
Automobile	0.0 %	0.0 %	96.1 %	0.0 %	0.0 %		0.0%	0.0%	0.8%	98.6%	9.0%		90.7%	90.3%	90.5%	90.6%	90.5%
s and the second se	99.9 %	0.0 %	0.0 %	0.0 %	0.0 %		0.1%	0.3%	2.4%	4.1%	94.0%		75.4%	75.9%	74.5%	76.3%	76.5%
Cat	0.0 %	0.0 %	95.6 %	0.0 %	0.0 %		94.5%		0.0%	0.0%	0.2%		68.5%	66.5%	66.1%	67.1%	67.1%
Deer	0.0 %	0.0 %	0.0 %	97.5 %	0.0 %		0.0%	23.6%	1.2%	98.7%	4.5%		85.8%	86.3%	86.1%	86.1%	86.2%
Dog	0.0 %	97.0 %	0.0 %	0.0 %	0.0 %		15.8%	8.0%	2.9%	4.7%	91.7%		76.3%	75.6%	77.5%	75.0%	76.5%
Frog	0.0 %	0.0 %	0.0 %	0.0 %	97.7 %		7.1%	0.9%	99.2%	2.7%	0.0%		90.1%	90.7%	90.3%	91.4%	90.6%
Horse	0.0 %	0.0 %	0.0 %	0.0 %	97.2 %		0.0%	0.0%	98.1%	0.0%	0.0%		87.3%	86.9%	86.6%	86.3%	87.2%
Ship	0.0 %	0.0 %	0.0 %	97.2 %	0.0 %		0.0%	97.3%	0.0%	0.0%	0.0%		91.6%	91.6%	91.4%	91.7%	90.7%
Truck	0.0 %	97.4 %	0.0 %	0.0 %	0.0 %		0.5%	96.1%	0.0%	0.0%	28.0%		90.4%	89.3%	89.8%	90.0%	90.0%
_	1	2	3	4	5		1	2	3	4	5		1	2	3	4	5
(a)	(a) Multiple choice learning (MCL)						(b) Confident MCL (CMCL)						(c) Independent ensemble (IE)				

Both MCL and CMCL make each model specialized for certain classes, while IE does not

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• Experiments on CIFAR-10 using 5 CNNs (2 Conv + 2 FC)

• Class-wise test set accuracy

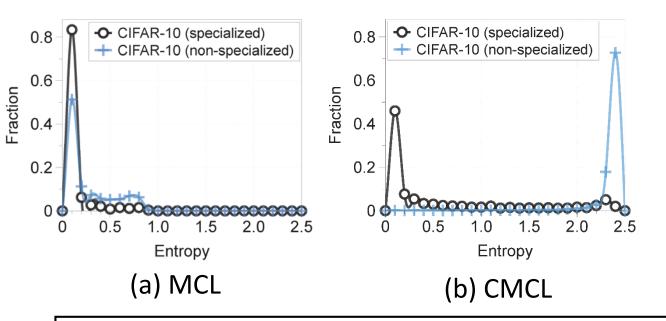
Airplane	0.0 %	0.0 %	93.6 %	0.0 %	0.0 %	95.8%	0.0%	4.4%	12.2%	2.2%		86.6%	85.5%	86.4%	85.7%	86.0%
Automobile	0.0 %	0.0 %	96.1 %	0.0 %	0.0 %	0.0%	0.0%	0.8%	98.6%	9.0%		90.7%	90.3%	90.5%	90.6%	90.5%
Bird	99.9 %	0.0 %	0.0 %	0.0 %	0.0 %	0.1%	0.3%	2.4%	4.1%	94.0%		75.4%	75.9%	74.5%	76.3%	76.5%
Cat	0.0 %	0.0 %	95.6 %	0.0 %	0.0 %	94.5%	2.6%	0.0%	0.0%	0.2%		68.5%	66.5%	66.1%	67.1%	67.1%
Deer	0.0 %	0.0 %	0.0%	97.5 %	0.0 %	0.0%	23.6%	1.2%	98.7%	4.5%		85.8%	86.3%	86.1%	86.1%	86.2%
Dog	0.0 %	97.0 %	06	0.0 %	0.0 %	15 6	8.0%	2.9%	4.7%	91.7%		76.3%	75.6%	77.5%	75.0%	76.5%
Frog	0.0 %	0.0 %	0 <mark></mark> 6	0.0 %	97.7 %	7.170	0.9%	99.2%	2.7%	0.0%		90.1%	90.7%	90.3%	91.4%	90.6%
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Ship	0.0 %	0.0 %	0.0 %	97.2 %	0.0 %	0.0%	97.3%	0.0%	0.0%	0.0%		91.6%	91.6%	91.4%	91.7%	90.7%
Truck	0.0 %	97.4 %	0.0 %	0.0 %	0.0 %	0.5%	96.1%	0.0%	0.0%	28.0%		90.4%	89.3%	89.8%	90.0%	90.0%
	1	2	3	4	5	1	2	3	4	5		1	2	3	4	5
(a)	(a) Multiple choice learning (MCL)					(b) Confident MCL (CMCL)						(c) Independent ensemble (IE)				

Both MCL and CMCL make each model specialized for certain classes, while IE does not

➡ For specialized data, model trained by CMCL and MCL outperforms model trained by IE

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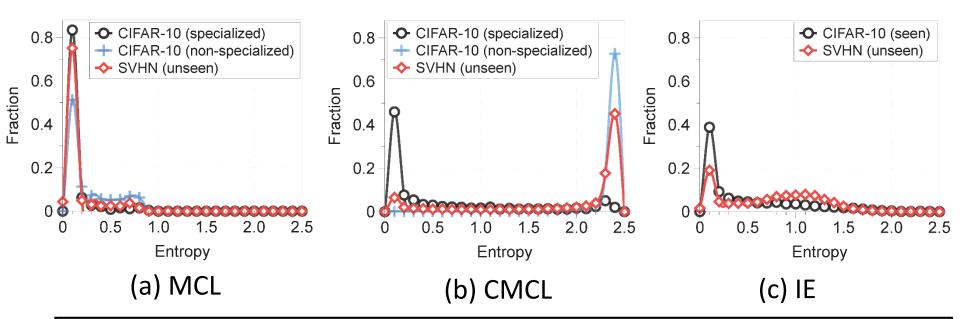
- Experiments on CIFAR-10 using 5 CNNs (2 Conv + 2 FC)
 - Histogram of the predictive entropy of model trained by each method



For non-specialized data (i.e., accuracy < 80%), ensemble members of CMCL are not overconfident compared to MCL

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- Experiments on CIFAR-10 using 5 CNNs (2 Conv + 2 FC)
 - Histogram of the predictive entropy of model trained by each method



 For non-specialized data (i.e., accuracy < 80%), ensemble members of CMCL are not overconfident compared to MCL
 For unseen dataset (SVHN), ensemble members of CMCL are not overconfident while models trained by MCL and IE are overconfident

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Regularization Techniques for CMCL

Feature sharing

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- Motivation: extracting general features from data
- Stochastically shares the features from ensemble members

$$\mathbf{h}_{m}^{\ell}(\mathbf{x}) = \phi \left(\mathbf{W}_{m}^{\ell} \left(\mathbf{h}_{m}^{\ell-1}(\mathbf{x}) + \sum_{n \neq m} \sigma_{nm}^{\ell} \star \mathbf{h}_{n}^{\ell-1}(\mathbf{x}) \right) \right)$$
Hidden Masked Shared Feature
Feature A Feature B₁ A + B_1 + B

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Regularization Techniques for CMCL

- Random labeling
 - Motivation: efficiency in computation and regularization effect
 - By definition,

 $\nabla_{\theta} D_{KL} \left(\mathcal{U} \left(y \right) \parallel P_{\theta} \left(y \mid \mathbf{x} \right) \right) = -\mathbb{E}_{\mathcal{U}(y)} [\nabla_{\theta} \log P_{\theta} \left(y \mid \mathbf{x} \right)].$

• Noisy unbiased estimator with Monte Carlo samples

$$\bigtriangledown_{\theta} D_{KL} \left(\mathcal{U} \left(y \right) \parallel P_{\theta} \left(y \mid \mathbf{x} \right) \right) \simeq -\frac{1}{S} \sum_{s} \bigtriangledown_{\theta} \log P_{\theta} \left(y^{s} \mid \mathbf{x} \right), \ y^{s} \sim \mathcal{U} \left(y \right)$$

Exact gradient Gradient of cross entropy

• Training using random labels ! (S = 1)

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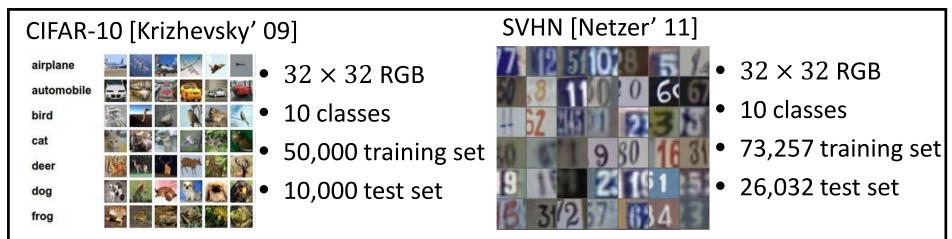
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Experimental Results: Image Classification

Classification test set error rates on CIFAR-10 and SVHN



- Top-1 error
 - Select the class from averaged probability
- Oracle error
 - Measuring whether none of the members predict the correct class
- We use both feature sharing and random labeling for all experiments

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Experimental Results: Image Classification

• Ensemble of small-scale CNNs (2 Conv + 2 FC)

Ensemble Method	K	Ensemble	Size $M = 5$	Ensemble Size $M = 10$			
Ensemble Method	Λ	Oracle Error Rate	Top-1 Error Rate	Oracle Error Rate	Top-1 Error Rate		
IE	-	10.65%	15.34%	9.26%	15.34%		
	1	4.40%	60.40%	0.00%	76.88%		
MCL	2	3.75%	20.66%	1.46%	49.31%		
MCL	3	4.73%	16.24%	1.52%	22.63%		
	4	5.83%	15.65%	1.82%	17.61%		
	1	3.32%	14.78%	1.96%	14.28%		
CMCI	2	3.69%	14.25% (-7.11%)	1.22%	13.95%		
CMCL	3	4.38%	14.38%	1.53%	14.00%		
	4	5.82%	14.49%	1.73%	13.94% (-9.13%)		

• Ensemble of 5 large-scale CNNs

Model Name	Ensemble	CIFAI	R-10	SVHN					
woder Name	Method	Oracle Error Rate	Top-1 Error Rate	Oracle Error Rate	Top-1 Error Rate				
	- (single)	10.65%	10.65%	5.22%	5.22%				
VGGNet-17	IE	3.27%	8.21%	1.99%	4.10%				
voonet-17	MCL	2.52%	45.58%	1.45%	45.30%				
	CMCL	2.95%	7.83% (-4.63%)	1.65%	3.92% (- 4.39%)				
	- (single)	10.15%	10.15%	4.59%	4.59%				
CooplaNat 19	IE	3.37%	7.97%	1.78%	3.60%				
GoogLeNet-18	MCL	2.41%	52.03%	1.39%	37.92%				
	CMCL	2.78%	7.51% (-5.77%)	1.36%	3.44% (-4.44%)				
	- (single)	14.03%	14.03%	5.31%	5.31%				
ResNet-20	IE	3.83%	10.18%	1.82%	3.94%				
Residet-20	MCL	2.47%	53.37%	1.29%	40.91%				
	CMCL	2.79%	8.75% (-14.05%)	1.42 %	3.68% (-6.60%)				

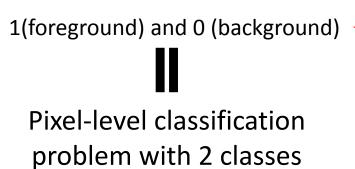
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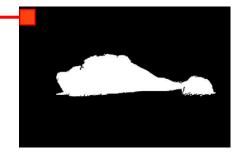
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Experimental Results: Image Segmentation

• iCoseg dataset

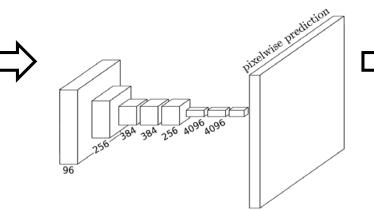












Fully convolutional neural networks (FCNs) [Long' 15]





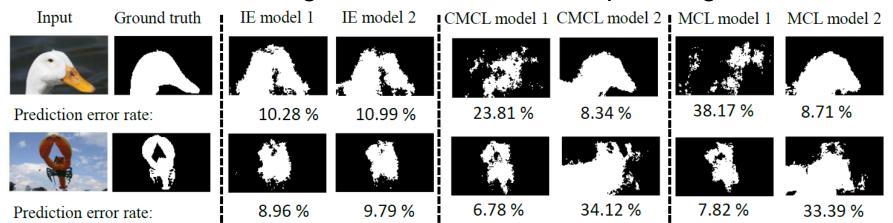
[Long' 15] Long, J., Shelhamer, E. and Darrell, T. Fully convolutional networks for semantic segmentation. In CVPR, 2015.

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Experimental Results: Image Segmentation

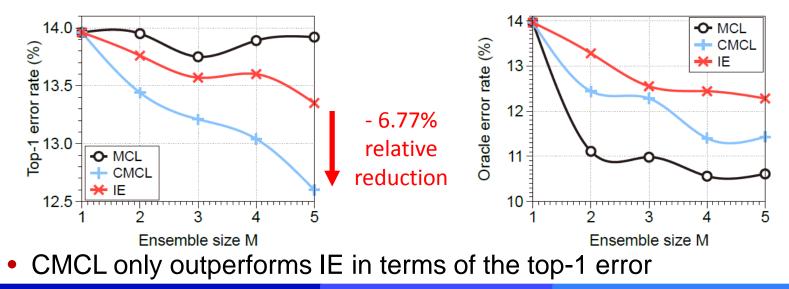
• Prediction results of segmentation for few sample images



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• MCL and CMCL generate high-quality predictions



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Conclusion

- We propose a new ensemble method coined CMCL
 - It produces diverse/plausible confident prediction of high quality !
- CMCL outperforms not only the known MCL, but also the traditional independent ensembles in classification and segmentation tasks.
- We believe that our new ensemble approach brings a refreshing angle for developing advanced large-scale deep networks in many related applications

Thank you !

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