

# Network Compression

AI602: Recent Advances in Deep Learning  
Lecture 14

Slide made by

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KAIST EE

## Presentation Schedule

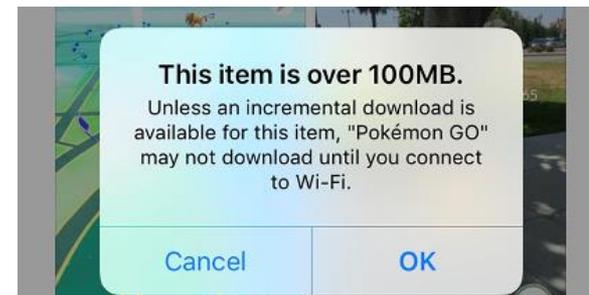
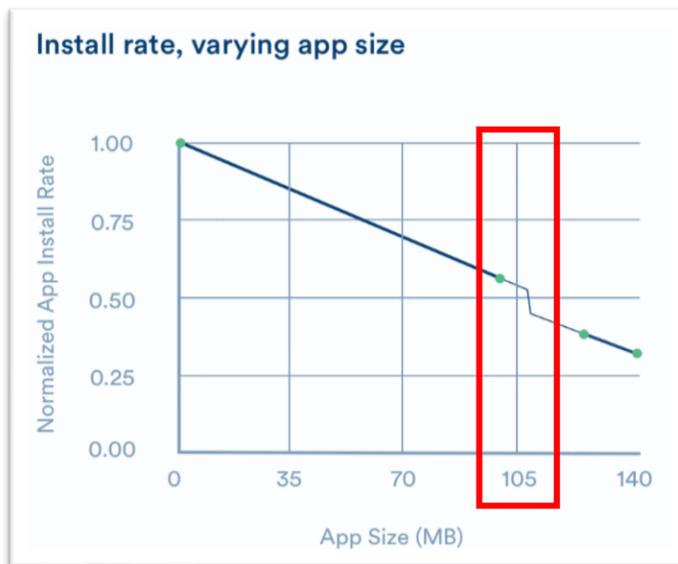
	11/21	11/26	12/10	12/12
1	정성희	David Albert	김도연	이동헌
2	김두연	Divyam Madaan	함동훈	이홍희
3	탁지훈	김경만	김재형	신재웅
4	박주혜	조인영	김종협	최중원
5	홍석찬	김규석	박관용	한문수
6	김성환	박석준	조명식	김명준
7	차현탁	이선경	서석인	도승헌
8	Thomas Thanh Minh DEFARD	Xuan Thanh Nguyen	이세웅	이수열
9	Tooba Imtiaz	신유주		
10		XUAN TRUNG PHAM		

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## Deploying Deep Neural Networks in Real-World

- **Deploying deep neural networks (DNNs)** has been increasingly difficult
  - Constraints on power consumption, memory usage, inference overhead, ...
- Inference with a large-scale network consumes huge costs
- In mobile apps, such issues become more serious
  - **“The dreaded 100MB effect”**
- Can we make DNNs to **perform inferences more efficiently?**



### **1. Network Pruning and Re-wiring**

- Optimal brain damage
- Pruning modern DNNs
- Dense-Sparse-Dense training flow

### **2. Sparse Network Learning**

- Structured sparsity learning
- Sparsification via variational dropout
- Variational information bottleneck

### **3. Weight Quantization**

- Deep compression
- Binarized neural networks

### **4. Summary**

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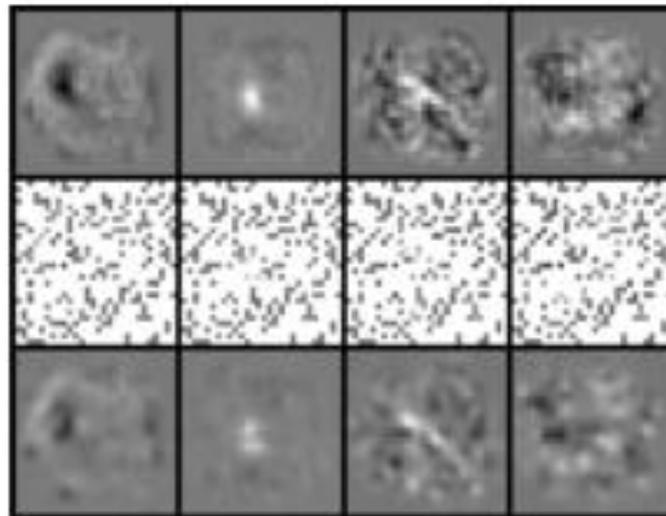
### 4. Summary

- DNNs include a significant number of **redundant parameters**
- Denil et al. (2013): Predicting **> 95% of weights from < 5%**
  - A simple kernel ridge regression is sufficient
  - ... without any drop in accuracy!
  - Many of the weights **need not be learned at all**

(a) Original weights

(b) Randomly selected

(c) Predicted from (b)

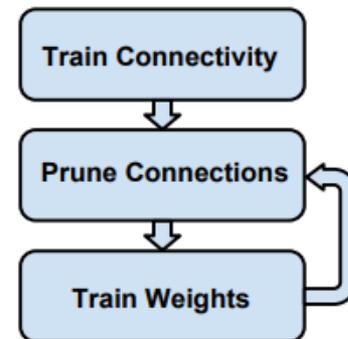


- Such redundancy can be exploited via **network pruning**

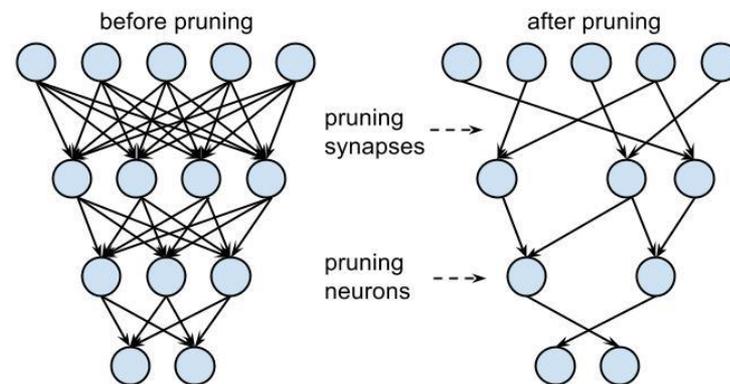
## Network Pruning

- Determining **low-saliency parameters**, given a pre-trained network
- Follows the framework proposed by LeCun et al. (1990):

1. **Train** a deep model until convergence
2. **Delete** “unimportant” connections w.r.t. a certain criteria
3. **Re-train** the network
4. **Iterate** to step 2, or stop

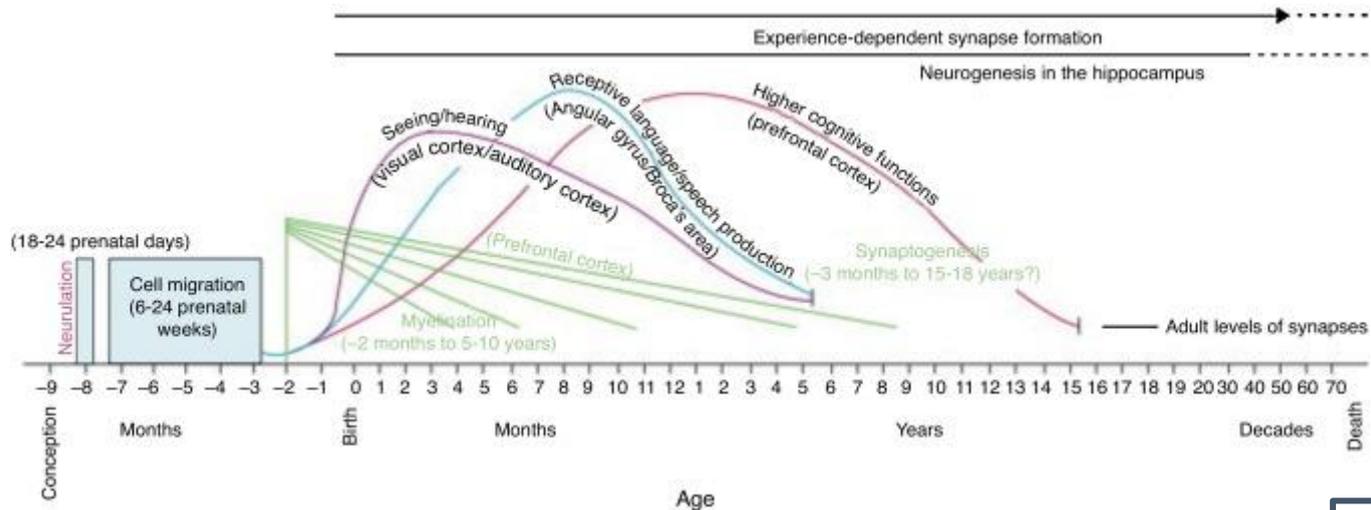


- Defining **which connection is unimportant** can vary
  - Weight magnitudes ( $L^2$ ,  $L^1$ , ...)
  - Mean activation [Molchanov et al., 2016]
  - Avg. % of Zeros (APoZ) [Hu et al., 2016]
  - Low entropy activation [Luo et al., 2017]
  - ...



# Synaptic Pruning in Human Brain

- Human brains are also using pruning schemes as well
- **Synaptic pruning** removes redundant synapses in the brain during lifetime



Next: OBD

\*source: Leisman et al., "The neurological development of the child with the educational enrichment in mind.", *Psicología Educativa* 2015

- Network pruning **perturbs weights  $\mathbf{W}$**  by **zeroing** some of them
- How the **loss  $L$**  would be changed when  $\mathbf{W}$  is perturbed?
- **OBD** approximates  $L$  by the **2<sup>nd</sup> order Taylor series**:

$$\delta L \simeq \underbrace{\sum_i \frac{\partial L}{\partial w_i} \delta w_i}_{\text{1st order}} + \underbrace{\frac{1}{2} \sum_i \frac{\partial^2 L}{\partial w_i^2} \delta w_i^2 + \frac{1}{2} \sum_{i,j} \frac{\partial^2 L}{\partial w_i \partial w_j} \delta w_i \delta w_j}_{\text{2nd order}} + O(\|\delta \mathbf{W}\|^3)$$

- **Problem:** Computing  $H = \left( \frac{\partial L}{\partial w_i \partial w_j} \right)_{i,j}$  is usually intractable
  - Requires  $O(n^2)$  on **# weights**
  - Neural networks usually have enormous number of weights
    - e.g. AlexNet: **60M** parameters  $\Rightarrow H$  consists  $\approx 3.6 \times 10^{15}$  elements

- **Problem:** Computing  $H = \left( \frac{\partial L}{\partial w_i \partial w_j} \right)_{i,j}$  is usually intractable

- Two additional assumptions for tractability

1. **Diagonal** approximation:  $H = \frac{\partial^2 L}{\partial w_i \partial w_j} = 0$  if  $i \neq j$

2. **Extremal** assumption:  $\frac{\partial L}{\partial w_i} = 0 \quad \forall i$

- **W** would be in a **local minima** if it's pre-trained

- Now we get:  $\delta L \simeq \frac{1}{2} \sum_i \frac{\partial^2 L}{\partial w_i^2} \delta w_i^2 + O(\|\delta \mathbf{W}\|^3)$

- It only needs  $\text{diag}(H) := \left( \frac{\partial^2 L}{\partial w_i^2} \right)_i$

- **diag(H)** can be computed in  $O(n)$ , allowing a **backprop-like algorithm**

- For details, see [LeCun et al., 1987]

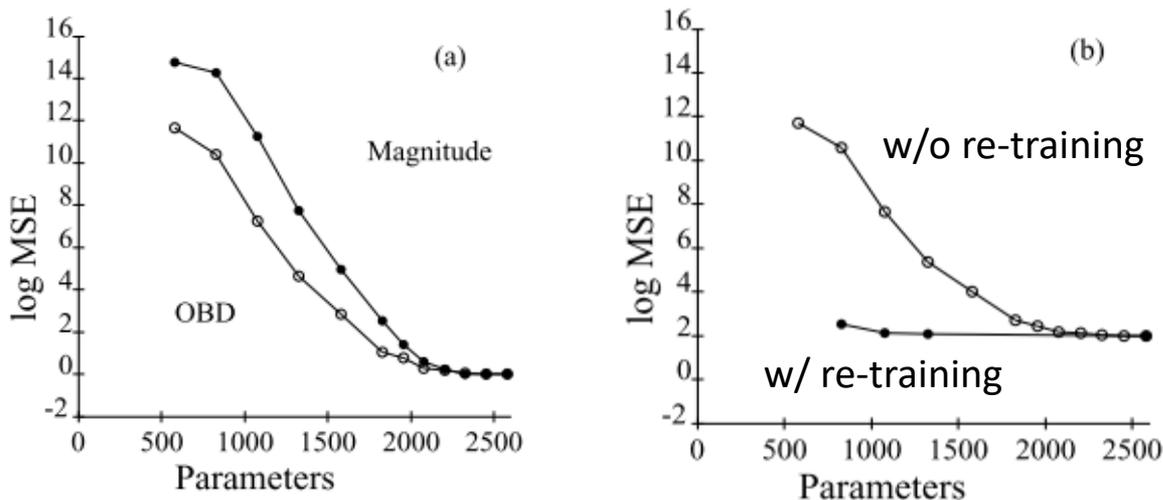
- How the **loss**  $L$  would be changed when  $\mathbf{W}$  is perturbed?

$$L(\delta\mathbf{W}) \simeq \frac{1}{2} \sum_i \frac{\partial^2 L}{\partial w_i^2} \delta w_i^2 =: \sum_i \frac{1}{2} h_{ii} \delta w_i^2$$

- The **saliency** for each weight  $\Rightarrow s_i := \frac{1}{2} h_{ii} |w_i|^2$

$$s_i := |w_i|$$

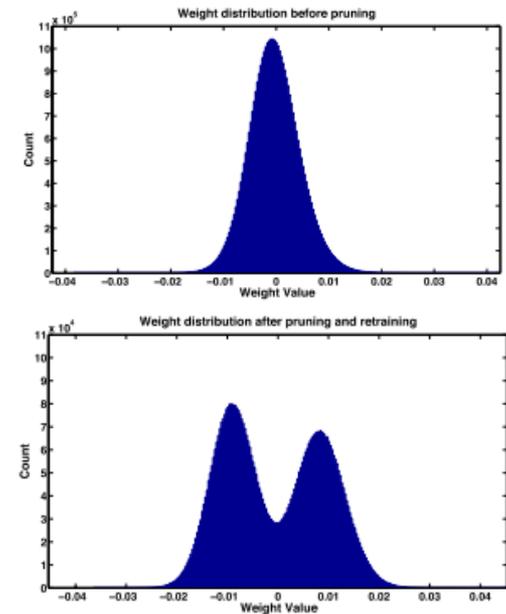
- OBD shows **robustness on pruning** compared to magnitude-based deletion
- After re-training, the original test accuracy is **recovered**



Next: Pruning modern DNNs

## Pruning Modern DNNs [Han et al., 2015]

- Han et al. (2015): Pruning larger DNNs
  - LeNet, AlexNet, VGG-16, ... on ImageNet
  - Highlights the **practical efficiency of pruning**
- OBD introduces extra computation on larger models
  - It requires an additional, separated backward pass
- The simple **magnitude-based pruning** works very well as long as **the network is re-trained**



### Comparison with other model reduction methods on AlexNet

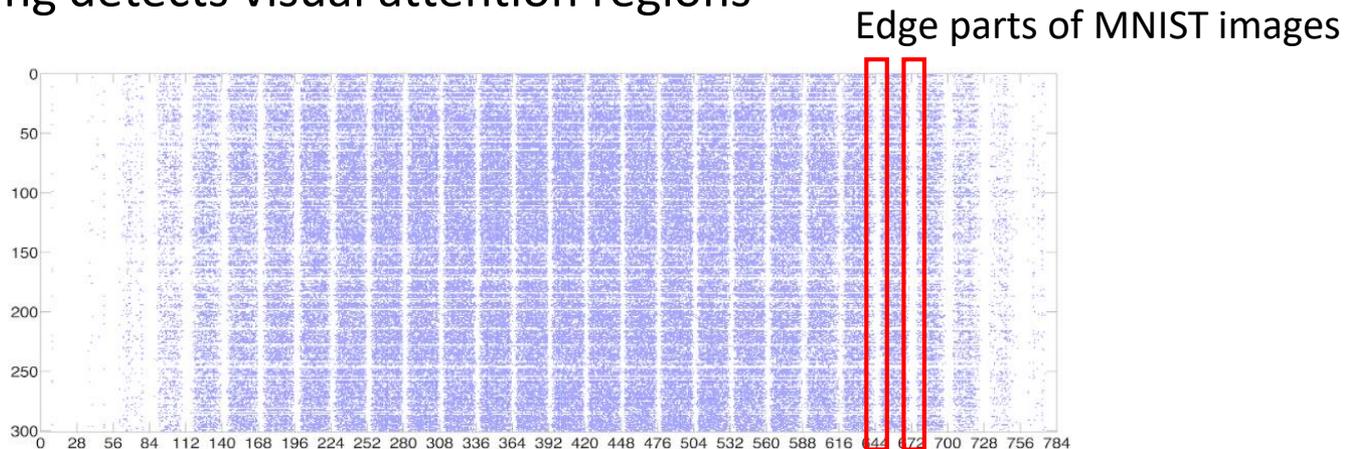
Network	Top-1 Error	Top-5 Error	Parameters	Compression Rate
Baseline Caffemodel [26]	42.78%	19.73%	61.0M	1×
Data-free pruning [28]	44.40%	-	39.6M	1.5×
Fastfood-32-AD [29]	41.93%	-	32.8M	2×
Fastfood-16-AD [29]	42.90%	-	16.4M	3.7×
Collins & Kohli [30]	44.40%	-	15.2M	4×
Naive Cut	47.18%	23.23%	13.8M	4.4×
SVD [12]	44.02%	20.56%	11.9M	5×
<b>Network Pruning</b>	<b>42.77%</b>	<b>19.67%</b>	<b>6.7M</b>	<b>9×</b>

## Pruning Modern DNNs [Han et al., 2015]

- Han et al. (2015): Pruning larger DNNs
  - Highlights the **practical efficiency of pruning**
- The **magnitude-based pruning** works well as long as **the network is re-trained**

Network	Top-1 Error	Top-5 Error	Parameters	Compression Rate
LeNet-300-100 Ref	1.64%	-	267K	
LeNet-300-100 Pruned	1.59%	-	<b>22K</b>	<b>12×</b>
LeNet-5 Ref	0.80%	-	431K	
LeNet-5 Pruned	0.77%	-	<b>36K</b>	<b>12×</b>
AlexNet Ref	42.78%	19.73%	61M	
AlexNet Pruned	42.77%	19.67%	<b>6.7M</b>	<b>9×</b>
VGG-16 Ref	31.50%	11.32%	138M	
VGG-16 Pruned	31.34%	10.88%	<b>10.3M</b>	<b>13×</b>

- Network pruning detects visual attention regions



- The **magnitude-based pruning** works well as long as **the network is re-trained**
- Mittal et al. (2018): In fact, **pruning criteria are not that important**
  - ... as long as the **re-training phase** exists
- Many strategies cannot even beat **random pruning** after fine-tuning

Heuristic	25 %	50%	75%
Random	0.650	0.569	0.415
Mean Activation	0.652	0.570	0.409
Entropy	0.641	0.549	0.405
Scaled Entropy	0.637	0.550	0.401
$l_1$ -norm	<b>0.667</b>	<b>0.593</b>	<b>0.436</b>
APoZ	0.647	0.564	0.422
Sensitivity	0.636	0.543	0.379

Table 1: Comparison of different filter pruning strategies on VGG-16.

Heuristics	#Layers Pruned	25 %	50%	75%
Random	16	0.722	0.683	0.617
$l_1$ -norm	16	0.714	0.677	0.610
Random	32	0.696	0.637	0.518
$l_1$ -norm	32	0.691	0.633	0.514

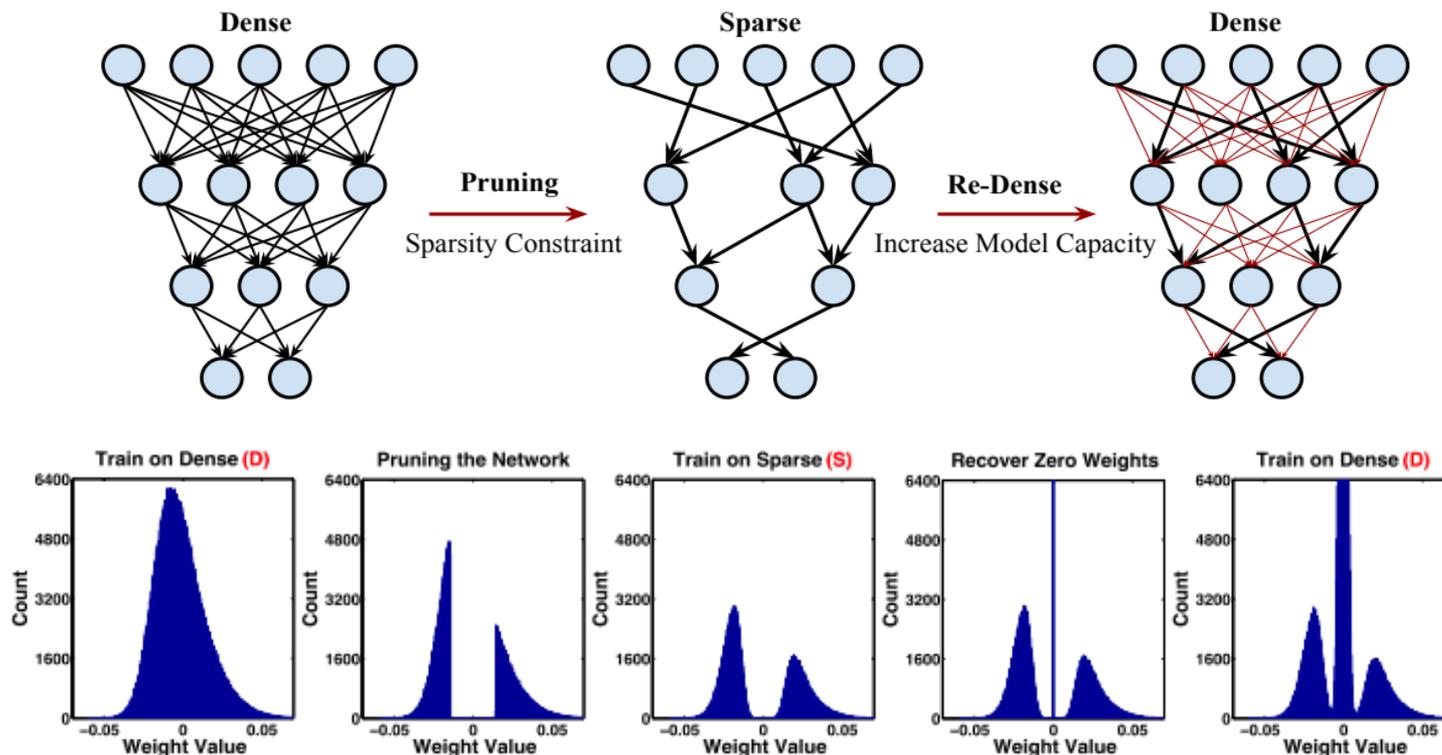
Table 3: Comparison of different filter pruning strategies on ResNet (Top-1 accuracy of unpruned network is 0.745)

- The compressibility of DNNs are NOT due to the specific criterion
  - ... but due to the **inherent plasticity** of DNNs

Next: Dense-Sparse-Dense

## Network Re-wiring: Dense-Sparse-Dense Training Flow

- Network pruning preserves accuracy of the original network
- Han et al. (2017): **Re-wiring** the pruned connections improves DNNs further
  - “**Dense-Sparse-Dense**” training flow



## Network Re-wiring: Dense-Sparse-Dense Training Flow

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- Network pruning preserves accuracy of the original network
- Han et al. (2017): **Re-wiring** the pruned connections improves DNNs further
  - “**Dense-Sparse-Dense**” training flow
- Pruning discovers **better optimum** that the current training cannot find

Neural Network	Domain	Dataset	Type	Baseline	DSD	Abs. Imp.	Rel. Imp.
GoogLeNet	Vision	ImageNet	CNN	31.1% <sup>1</sup>	<b>30.0%</b>	1.1%	3.6%
VGG-16	Vision	ImageNet	CNN	31.5% <sup>1</sup>	<b>27.2%</b>	4.3%	13.7%
ResNet-18	Vision	ImageNet	CNN	30.4% <sup>1</sup>	<b>29.2%</b>	1.2%	4.1%
ResNet-50	Vision	ImageNet	CNN	24.0% <sup>1</sup>	<b>22.9%</b>	1.1%	4.6%
NeuralTalk	Caption	Flickr-8K	LSTM	16.8 <sup>2</sup>	<b>18.5</b>	1.7	10.1%
DeepSpeech	Speech	WSJ'93	RNN	33.6% <sup>3</sup>	<b>31.6%</b>	2.0%	5.8%
DeepSpeech-2	Speech	WSJ'93	RNN	14.5% <sup>3</sup>	<b>13.4%</b>	1.1%	7.4%

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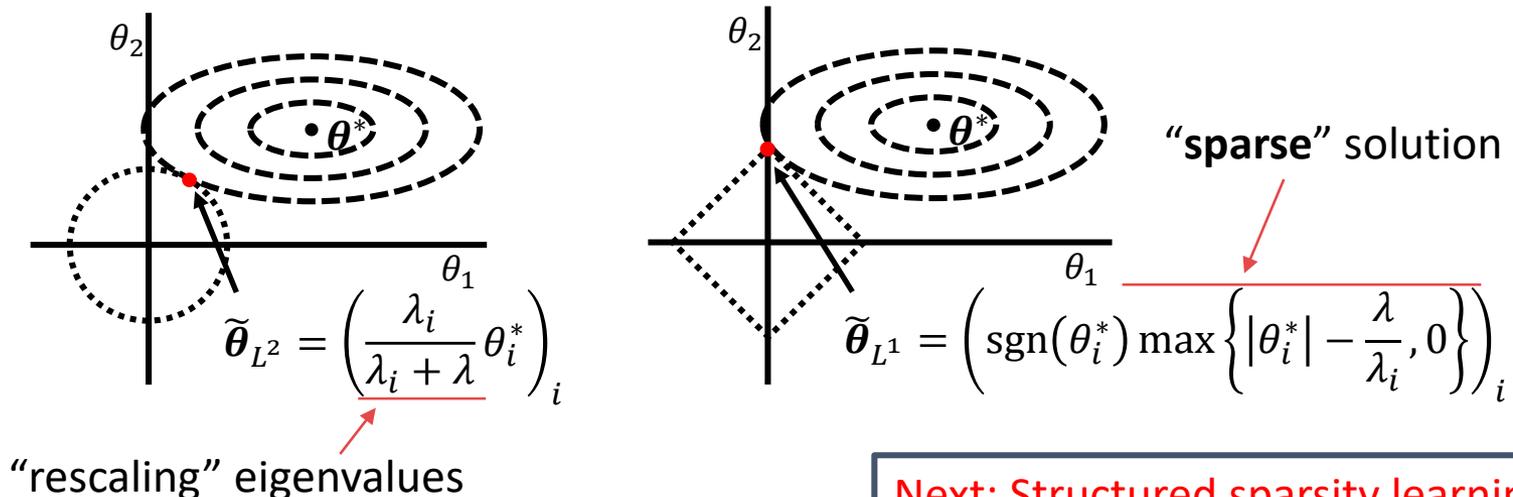
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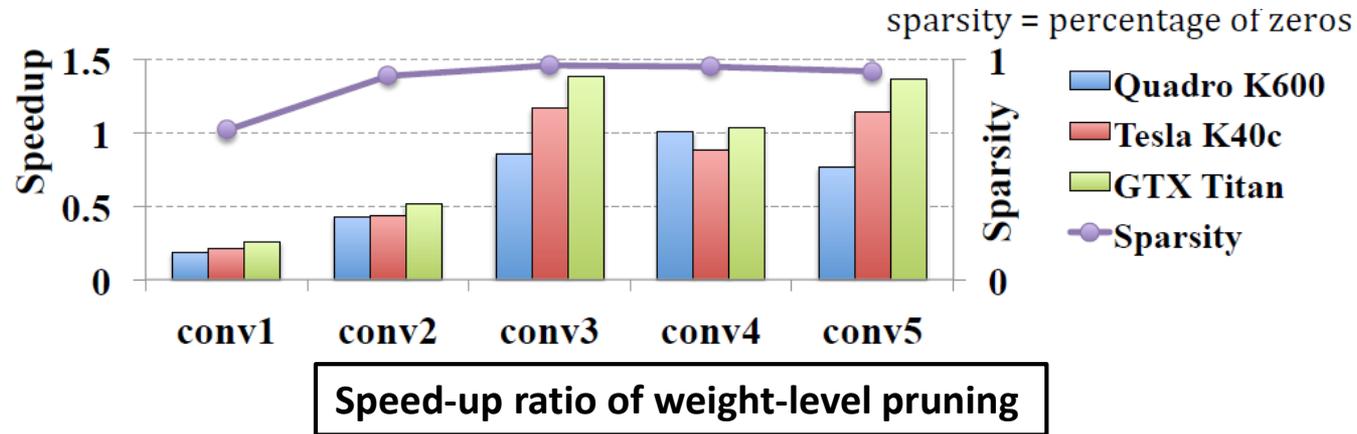
## 4. Summary

- The performance of pruning depends on the **initial training scheme**
  - e.g. Which regularization to use:  $L^2$  or  $L^1$ ?
- Which training scheme will **maximize** the pruning performance?
  - We still don't know about the optimal points of a DNN
- One prominent way: **Sparse network learning**
  - Inducing to a **sparse solution** from training a network
  - Weights with value 0 can safely be removed  $\Rightarrow$  it **does not** require re-training
- **Example:**  $L^1$ -regularization



Next: Structured sparsity learning

- “Un-structured” **weight-level pruning** may not engage a **practical speed-up**
  - Despite of extremely high sparsity, actual speed-ups in GPU is limited



Non-structured sparsity (poor data pattern)



Structured sparsity (regular data pattern)



5× speedup after concatenation of nonzero rows and columns



- **Structured sparsity** can be induced by adding **group-lasso regularization**

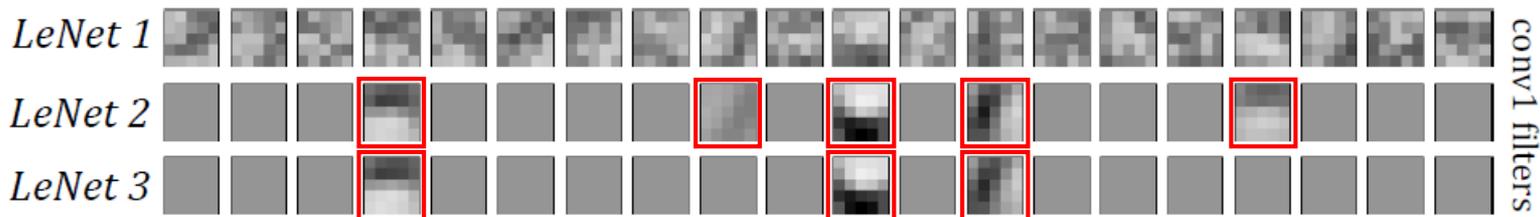
$$\min_{\mathbf{W}} \mathcal{L}(\mathbf{W}) + \lambda \sum_{l=1}^L R_g(\mathbf{W}^{(l)}), \quad R_g(\mathbf{w}) = \sum_{g=1}^G \|\mathbf{w}^{(g)}\|_2$$

- **Filter-wise and channel-wise:**
  - # filters
  - # channels
$$R_g(\mathbf{W}^{(l)}) = \sum_{n_l=1}^{N_l} \|\mathbf{W}_{n_l, :, :, :}^{(l)}\|_2 + \sum_{c_l=1}^{C_l} \|\mathbf{W}_{:, c_l, :, :}^{(l)}\|_2$$

Table 1: Results after penalizing unimportant filters and channels in *LeNet*

<i>LeNet</i> #	Error	Filter # <sup>§</sup>	Channel # <sup>§</sup>	FLOP <sup>§</sup>	Speedup <sup>§</sup>
1 ( <i>baseline</i> )	0.9%	20—50	1—20	100%—100%	1.00×—1.00×
2	0.8%	5—19	1—4	25%—7.6%	1.64×—5.23×
3	1.0%	3—12	1—3	15%—3.6%	1.99×—7.44×

<sup>§</sup>In the order of *conv1—conv2*



Fewer but smoother feature extractors

- **Structured sparsity** can be induced by adding **group-lasso regularization**

$$\min_{\mathbf{W}} \mathcal{L}(\mathbf{W}) + \lambda \sum_{l=1}^L R_g(\mathbf{W}^{(l)}), \quad R_g(\mathbf{w}) = \sum_{g=1}^G \|\mathbf{w}^{(g)}\|_2$$

- **Shape-wise sparsity:**

$$R_g(\mathbf{W}^{(l)}) = \sum_{c_l=1}^{C_l} \sum_{m_l=1}^{M_l} \sum_{k_l=1}^{K_l} \|\mathbf{W}_{:,c_l,m_l,k_l}^{(l)}\|_2$$

width
height

Table 2: Results after learning filter shapes in *LeNet*

<i>LeNet</i> #	Error	Filter size <sup>§</sup>	Channel #	FLOP	Speedup
1 ( <i>baseline</i> )	0.9%	25—500	1—20	100%—100%	1.00×—1.00×
4	0.8%	21—41	1—2	8.4%—8.2%	2.33×—6.93×
5	1.0%	7—14	1—1	1.4%—2.8%	5.19×—10.82×

<sup>§</sup> The sizes of filters after removing zero shape fibers, in the order of *conv1—conv2*



- **Structured sparsity** can be induced by adding **group-lasso regularization**

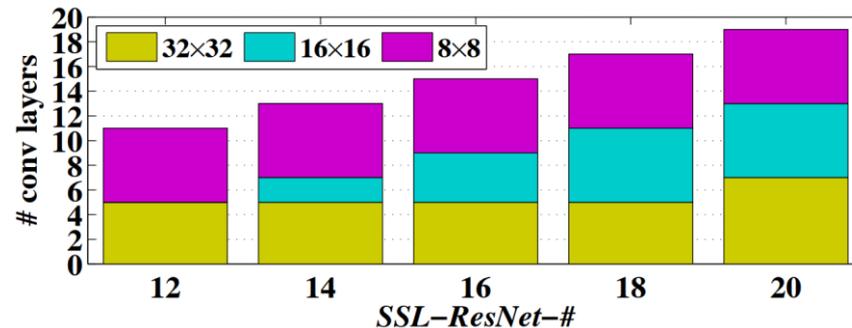
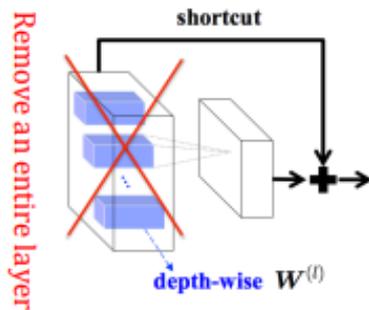
$$\min_{\mathbf{W}} \mathcal{L}(\mathbf{W}) + \lambda \sum_{l=1}^L R_g(\mathbf{W}^{(l)}), \quad R_g(\mathbf{w}) = \sum_{g=1}^G \|\mathbf{w}^{(g)}\|_2$$

- **Depth-wise sparsity:**  $R_g(\mathbf{W}^{(l)}) = \|\mathbf{W}^{(l)}\|_2$

ResNet-20/32: baseline with 20/32 layers

SSL-ResNet-#: Ours with # layers after learning depth of ResNet-20

	# layers	error	# layers	error
ResNet	20	8.82%	32	7.51%
SSL-ResNet	<b>14</b>	<b>8.54%</b>	<b>18</b>	<b>7.40%</b>



**Next: Sparsification via variational dropout**

- **Variational dropout** (VD) allows to **learn** the dropout rates separately
- Unlike dropout, VD imposes noises on **weights  $\theta$** :

$$w_i := \theta_i \cdot \xi_i, \quad \text{where } p_{\alpha_i}(\xi_i) = \mathcal{N}(1, \alpha_i)$$

- A Bayesian generalization of Gaussian dropout [Srivastava et al., 2014]
  - $\mathbf{w} = (w_i)_i$  is **adapted to data** in Bayesian sense by optimizing  $\alpha$  and  $\theta$
- **Re-parametrization trick** allows  $\mathbf{w}$  to be learned via minibatch-based gradient estimation methods [Kingma & Welling, 2013]
    - $\alpha$  and  $\theta$  can be **optimized** separated from noises

$$w_i = \theta_i + (\theta_i \sqrt{\alpha_i}) \cdot \varepsilon_i, \quad \text{where } \varepsilon_i \sim \mathcal{N}(0, 1)$$

- VD imposes noises on weights  $\theta$ :

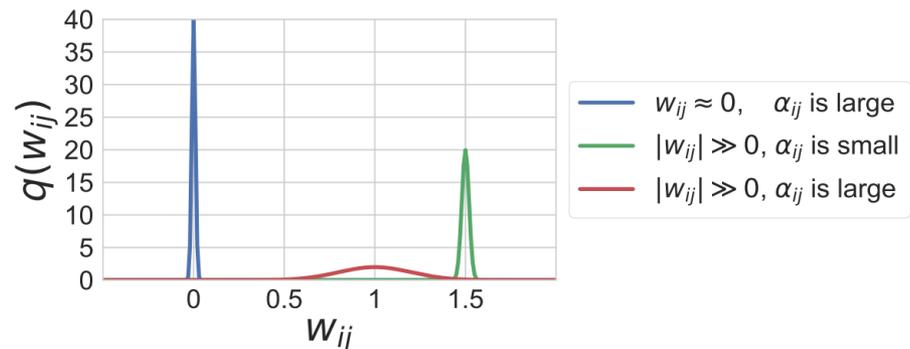
$$w_i := \theta_i \cdot \xi_i, \quad \text{where } p_{\alpha_i}(\xi_i) = \mathcal{N}(1, \alpha_i)$$

- The original VD set a **constraint**  $\alpha_i \leq 1$  for technical reasons
  - It corresponds to  $p \leq 0.5$  in binary dropout

**Q. What if  $\alpha_i > 1$ ? What happens when  $\alpha_i \rightarrow \infty$ ?**

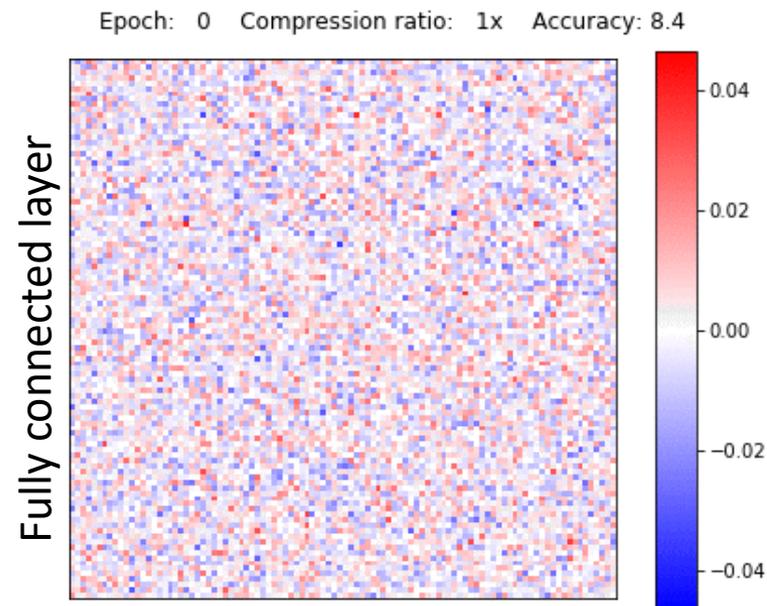
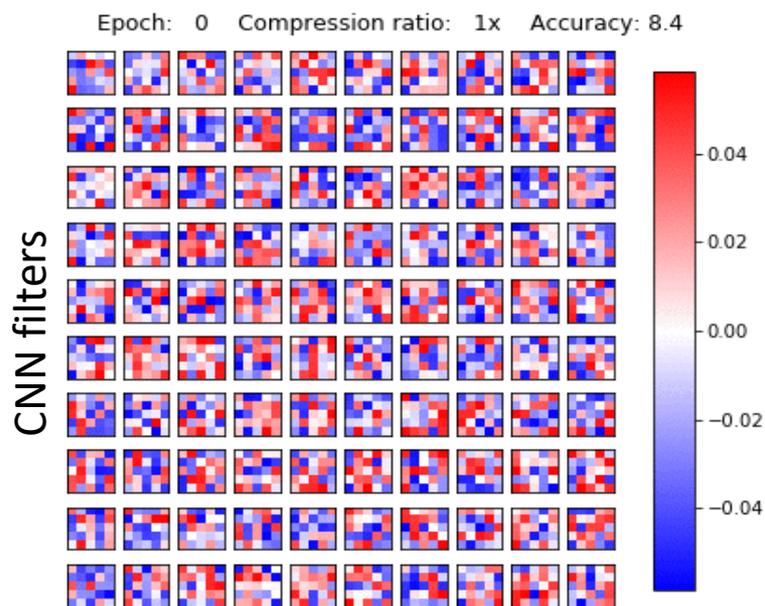
- $p(w_i) = \theta_i \cdot p(\xi_i) = \mathcal{N}(\theta_i, \alpha_i \theta_i^2)$
- $w_i$  will be **completely random** as  $\alpha_i \rightarrow \infty$
- Such  $w_i$  will **corrupt** the expected log likelihood
- ... **except** that  $\theta_i \rightarrow 0$  as well!

$$\begin{aligned} \theta_{ij} \rightarrow 0, \quad \alpha_{ij} \theta_{ij}^2 \rightarrow 0 \\ \Downarrow \\ q(w_{ij} | \theta_{ij}, \alpha_{ij}) \rightarrow \mathcal{N}(w_{ij} | 0, 0) = \delta(w_{ij}) \end{aligned}$$



Q. What if  $\alpha_i > 1$ ? What happens when  $\alpha_i \rightarrow \infty$ ?

- It will **corrupt** the expected log likelihood **except** that  $\theta_i \rightarrow 0$  as well
- Molchanov et al. (2017): **Extending VD for  $\alpha_i > 1 \Rightarrow$  Super sparse solutions**
  - Weights with  $\log \alpha > 3$  are pruned away during training



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Network	Method	Error %	Sparsity per Layer %	$\frac{ W }{ W_{\neq 0} }$
LeNet-300-100	Original	1.64		1
	Pruning	1.59	92.0 – 91.0 – 74.0	12 [Han et al., 2015]
	DNS	1.99	98.2 – 98.2 – 94.5	56
	SWS	1.94		23
	(ours) Sparse VD	1.92	98.9 – 97.2 – 62.0	<b>68</b>
LeNet-5-Caffe	Original	0.80		1
	Pruning	0.77	34 – 88 – 92.0 – 81	12 [Han et al., 2015]
	DNS	0.91	86 – 97 – 99.3 – 96	111
	SWS	0.97		200
	(ours) Sparse VD	0.75	67 – 98 – 99.8 – 95	<b>280</b>

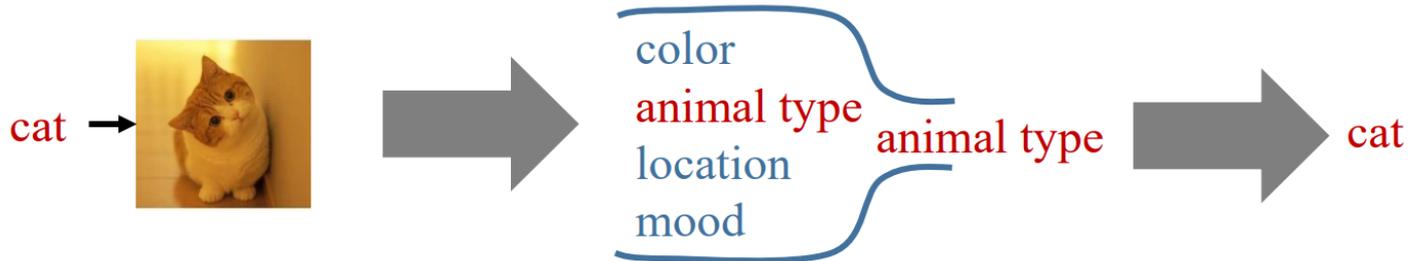
Next: Variational information bottleneck

- **Motivation:** Markov chain interpretation of DNN [Tishby & Zaslavsky, 2015]

$$y \rightarrow x = h_0 \rightarrow h_1 \rightarrow \dots \rightarrow \underline{h_{i-1}} \rightarrow \underline{h_i} \rightarrow \dots \rightarrow \underline{h_L} \rightarrow \hat{y}$$

$p(h_i | h_{i-1})$

Approximate  $p(y | h_L)$   
via tractable  $p(\hat{y} | h_L)$



1. Maximize  $I(h_i; y)$  for high-accuracy prediction
2. Minimize  $I(h_i; h_{i-1})$  for compression  $\Rightarrow$  “**information bottleneck**”

- **Layer-wise losses** become:

$$\mathcal{L}_i = \gamma_i I(h_i; h_{i-1}) - I(h_i; y)$$

Mutual information  
↓  
↙

↘  
The relative strength of bottleneck

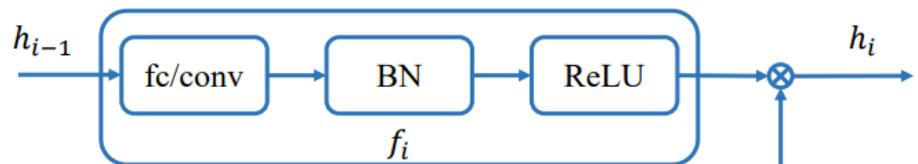
- **Layer-wise losses** become  $\mathcal{L}_i = \gamma_i I(\mathbf{h}_i; \mathbf{h}_{i-1}) - I(\mathbf{h}_i; \mathbf{y})$
- **Problem:** Computing  $I(\cdot; \cdot)$  is usually **intractable**
- Instead, we minimize **variational upper bound** of it

$$\mathcal{L}_i \leq \tilde{\mathcal{L}}_i = \gamma_i \mathbb{E}[\text{KL}(\underbrace{p(\mathbf{h}_i | \mathbf{h}_{i-1})}_{\text{variational approx. of } p(\mathbf{h}_i)} || \underbrace{q(\mathbf{h}_i)}_{\text{variational approx. of } p(\mathbf{y} | \mathbf{h}_L)})] - \mathbb{E}[\log \underbrace{q(\mathbf{y} | \mathbf{h}_L)}_{\substack{\text{multinomial for classification} \\ \text{Gaussian for regression}}}]$$

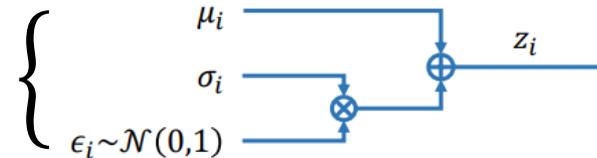
- **Variational Information Bottleneck (VIB) model**

$$p(\mathbf{h}_i | \mathbf{h}_{i-1}) := f_i(\mathbf{h}_{i-1}) \odot \mathcal{N}(\mathbf{h}_i | \boldsymbol{\mu}_i, \text{diag}(\boldsymbol{\sigma}_i^2))$$

$$q(\mathbf{h}_i) := \mathcal{N}(\mathbf{h}_i | \mathbf{0}, \text{diag}(\boldsymbol{\xi}_i))$$



**Reparametrization trick**  
[Kingma & Welling, 2013]



- We minimize **variational upper bound** of  $\mathcal{L}_i$

$$\mathcal{L}_i \leq \tilde{\mathcal{L}}_i = \gamma_i \mathbb{E}[\text{KL}(p(\mathbf{h}_i | \mathbf{h}_{i-1}) || q(\mathbf{h}_i))] - \mathbb{E}[\log q(\mathbf{y} | \mathbf{h}_L)]$$

- Final variational objective function (**VIBNet**):

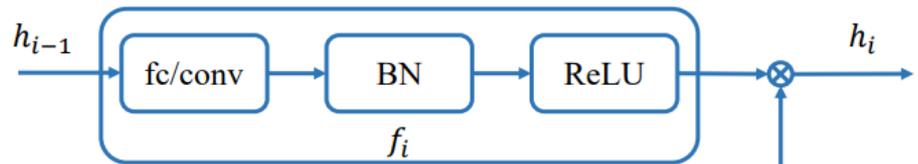
$$\tilde{\mathcal{L}} = \underbrace{\sum_{i=1}^L \gamma_i \sum_j \log \left( 1 + \frac{\mu_{ij}^2}{\sigma_{ij}^2} \right)}_{\text{regularization}} - \underbrace{L \cdot \mathbb{E}[\log q(\mathbf{y} | \mathbf{h}_L)]}_{\text{data-fit}}$$

# layers

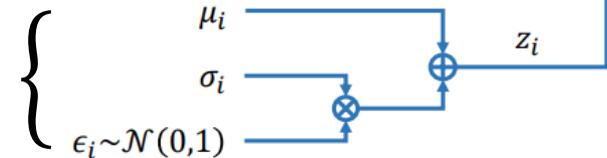
↓

- Pruning criteria:**  $\alpha_{ij} := \frac{\mu_{ij}^2}{\sigma_{ij}^2} \rightarrow 0$

- Neurons with **low value** of  $\alpha_{ij}$ 's are pruned after training



**Reparametrization trick**  
[Kingma & Welling, 2013]

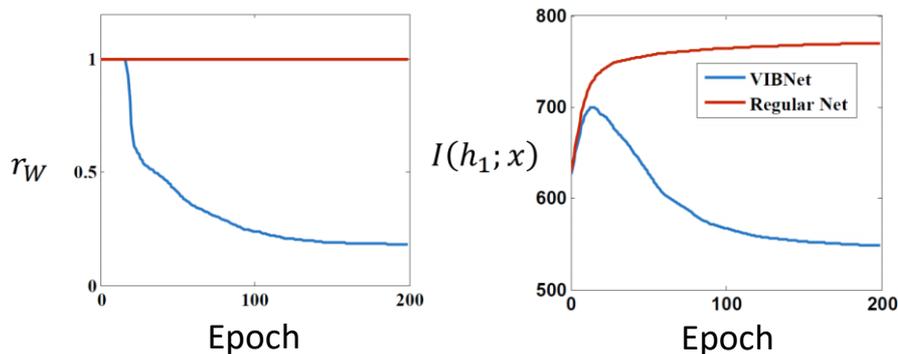


- **VIBNet** outperforms various methods by large margins

- $r_W(\%)$ : ratio of # parameters
- $r_N(\%)$ : ratio of memory footprint

Method	$r_W(\%)$	$r_N(\%)$	error(%)	Pruned Model
VD	25.28	58.95	1.8	512-114-72
BC-GNJ	10.76	32.85	1.8	278-98-13
BC-GHS	10.55	34.71	1.8	311-86-14
L0	26.02	45.02	<b>1.4</b>	219-214-100
L0-sep	10.01	32.69	1.8	266-88-33
DN	23.05	57.94	1.8	542-83-61
VIBNet	<b>3.59</b>	<b>16.98</b>	1.6	<b>97-71-33</b>

Table 1. Compression results on MNIST using LeNet-300-100.



After fine-tuning

Method	$r_W(\%)$	FLOP(Mil)	$r_N(\%)$	error(%)
BC-GNJ	6.57	141.5	81.68	8.6
BC-GHS	5.40	121.9	74.82	9.0
VIBNet	<b>5.30</b>	<b>70.63</b>	<b>49.57</b>	8.8 ( <b>8.5</b> )
PF	35.99	206.3	83.97	6.6
SBP	7.01	136.0	80.72	7.5
SBPa	5.78	99.20	66.46	9.0
VIBNet	<b>5.45</b>	<b>86.82</b>	<b>57.86</b>	6.5 ( <b>6.1</b> )
NS-Single	11.50	195.5	-	6.2
NS-Best	8.60	147.0	-	5.9
VIBNet	<b>5.79</b>	<b>116.0</b>	<b>59.60</b>	6.2 ( <b>5.8</b> )

Table 3. Compression results on CIFAR10 using VGG-16.

Method	$r_W(\%)$	FLOP(Mil)	$r_N(\%)$	error(%)
RNP	-	160	-	38.0
VIBNet	<b>22.75</b>	<b>133.6</b>	<b>59.80</b>	37.6 ( <b>37.4</b> )
NS-Single	24.90	250.5	-	26.5
NS-Best	20.80	214.8	-	26.0
VIBNet	<b>15.08</b>	<b>203.1</b>	<b>73.80</b>	25.9 ( <b>25.7</b> )

Table 4. Compression results on CIFAR100 using VGG-16.

## 1. Network Pruning and Re-wiring

- Optimal brain damage
- Pruning modern DNNs
- Dense-Sparse-Dense training flow

## 2. Sparse Network Learning

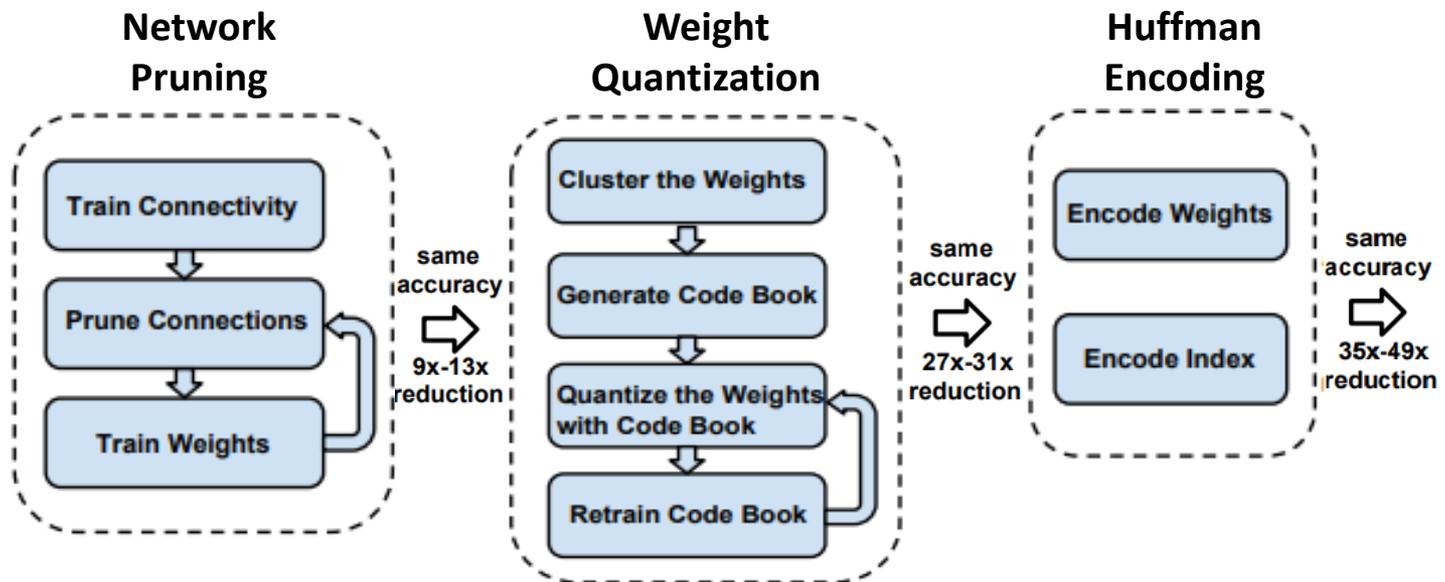
- Structured sparsity learning
- Sparsification via variational dropout
- Variational information bottleneck

## 3. Weight Quantization

- Deep compression
- Binarized neural networks

## 4. Summary

- **Quantizing weights** can further compress the pruned networks
  - Weights are **clustered** into discrete values
  - The network is represented only with several **centroid values**
- Han et al. (2015): Pruning DNNs  $\Rightarrow$  9x-13x reduction
- Han et al. (2016): Pruning + **Quantization** + **Huffman**  $\Rightarrow$  **35x-49x** reduction

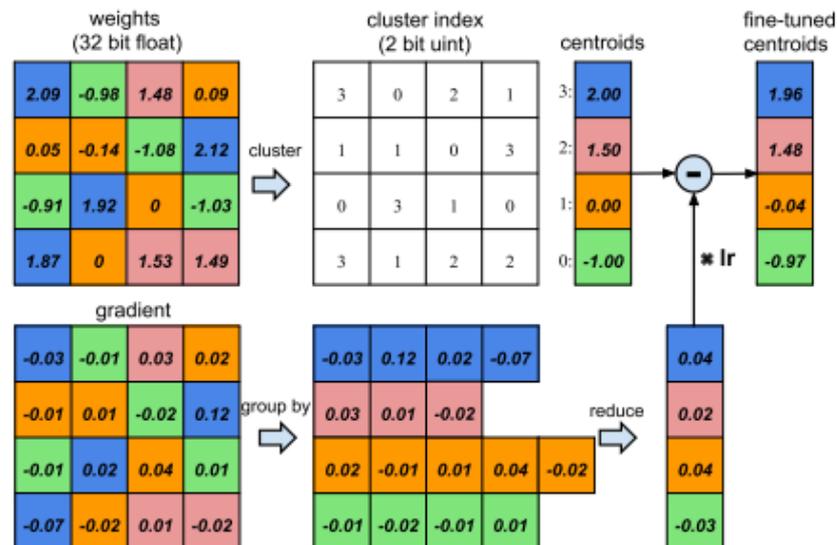


- **Quantizing weights** can further compress the pruned networks
  - Weights are **clustered** into discrete values
  - The network is represented only with several centroid values

1. **Train** a deep model until convergence
2. **Find**  $k$  clusters that minimizes **within-cluster sum of squares (WCSS)**:
 
$$\operatorname{argmin}_C \sum_{i=1}^k \sum_{w \in c_i} |w - c_i|^2$$
3. **Quantize** with the cluster  $C$  via weight sharing
4. **Fine-tune** the network with the shared weights

- In the **fine-tuning** phase, gradients in each cluster are **aggregated**:

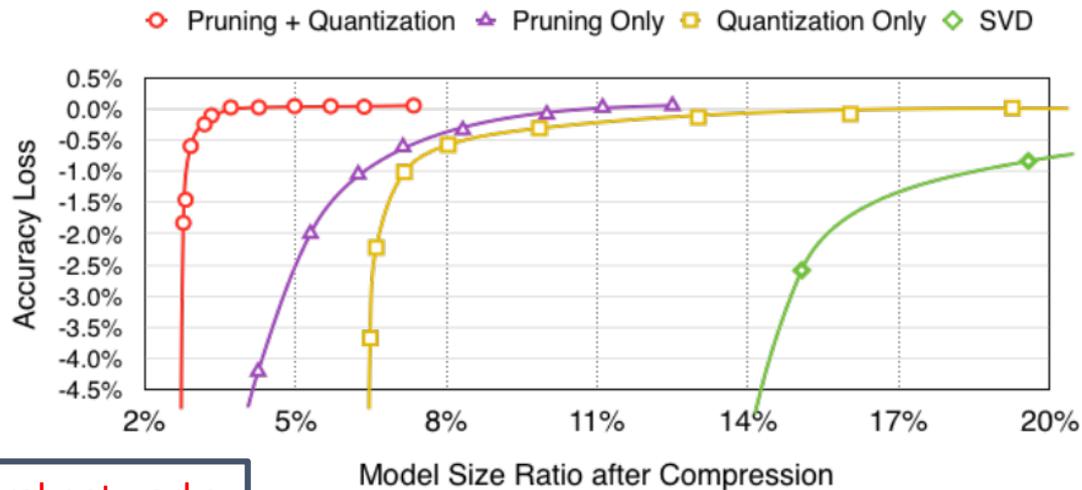
$$\begin{aligned} \frac{\partial \mathcal{L}}{\partial C_k} &= \sum_{i,j} \frac{\partial \mathcal{L}}{\partial W_{ij}} \frac{\partial W_{ij}}{\partial C_k} \\ &= \sum_{i,j} \frac{\partial \mathcal{L}}{\partial W_{ij}} \mathbf{1}(W_{ij} \in C_k) \end{aligned}$$



\*source : Han et al., "Deep Compression - Compressing Deep Neural Networks with Pruning, Trained Quantization and Huffman Coding", ICLR 2016

- **Deep compression** reduces the model size significantly

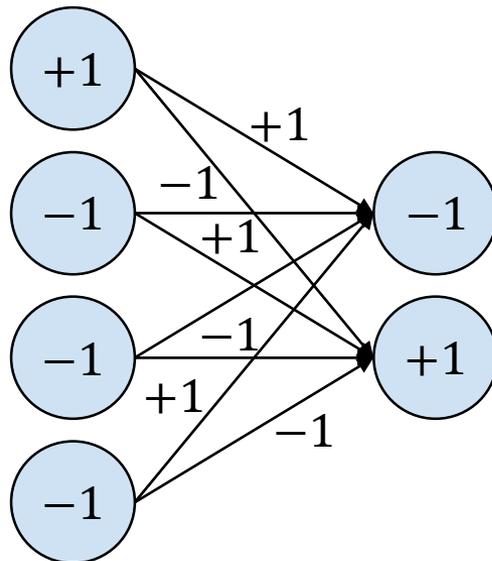
Network	Original Size	Compressed Size	Compression Ratio	Original Accuracy (%)	Compressed Accuracy (%)
LeNet-300	1070KB →	<b>27KB</b>	<b>40x</b>	98.36 →	98.42
LeNet-5	1720KB →	<b>44KB</b>	<b>39x</b>	99.20 →	99.26
AlexNet	240MB →	<b>6.9MB</b>	<b>35x</b>	80.27 →	80.30
VGGNet	550MB →	<b>11.3MB</b>	<b>49x</b>	88.68 →	89.09
GoogLeNet	28MB →	<b>2.8MB</b>	<b>10x</b>	88.90 →	88.92
SqueezeNet	4.8MB →	<b>0.47MB</b>	<b>10x</b>	80.32 →	80.35



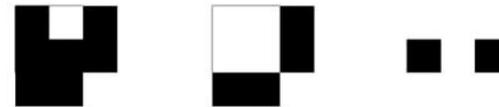
**Next: Binarized neural networks**

\*source : Han et al., "Deep Compression - Compressing Deep Neural Networks with Pruning, Trained Quantization and Huffman Coding", ICLR 2016

- Neural networks can be even **binarized** (+1 or -1)
  - DNNs trained to use **binary** weights and **binary** activations
- Expensive **32-bit MAC (Multiply-ACcumulate)**  $\Rightarrow$  Cheap **1-bit XNOR-Count**
  - “MAC == XNOR-Count”: when the weights and activations are  $\pm 1$  ↖  
# 1s in bits



Binarized weights



Binarized feature maps

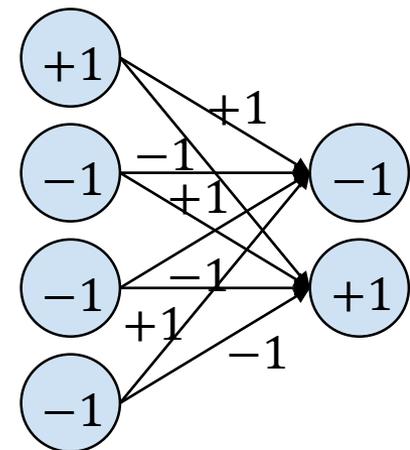


- **Idea:** Training real-valued nets ( $W_r$ ) treating binarization ( $W_b$ ) **as noise**
  - Training  $W_r$  is done by **stochastic gradient descent**
- **Binarization** ( $W_r \rightarrow W_b$ ) occurs for each forward propagation
  - On each of **weights**:  $W_b = \text{sign}(W_r)$
  - ... also on each **activation**:  $a_b = \text{sign}(a_r)$
- Gradients for  $W_r$  is estimated from  $\frac{\partial L}{\partial W_b}$  [Bengio et al., 2013]
  - “Straight-through estimator”: **ignore** the binarization during backward!

$$\frac{\partial L}{\partial W_r} = \frac{\partial L}{\partial W_b} \mathbf{1}_{|W_r| \leq 1}$$

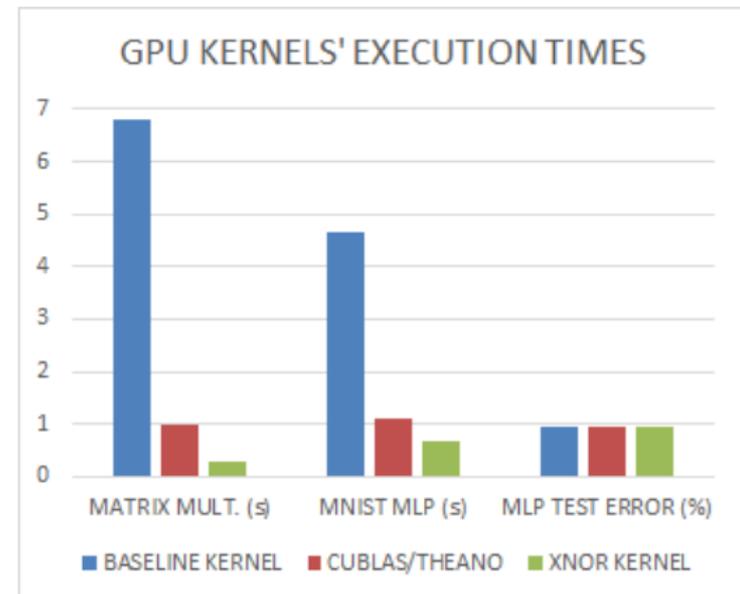
$$\frac{\partial L}{\partial a_r} = \frac{\partial L}{\partial a_b} \mathbf{1}_{|a_r| \leq 1}$$

- Cancelling gradients for better performance
  - When the value is too large



- Neural networks can be even **binarized (+1 or -1)**
  - DNNs trained to use **binary** weights and **binary** activations
- BNN yields **32x less memory** compared to the baseline 32-bit DNNs
  - ... also expected to reduce energy consumption drastically
- **23x faster** on kernel execution times
  - BNN allows us to use XNOR kernels
  - **3.4x** faster than cuBLAS

Operation	MUL	ADD
8bit Integer	0.2pJ	0.03pJ
32bit Integer	3.1pJ	0.1pJ
16bit Floating Point	1.1pJ	0.4pJ
32bit Floating Point	3.7pJ	0.9pJ



## Binarized Neural Networks [Hubara et al., 2016]

- Neural networks can be even **binarized** (+1 or -1)
  - DNNs trained to use **binary** weights and **binary** activations
- **BNN** achieves comparable error rates over existing DNNs

Data set	MNIST	SVHN	CIFAR-10
Binarized activations+weights, during training and test			
BNN (Torch7)	1.40%	2.53%	10.15%
BNN (Theano)	0.96%	2.80%	11.40%
Committee Machines' Array (Baldassi et al., 2015)	1.35%	-	-
Binarized weights, during training and test			
BinaryConnect (Courbariaux et al., 2015)	1.29 ± 0.08%	2.30%	9.90%
Binarized activations+weights, during test			
EBP (Cheng et al., 2015)	2.2 ± 0.1%	-	-
Bitwise DNNs (Kim & Smaragdis, 2016)	1.33%	-	-
Ternary weights, binary activations, during test			
(Hwang & Sung, 2014)	1.45%	-	-
No binarization (standard results)			
Maxout Networks (Goodfellow et al.)	0.94%	2.47%	11.68%
Network in Network (Lin et al.)	-	2.35%	10.41%
Gated pooling (Lee et al., 2015)	-	1.69%	7.62%

## 1. Network Pruning and Re-wiring

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- Binarized neural networks

## 4. Summary

- **Broad economic viability requires energy efficient AI** [Welling, 2018]
  - “Energy efficiency of a brain is **100x better** than current hardware”
  - “AI algorithms will be measured by **the amount of intelligence per kWh**”
- **Network pruning and re-wiring**
  - A **simple but effective** way to compress DNNs
  - Allow us to find **better optimum** that the current training cannot
- **Sparse network learning**
  - Which training scheme will **maximize** the pruning performance?
  - It has gained significant attention recently
- **Various other techniques have been also proposed**
  - Weight quantization
  - Anytime/adaptive networks [Huang et al., 2018]
  - ...

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