

Network Compression

AI602: Recent Advances in Deep Learning
Lecture 14

Slide made by

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KAIST EE

Presentation Schedule

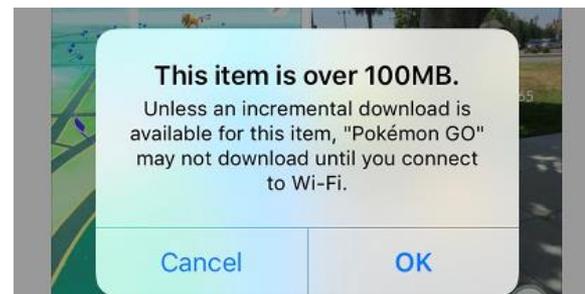
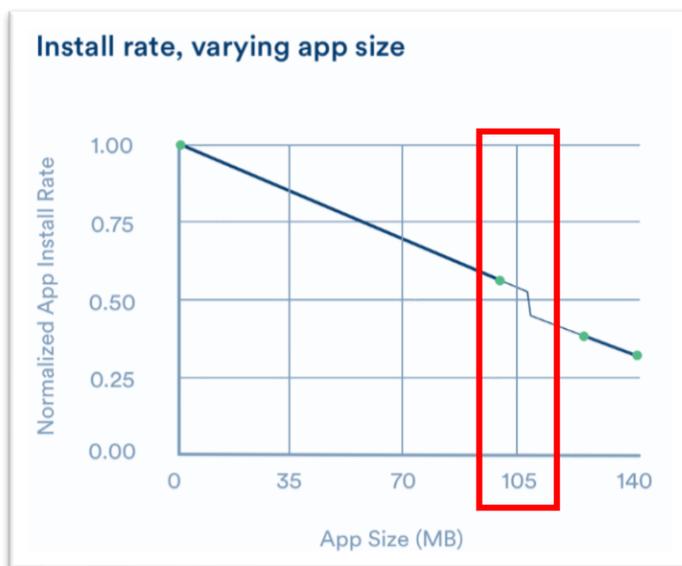
	11/21	11/26	12/10	12/12
1	정성희	David Albert	김도연	이동헌
2	김두연	Divyam Madaan	함동훈	이홍희
3	탁지훈	김경만	김재형	신재웅
4	박주혜	조인영	김종협	최중원
5	홍석찬	김규석	박관용	한문수
6	김성환	박석준	조명식	김명준
7	차현탁	이선경	서석인	도승헌
8	Thomas Thanh Minh DEFARD	Xuan Thanh Nguyen	이세웅	이수열
9	Tooba Imtiaz	신유주		
10		XUAN TRUNG PHAM		

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Deploying Deep Neural Networks in Real-World

- **Deploying deep neural networks (DNNs)** has been increasingly difficult
 - Constraints on power consumption, memory usage, inference overhead, ...
- Inference with a large-scale network consumes huge costs
- In mobile apps, such issues become more serious
 - **“The dreaded 100MB effect”**
- Can we make DNNs to **perform inferences more efficiently?**



1. Network Pruning and Re-wiring

- Optimal brain damage
- Pruning modern DNNs
- Dense-Sparse-Dense training flow

2. Sparse Network Learning

- Structured sparsity learning
- Sparsification via variational dropout
- Variational information bottleneck

3. Weight Quantization

- Deep compression
- Binarized neural networks

4. Summary

1. Network Pruning and Re-wiring

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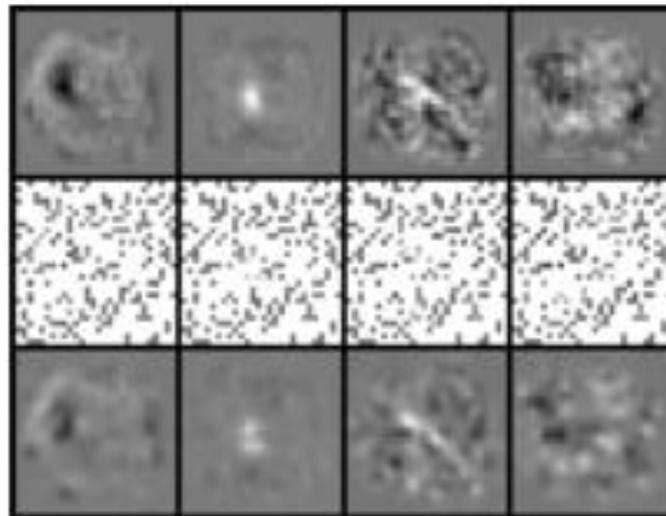
4. Summary

- DNNs include a significant number of **redundant parameters**
- Denil et al. (2013): Predicting **> 95% of weights from < 5%**
 - A simple kernel ridge regression is sufficient
 - ... without any drop in accuracy!
 - Many of the weights **need not be learned at all**

(a) Original weights

(b) Randomly selected

(c) Predicted from (b)

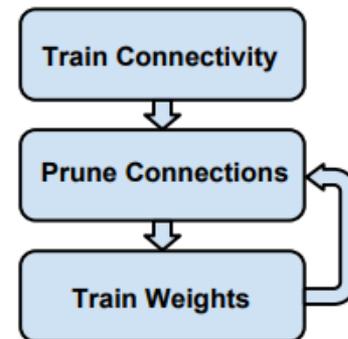


- Such redundancy can be exploited via **network pruning**

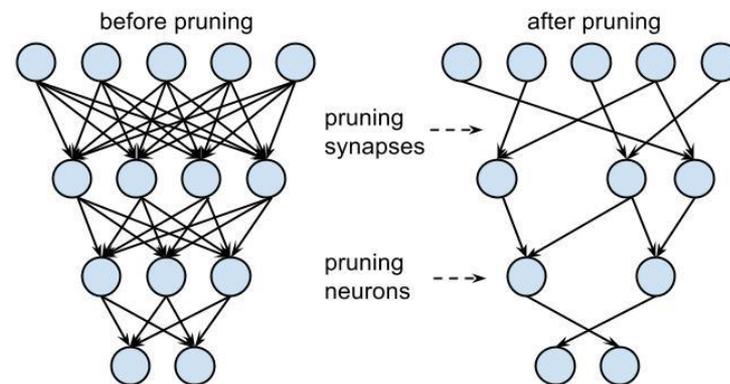
Network Pruning

- Determining **low-saliency parameters**, given a pre-trained network
- Follows the framework proposed by LeCun et al. (1990):

1. **Train** a deep model until convergence
2. **Delete** “unimportant” connections w.r.t. a certain criteria
3. **Re-train** the network
4. **Iterate** to step 2, or stop

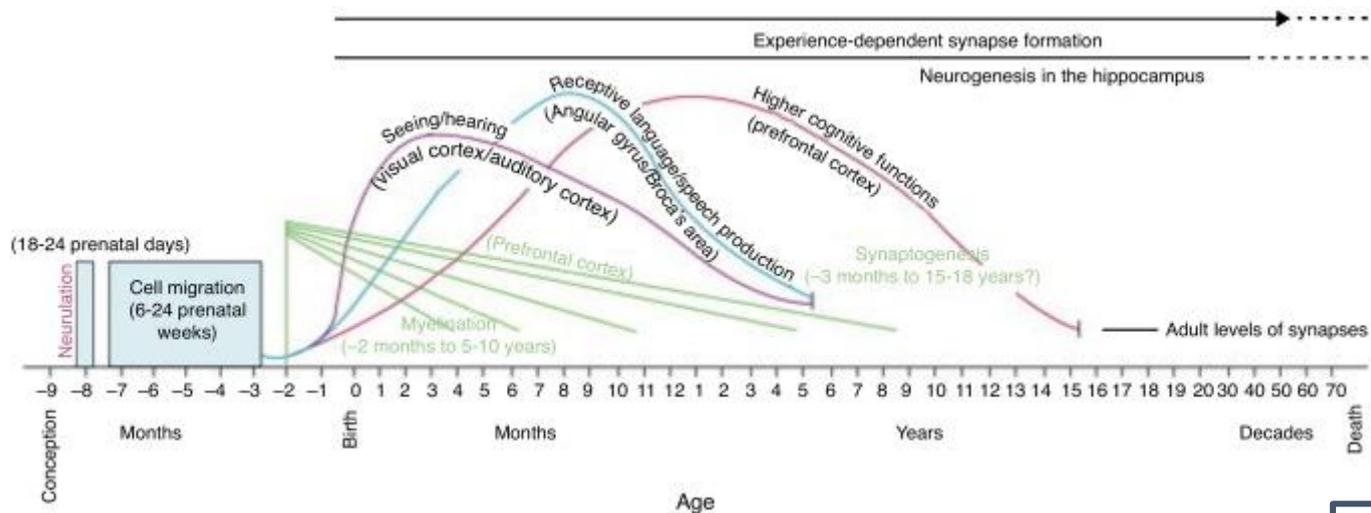


- Defining **which connection is unimportant** can vary
 - Weight magnitudes (L^2 , L^1 , ...)
 - Mean activation [Molchanov et al., 2016]
 - Avg. % of Zeros (APoZ) [Hu et al., 2016]
 - Low entropy activation [Luo et al., 2017]
 - ...



Synaptic Pruning in Human Brain

- Human brains are also using pruning schemes as well
- **Synaptic pruning** removes redundant synapses in the brain during lifetime



Next: OBD

*source: Leisman et al., "The neurological development of the child with the educational enrichment in mind.", *Psicología Educativa* 2015

- Network pruning **perturbs weights \mathbf{W}** by **zeroing** some of them
- How the **loss L** would be changed when \mathbf{W} is perturbed?
- **OBD** approximates L by the **2nd order Taylor series**:

$$\delta L \simeq \underbrace{\sum_i \frac{\partial L}{\partial w_i} \delta w_i}_{\text{1st order}} + \underbrace{\frac{1}{2} \sum_i \frac{\partial^2 L}{\partial w_i^2} \delta w_i^2 + \frac{1}{2} \sum_{i,j} \frac{\partial^2 L}{\partial w_i \partial w_j} \delta w_i \delta w_j}_{\text{2nd order}} + O(\|\delta \mathbf{W}\|^3)$$

- **Problem:** Computing $H = \left(\frac{\partial L}{\partial w_i \partial w_j} \right)_{i,j}$ is usually intractable
 - Requires $O(n^2)$ on **# weights**
 - Neural networks usually have enormous number of weights
 - e.g. AlexNet: **60M** parameters $\Rightarrow H$ consists $\approx 3.6 \times 10^{15}$ elements

- **Problem:** Computing $H = \left(\frac{\partial L}{\partial w_i \partial w_j} \right)_{i,j}$ is usually intractable

- Two additional assumptions for tractability

1. **Diagonal** approximation: $H = \frac{\partial^2 L}{\partial w_i \partial w_j} = 0$ if $i \neq j$

2. **Extremal** assumption: $\frac{\partial L}{\partial w_i} = 0 \quad \forall i$

- **W** would be in a **local minima** if it's pre-trained

- Now we get: $\delta L \simeq \frac{1}{2} \sum_i \frac{\partial^2 L}{\partial w_i^2} \delta w_i^2 + O(\|\delta \mathbf{W}\|^3)$

- It only needs $\text{diag}(H) := \left(\frac{\partial^2 L}{\partial w_i^2} \right)_i$

- **diag(H)** can be computed **in $O(n)$** , allowing a **backprop-like algorithm**

- For details, see [LeCun et al., 1987]

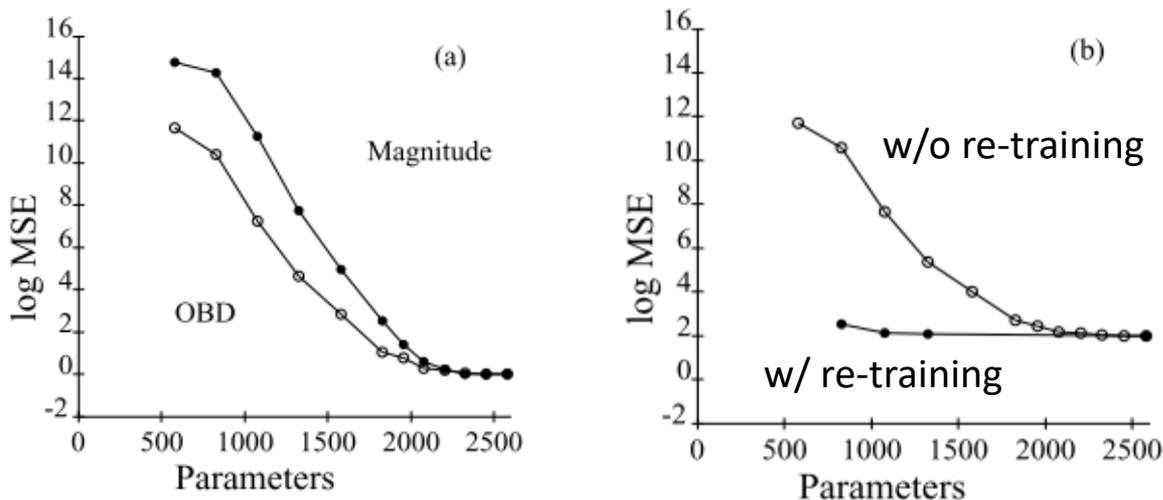
- How the **loss** L would be changed when \mathbf{W} is perturbed?

$$L(\delta\mathbf{W}) \simeq \frac{1}{2} \sum_i \frac{\partial^2 L}{\partial w_i^2} \delta w_i^2 =: \sum_i \frac{1}{2} h_{ii} \delta w_i^2$$

- The **saliency** for each weight $\Rightarrow s_i := \frac{1}{2} h_{ii} |w_i|^2$

$$s_i := |w_i|$$

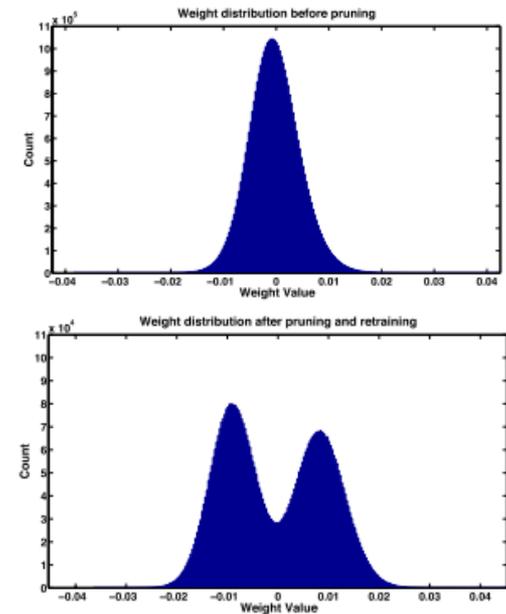
- OBD shows **robustness on pruning** compared to magnitude-based deletion
- After re-training, the original test accuracy is **recovered**



Next: Pruning modern DNNs

Pruning Modern DNNs [Han et al., 2015]

- Han et al. (2015): Pruning larger DNNs
 - LeNet, AlexNet, VGG-16, ... on ImageNet
 - Highlights the **practical efficiency of pruning**
- OBD introduces extra computation on larger models
 - It requires an additional, separated backward pass
- The simple **magnitude-based pruning** works very well as long as **the network is re-trained**



Comparison with other model reduction methods on AlexNet

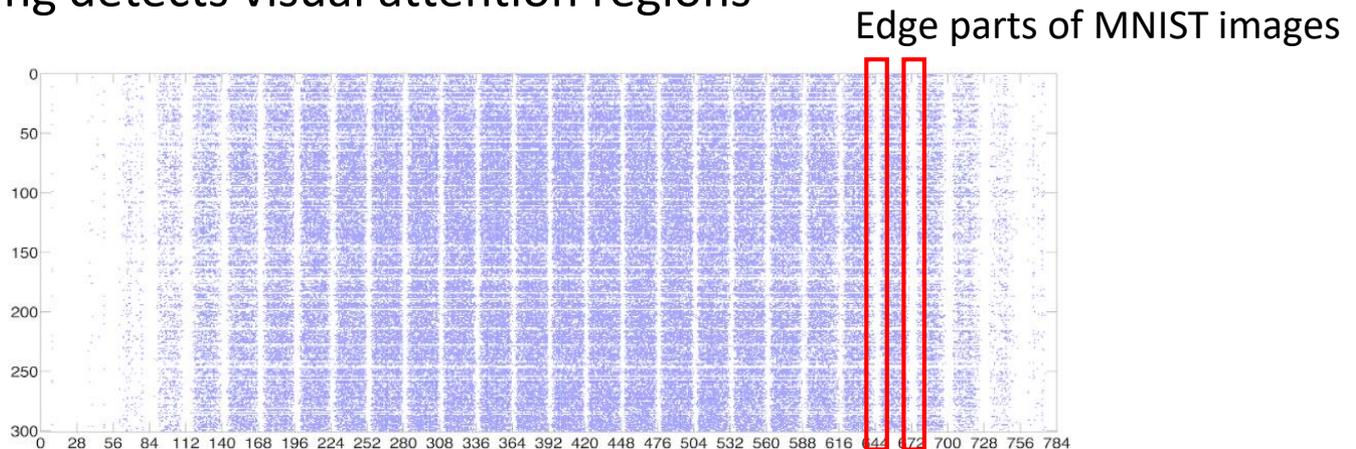
Network	Top-1 Error	Top-5 Error	Parameters	Compression Rate
Baseline Caffemodel [26]	42.78%	19.73%	61.0M	1×
Data-free pruning [28]	44.40%	-	39.6M	1.5×
Fastfood-32-AD [29]	41.93%	-	32.8M	2×
Fastfood-16-AD [29]	42.90%	-	16.4M	3.7×
Collins & Kohli [30]	44.40%	-	15.2M	4×
Naive Cut	47.18%	23.23%	13.8M	4.4×
SVD [12]	44.02%	20.56%	11.9M	5×
Network Pruning	42.77%	19.67%	6.7M	9×

Pruning Modern DNNs [Han et al., 2015]

- Han et al. (2015): Pruning larger DNNs
 - Highlights the **practical efficiency of pruning**
- The **magnitude-based pruning** works well as long as **the network is re-trained**

Network	Top-1 Error	Top-5 Error	Parameters	Compression Rate
LeNet-300-100 Ref	1.64%	-	267K	
LeNet-300-100 Pruned	1.59%	-	22K	12×
LeNet-5 Ref	0.80%	-	431K	
LeNet-5 Pruned	0.77%	-	36K	12×
AlexNet Ref	42.78%	19.73%	61M	
AlexNet Pruned	42.77%	19.67%	6.7M	9×
VGG-16 Ref	31.50%	11.32%	138M	
VGG-16 Pruned	31.34%	10.88%	10.3M	13×

- Network pruning detects visual attention regions



- The **magnitude-based pruning** works well as long as **the network is re-trained**
- Mittal et al. (2018): In fact, **pruning criteria are not that important**
 - ... as long as the **re-training phase** exists
- Many strategies cannot even beat **random pruning** after fine-tuning

Heuristic	25 %	50%	75%
Random	0.650	0.569	0.415
Mean Activation	0.652	0.570	0.409
Entropy	0.641	0.549	0.405
Scaled Entropy	0.637	0.550	0.401
l_1 -norm	0.667	0.593	0.436
APoZ	0.647	0.564	0.422
Sensitivity	0.636	0.543	0.379

Table 1: Comparison of different filter pruning strategies on VGG-16.

Heuristics	#Layers Pruned	25 %	50%	75%
Random	16	0.722	0.683	0.617
l_1 -norm	16	0.714	0.677	0.610
Random	32	0.696	0.637	0.518
l_1 -norm	32	0.691	0.633	0.514

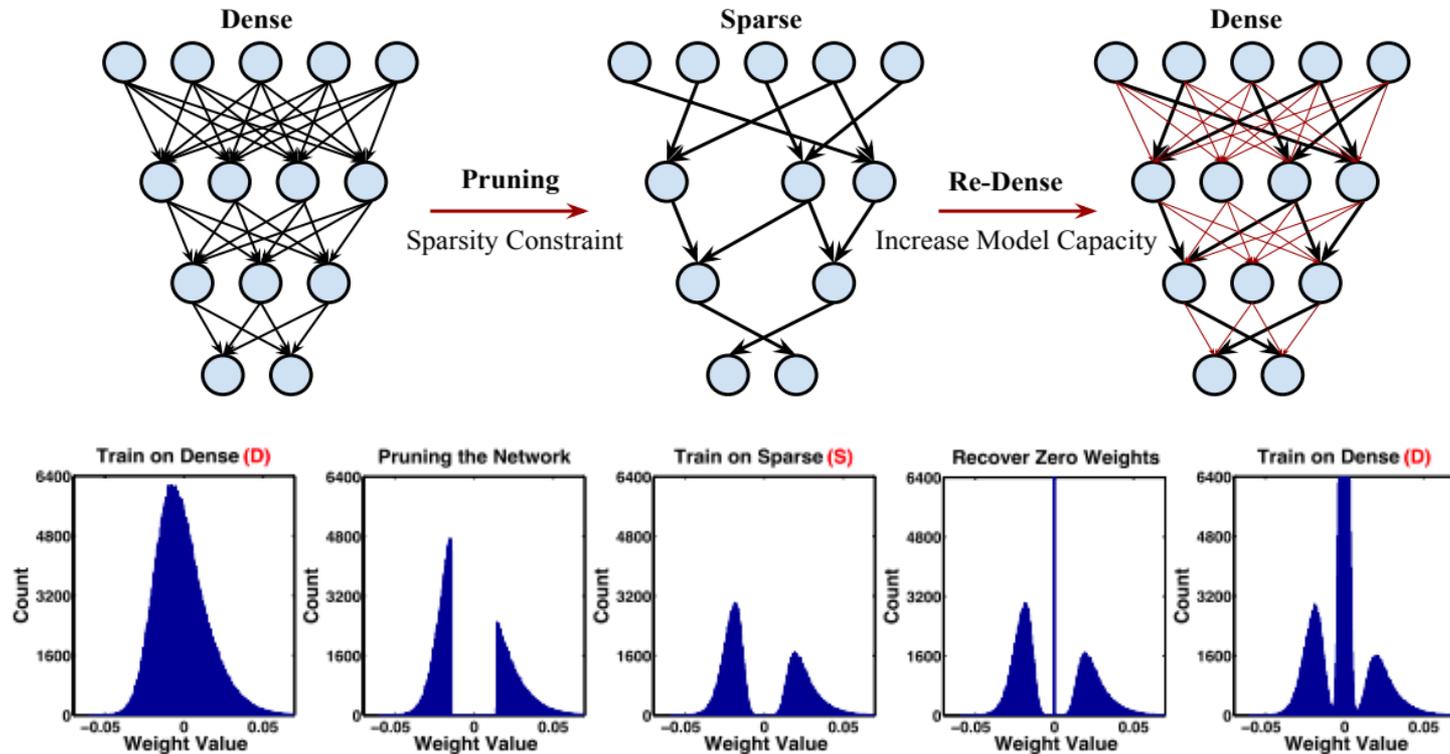
Table 3: Comparison of different filter pruning strategies on ResNet (Top-1 accuracy of unpruned network is 0.745)

- The compressibility of DNNs are NOT due to the specific criterion
 - ... but due to the **inherent plasticity** of DNNs

Next: Dense-Sparse-Dense

Network Re-wiring: Dense-Sparse-Dense Training Flow

- Network pruning preserves accuracy of the original network
- Han et al. (2017): **Re-wiring** the pruned connections improves DNNs further
 - “**Dense-Sparse-Dense**” training flow



Network Re-wiring: Dense-Sparse-Dense Training Flow

- Network pruning preserves accuracy of the original network
- Han et al. (2017): **Re-wiring** the pruned connections improves DNNs further
 - “**Dense-Sparse-Dense**” training flow
- Pruning discovers **better optimum** that the current training cannot find

Neural Network	Domain	Dataset	Type	Baseline	DSD	Abs. Imp.	Rel. Imp.
GoogLeNet	Vision	ImageNet	CNN	31.1% ¹	30.0%	1.1%	3.6%
VGG-16	Vision	ImageNet	CNN	31.5% ¹	27.2%	4.3%	13.7%
ResNet-18	Vision	ImageNet	CNN	30.4% ¹	29.2%	1.2%	4.1%
ResNet-50	Vision	ImageNet	CNN	24.0% ¹	22.9%	1.1%	4.6%
NeuralTalk	Caption	Flickr-8K	LSTM	16.8 ²	18.5	1.7	10.1%
DeepSpeech	Speech	WSJ'93	RNN	33.6% ³	31.6%	2.0%	5.8%
DeepSpeech-2	Speech	WSJ'93	RNN	14.5% ³	13.4%	1.1%	7.4%

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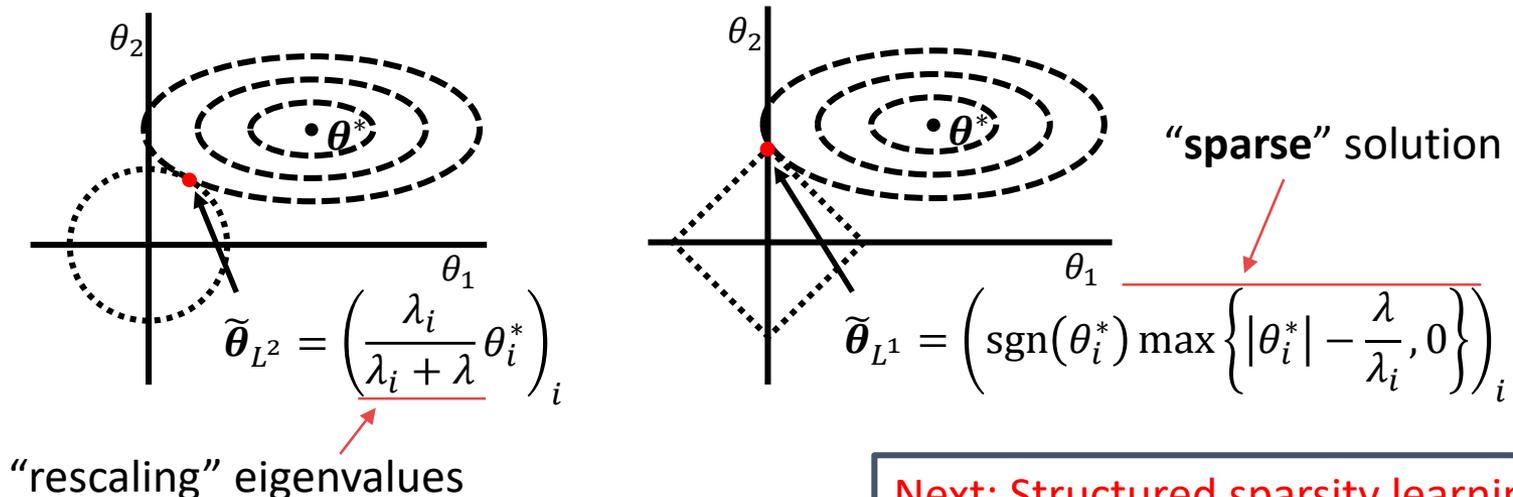
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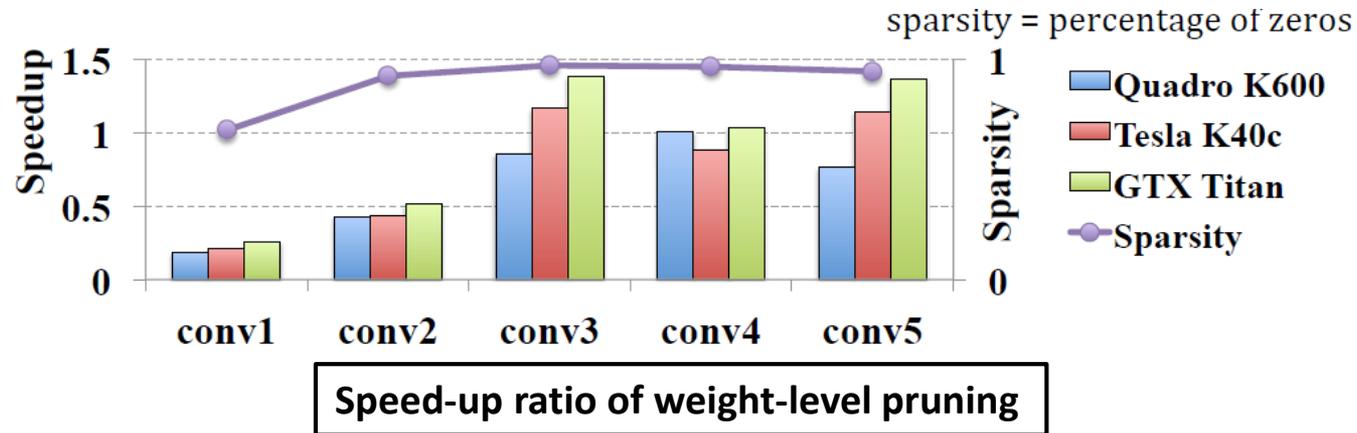
4. Summary

- The performance of pruning depends on the **initial training scheme**
 - e.g. Which regularization to use: L^2 or L^1 ?
- Which training scheme will **maximize** the pruning performance?
 - We still don't know about the optimal points of a DNN
- One prominent way: **Sparse network learning**
 - Inducing to a **sparse solution** from training a network
 - Weights with value 0 can safely be removed \Rightarrow it **does not** require re-training
- **Example:** L^1 -regularization



Next: Structured sparsity learning

- “Un-structured” **weight-level pruning** may not engage a **practical speed-up**
 - Despite of extremely high sparsity, actual speed-ups in GPU is limited



Non-structured sparsity (poor data pattern)



Structured sparsity (regular data pattern)



5× speedup after concatenation of nonzero rows and columns

- **Structured sparsity** can be induced by adding **group-lasso regularization**

$$\min_{\mathbf{W}} \mathcal{L}(\mathbf{W}) + \lambda \sum_{l=1}^L R_g(\mathbf{W}^{(l)}), \quad R_g(\mathbf{w}) = \sum_{g=1}^G \|\mathbf{w}^{(g)}\|_2$$

$G \leftarrow$ # groups

- **Filter-wise and channel-wise:**

$R_g(\mathbf{W}^{(l)}) = \sum_{n_l=1}^{N_l} \|\mathbf{W}_{n_l, :, :, :}^{(l)}\|_2 + \sum_{c_l=1}^{C_l} \|\mathbf{W}_{:, c_l, :, :}^{(l)}\|_2$

\nwarrow # filters
 \nwarrow # channels

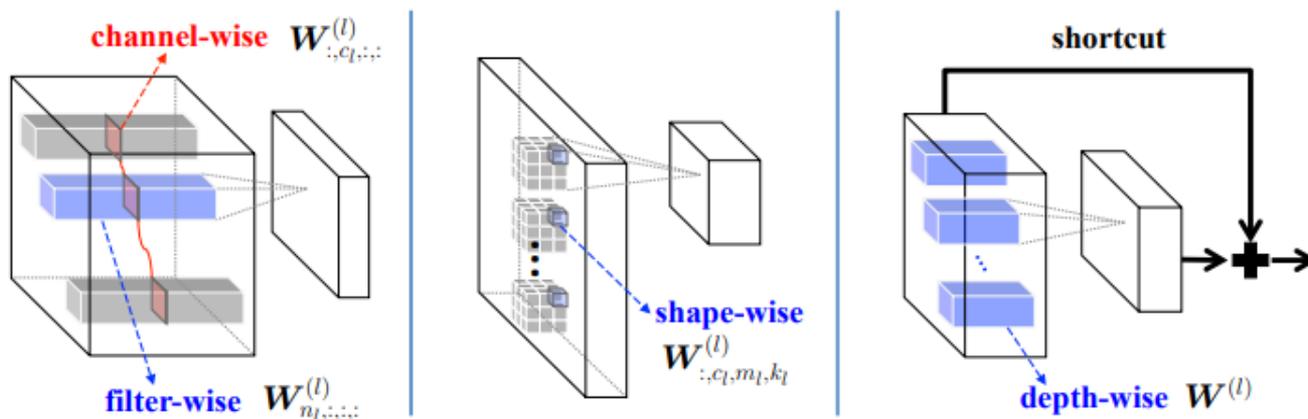
- **Shape-wise sparsity:**

$R_g(\mathbf{W}^{(l)}) = \sum_{c_l=1}^{C_l} \sum_{m_l=1}^{M_l} \sum_{k_l=1}^{K_l} \|\mathbf{W}_{:, c_l, m_l, k_l}^{(l)}\|_2$

\nwarrow width
 \nwarrow height

- **Depth-wise sparsity (applicable only for ResNet):**

$$R_g(\mathbf{W}^{(l)}) = \|\mathbf{W}^{(l)}\|_2$$



- **Structured sparsity** can be induced by adding **group-lasso regularization**

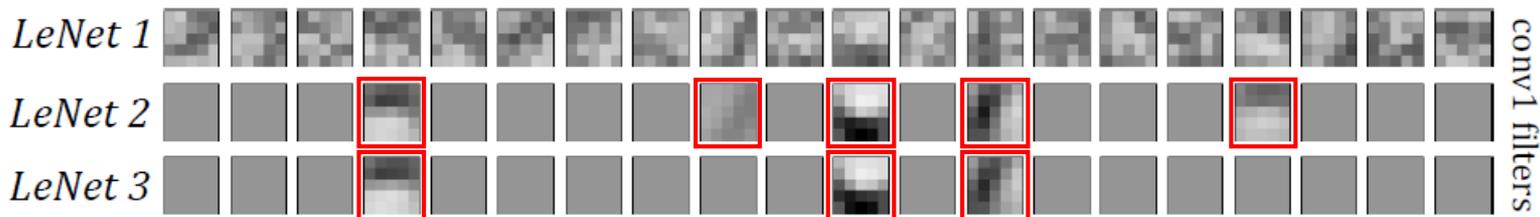
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- **Filter-wise and channel-wise:**
 - # filters
 - # channels
$$R_g(\mathbf{W}^{(l)}) = \sum_{n_l=1}^{N_l} \|\mathbf{W}_{n_l, :, :, :}^{(l)}\|_2 + \sum_{c_l=1}^{C_l} \|\mathbf{W}_{:, c_l, :, :}^{(l)}\|_2$$

Table 1: Results after penalizing unimportant filters and channels in *LeNet*

<i>LeNet</i> #	Error	Filter # [§]	Channel # [§]	FLOP [§]	Speedup [§]
1 (<i>baseline</i>)	0.9%	20—50	1—20	100%—100%	1.00×—1.00×
2	0.8%	5—19	1—4	25%—7.6%	1.64×—5.23×
3	1.0%	3—12	1—3	15%—3.6%	1.99×—7.44×

[§]In the order of *conv1—conv2*



Fewer but smoother feature extractors

- **Structured sparsity** can be induced by adding **group-lasso regularization**

$$\min_{\mathbf{W}} \mathcal{L}(\mathbf{W}) + \lambda \sum_{l=1}^L R_g(\mathbf{W}^{(l)}), \quad R_g(\mathbf{w}) = \sum_{g=1}^G \|\mathbf{w}^{(g)}\|_2$$

- **Shape-wise sparsity:**

$$R_g(\mathbf{W}^{(l)}) = \sum_{c_l=1}^{C_l} \sum_{m_l=1}^{M_l} \sum_{k_l=1}^{K_l} \|\mathbf{W}_{:,c_l,m_l,k_l}^{(l)}\|_2$$

width
height

Table 2: Results after learning filter shapes in *LeNet*

<i>LeNet</i> #	Error	Filter size [§]	Channel #	FLOP	Speedup
1 (<i>baseline</i>)	0.9%	25—500	1—20	100%—100%	1.00×—1.00×
4	0.8%	21—41	1—2	8.4%—8.2%	2.33×—6.93×
5	1.0%	7—14	1—1	1.4%—2.8%	5.19×—10.82×

[§] The sizes of filters after removing zero shape fibers, in the order of *conv1—conv2*



- **Structured sparsity** can be induced by adding **group-lasso regularization**

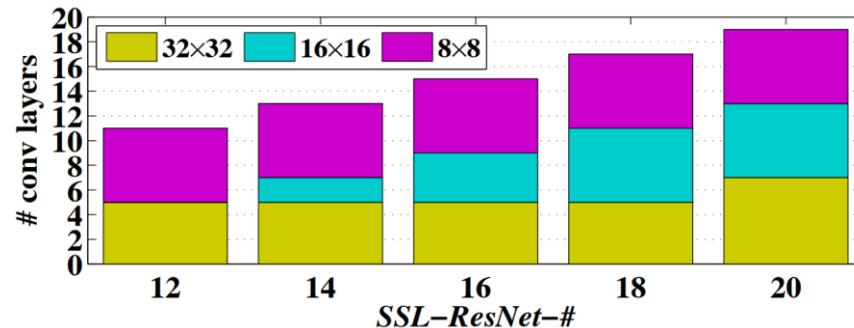
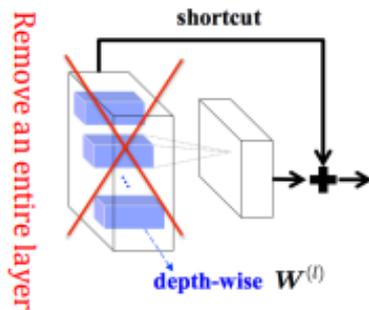
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- **Depth-wise sparsity:** $R_g(\mathbf{W}^{(l)}) = \|\mathbf{W}^{(l)}\|_2$

ResNet-20/32: baseline with 20/32 layers

SSL-ResNet-#: Ours with # layers after learning depth of ResNet-20

	# layers	error	# layers	error
ResNet	20	8.82%	32	7.51%
SSL-ResNet	14	8.54%	18	7.40%



Next: Sparsification via variational dropout

- **Variational dropout** (VD) allows to **learn** the dropout rates separately
- Unlike dropout, VD imposes noises on **weights θ** :

$$w_i := \theta_i \cdot \xi_i, \quad \text{where } p_{\alpha_i}(\xi_i) = \mathcal{N}(1, \alpha_i)$$

- A Bayesian generalization of Gaussian dropout [Srivastava et al., 2014]
 - $\mathbf{w} = (w_i)_i$ is **adapted to data** in Bayesian sense by optimizing α and θ
- **Re-parametrization trick** allows \mathbf{w} to be learned via minibatch-based gradient estimation methods [Kingma & Welling, 2013]
 - α and θ can be **optimized** separated from noises

$$w_i = \theta_i + (\theta_i \sqrt{\alpha_i}) \cdot \varepsilon_i, \quad \text{where } \varepsilon_i \sim \mathcal{N}(0, 1)$$

- VD imposes noises on weights θ :

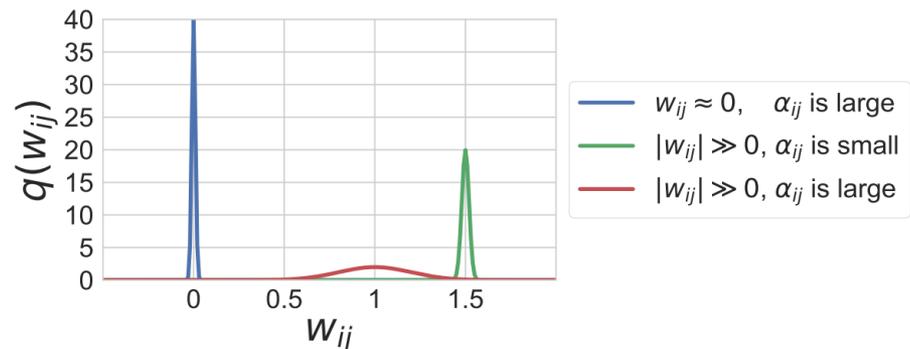
$$w_i := \theta_i \cdot \xi_i, \quad \text{where } p_{\alpha_i}(\xi_i) = \mathcal{N}(1, \alpha_i)$$

- The original VD set a **constraint** $\alpha_i \leq 1$ for technical reasons
 - It corresponds to $p \leq 0.5$ in binary dropout

Q. What if $\alpha_i > 1$? What happens when $\alpha_i \rightarrow \infty$?

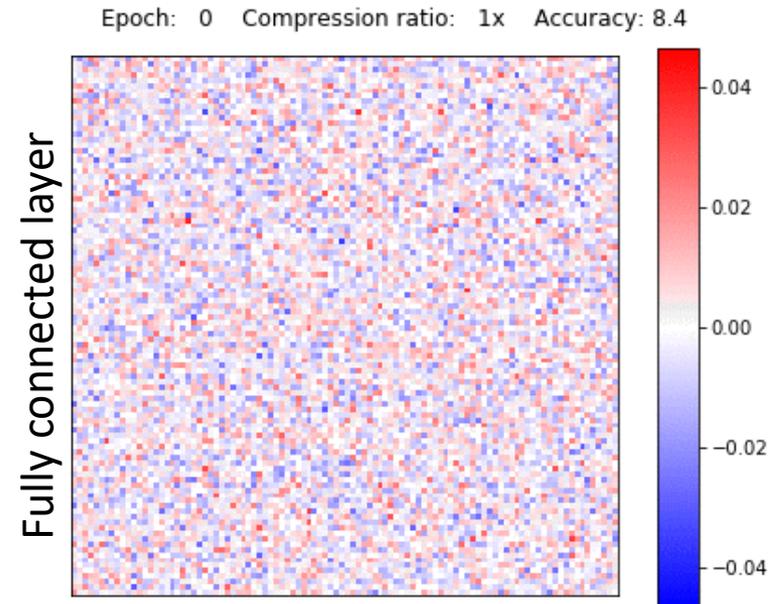
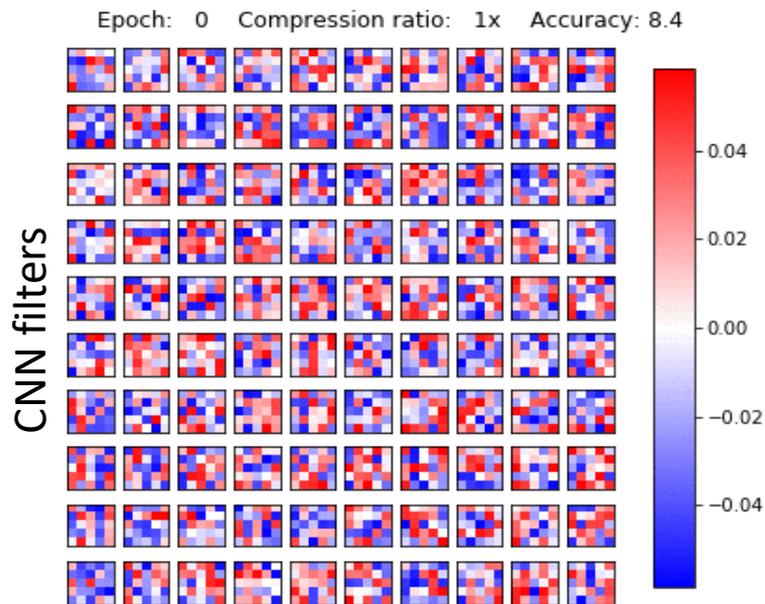
- $p(w_i) = \theta_i \cdot p(\xi_i) = \mathcal{N}(\theta_i, \alpha_i \theta_i^2)$
- w_i will be **completely random** as $\alpha_i \rightarrow \infty$
- Such w_i will **corrupt** the expected log likelihood
- ... **except** that $\theta_i \rightarrow 0$ as well!

$$\begin{aligned} \theta_{ij} \rightarrow 0, \quad \alpha_{ij} \theta_{ij}^2 \rightarrow 0 \\ \Downarrow \\ q(w_{ij} | \theta_{ij}, \alpha_{ij}) \rightarrow \mathcal{N}(w_{ij} | 0, 0) = \delta(w_{ij}) \end{aligned}$$



Q. What if $\alpha_i > 1$? What happens when $\alpha_i \rightarrow \infty$?

- It will **corrupt** the expected log likelihood **except** that $\theta_i \rightarrow 0$ as well
- Molchanov et al. (2017): **Extending VD for $\alpha_i > 1 \Rightarrow$ Super sparse solutions**
 - Weights with $\log \alpha > 3$ are pruned away during training



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Network	Method	Error %	Sparsity per Layer %	$\frac{ W }{ W_{\neq 0} }$
LeNet-300-100	Original	1.64		1
	Pruning	1.59	92.0 – 91.0 – 74.0	12 [Han et al., 2015]
	DNS	1.99	98.2 – 98.2 – 94.5	56
	SWS	1.94		23
	(ours) Sparse VD	1.92	98.9 – 97.2 – 62.0	68
LeNet-5-Caffe	Original	0.80		1
	Pruning	0.77	34 – 88 – 92.0 – 81	12 [Han et al., 2015]
	DNS	0.91	86 – 97 – 99.3 – 96	111
	SWS	0.97		200
	(ours) Sparse VD	0.75	67 – 98 – 99.8 – 95	280

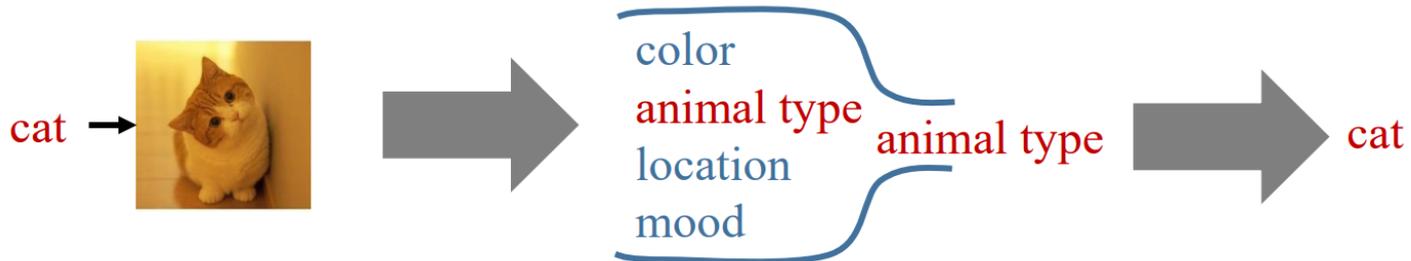
Next: Variational information bottleneck

- **Motivation:** Markov chain interpretation of DNN [Tishby & Zaslavsky, 2015]

$$y \rightarrow x = h_0 \rightarrow h_1 \rightarrow \dots \rightarrow \underline{h_{i-1}} \rightarrow \underline{h_i} \rightarrow \dots \rightarrow \underline{h_L} \rightarrow \hat{y}$$

$p(h_i | h_{i-1})$

Approximate $p(y | h_L)$
via tractable $p(\hat{y} | h_L)$



1. Maximize $I(h_i; y)$ for high-accuracy prediction
2. Minimize $I(h_i; h_{i-1})$ for compression \Rightarrow “**information bottleneck**”

- **Layer-wise losses** become:

$$\mathcal{L}_i = \gamma_i I(h_i; h_{i-1}) - I(h_i; y)$$

Mutual information
↙

↘
The relative strength of bottleneck

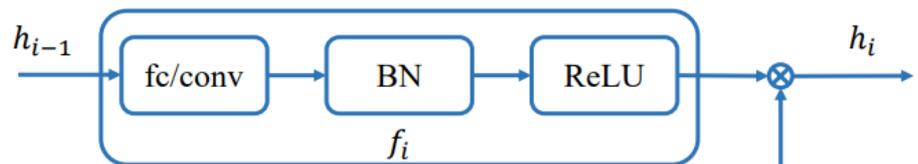
- **Layer-wise losses** become $\mathcal{L}_i = \gamma_i I(\mathbf{h}_i; \mathbf{h}_{i-1}) - I(\mathbf{h}_i; \mathbf{y})$
- **Problem:** Computing $I(\cdot; \cdot)$ is usually **intractable**
- Instead, we minimize **variational upper bound** of it

$$\mathcal{L}_i \leq \tilde{\mathcal{L}}_i = \gamma_i \mathbb{E}[\text{KL}(\underbrace{p(\mathbf{h}_i | \mathbf{h}_{i-1})}_{\text{variational approx. of } p(\mathbf{h}_i)} || \underbrace{q(\mathbf{h}_i)}_{\text{variational approx. of } p(\mathbf{y} | \mathbf{h}_L)})] - \mathbb{E}[\log \underbrace{q(\mathbf{y} | \mathbf{h}_L)}_{\substack{\text{multinomial for classification} \\ \text{Gaussian for regression}}}]$$

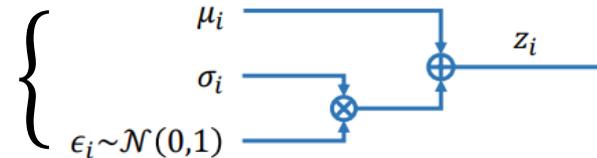
- **Variational Information Bottleneck (VIB) model**

$$p(\mathbf{h}_i | \mathbf{h}_{i-1}) := f_i(\mathbf{h}_{i-1}) \odot \mathcal{N}(\mathbf{h}_i | \boldsymbol{\mu}_i, \text{diag}(\boldsymbol{\sigma}_i^2))$$

$$q(\mathbf{h}_i) := \mathcal{N}(\mathbf{h}_i | \mathbf{0}, \text{diag}(\boldsymbol{\xi}_i))$$



Reparametrization trick
[Kingma & Welling, 2013]



- We minimize **variational upper bound** of \mathcal{L}_i

$$\mathcal{L}_i \leq \tilde{\mathcal{L}}_i = \gamma_i \mathbb{E}[\text{KL}(p(\mathbf{h}_i | \mathbf{h}_{i-1}) || q(\mathbf{h}_i))] - \mathbb{E}[\log q(\mathbf{y} | \mathbf{h}_L)]$$

- Final variational objective function (**VIBNet**):

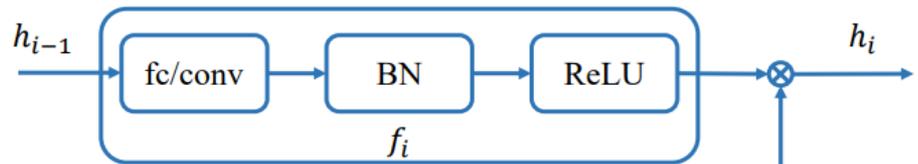
$$\tilde{\mathcal{L}} = \underbrace{\sum_{i=1}^L \gamma_i \sum_j \log \left(1 + \frac{\mu_{ij}^2}{\sigma_{ij}^2} \right)}_{\text{regularization}} - \underbrace{L \cdot \mathbb{E}[\log q(\mathbf{y} | \mathbf{h}_L)]}_{\text{data-fit}}$$

layers

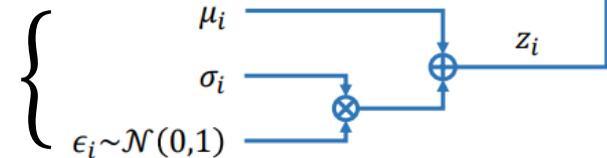
↓

- Pruning criteria:** $\alpha_{ij} := \frac{\mu_{ij}^2}{\sigma_{ij}^2} \rightarrow 0$

- Neurons with **low value** of α_{ij} 's are pruned after training



Reparametrization trick
[Kingma & Welling, 2013]

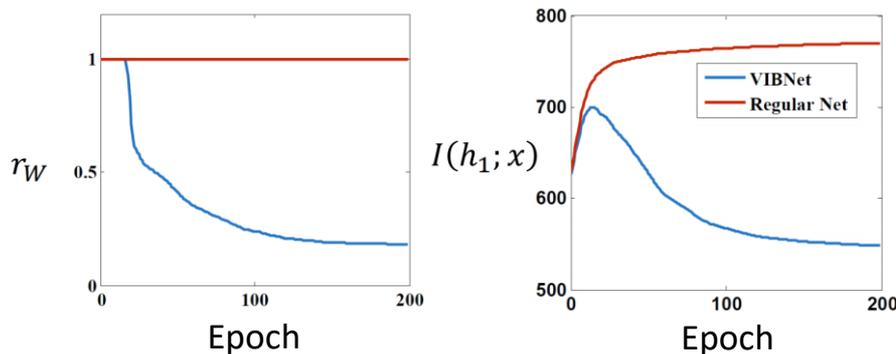


- **VIBNet** outperforms various methods by large margins

- $r_W(\%)$: ratio of # parameters
- $r_N(\%)$: ratio of memory footprint

Method	$r_W(\%)$	$r_N(\%)$	error(%)	Pruned Model
VD	25.28	58.95	1.8	512-114-72
BC-GNJ	10.76	32.85	1.8	278-98-13
BC-GHS	10.55	34.71	1.8	311-86-14
L0	26.02	45.02	1.4	219-214-100
L0-sep	10.01	32.69	1.8	266-88-33
DN	23.05	57.94	1.8	542-83-61
VIBNet	3.59	16.98	1.6	97-71-33

Table 1. Compression results on MNIST using LeNet-300-100.



After fine-tuning

Method	$r_W(\%)$	FLOP(Mil)	$r_N(\%)$	error(%)
BC-GNJ	6.57	141.5	81.68	8.6
BC-GHS	5.40	121.9	74.82	9.0
VIBNet	5.30	70.63	49.57	8.8 (8.5)
PF	35.99	206.3	83.97	6.6
SBP	7.01	136.0	80.72	7.5
SBPa	5.78	99.20	66.46	9.0
VIBNet	5.45	86.82	57.86	6.5 (6.1)
NS-Single	11.50	195.5	-	6.2
NS-Best	8.60	147.0	-	5.9
VIBNet	5.79	116.0	59.60	6.2 (5.8)

Table 3. Compression results on CIFAR10 using VGG-16.

Method	$r_W(\%)$	FLOP(Mil)	$r_N(\%)$	error(%)
RNP	-	160	-	38.0
VIBNet	22.75	133.6	59.80	37.6 (37.4)
NS-Single	24.90	250.5	-	26.5
NS-Best	20.80	214.8	-	26.0
VIBNet	15.08	203.1	73.80	25.9 (25.7)

Table 4. Compression results on CIFAR100 using VGG-16.

1. Network Pruning and Re-wiring

- Optimal brain damage
- Pruning modern DNNs
- Dense-Sparse-Dense training flow

2. Sparse Network Learning

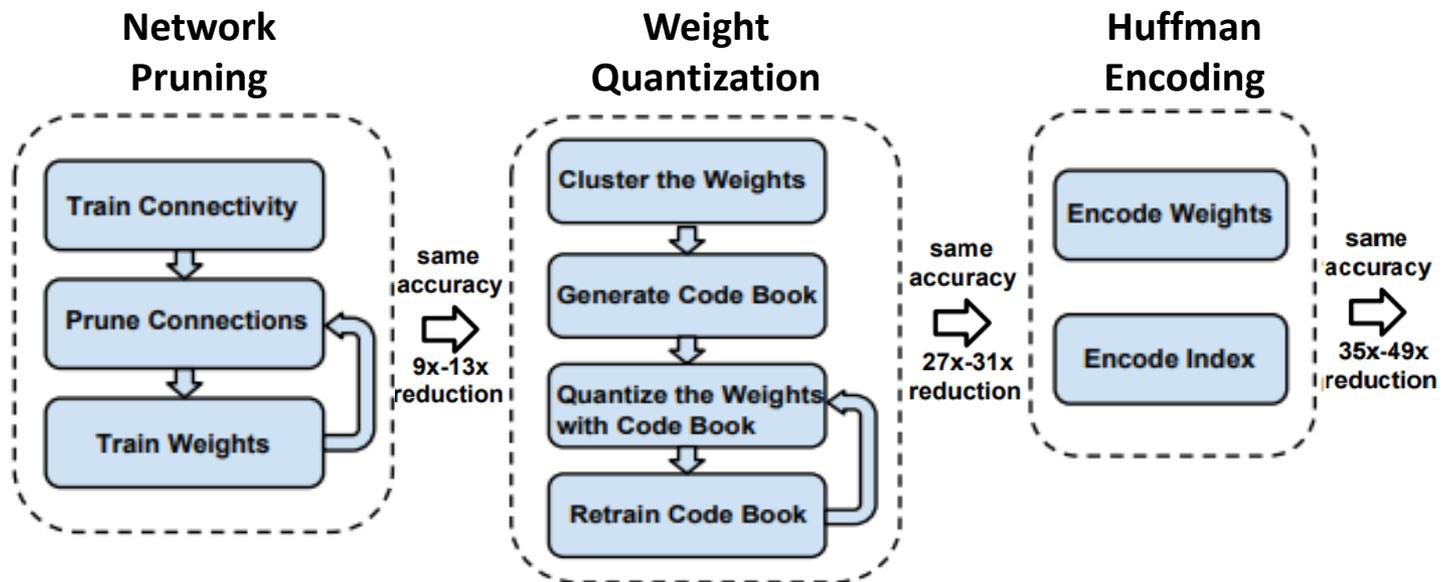
- Structured sparsity learning
- Sparsification via variational dropout
- Variational information bottleneck

3. Weight Quantization

- Deep compression
- Binarized neural networks

4. Summary

- **Quantizing weights** can further compress the pruned networks
 - Weights are **clustered** into discrete values
 - The network is represented only with several **centroid values**
- Han et al. (2015): Pruning DNNs \Rightarrow 9x-13x reduction
- Han et al. (2016): Pruning + **Quantization** + **Huffman** \Rightarrow **35x-49x** reduction



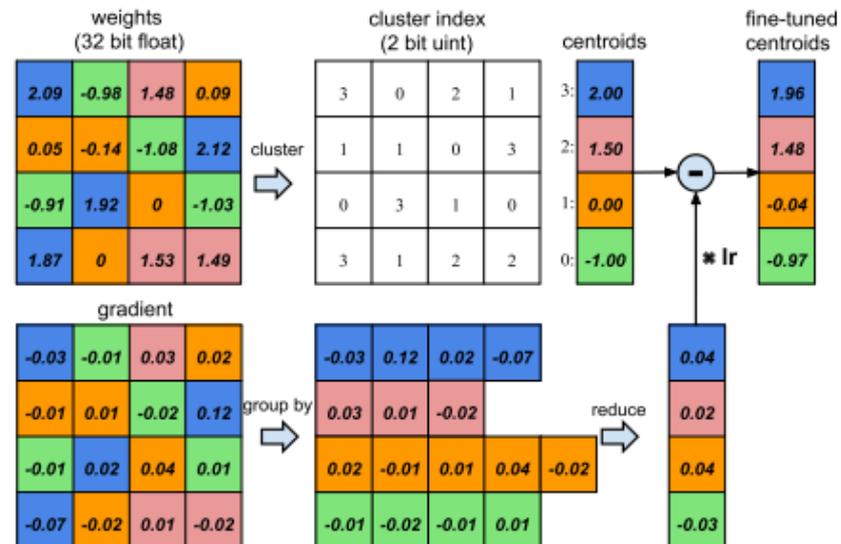
- **Quantizing weights** can further compress the pruned networks
 - Weights are **clustered** into discrete values
 - The network is represented only with several centroid values

1. **Train** a deep model until convergence
2. **Find** k clusters that minimizes **within-cluster sum of squares (WCSS)**:

$$\operatorname{argmin}_C \sum_{i=1}^k \sum_{w \in c_i} |w - c_i|^2$$
3. **Quantize** with the cluster C via weight sharing
4. **Fine-tune** the network with the shared weights

- In the **fine-tuning** phase, gradients in each cluster are **aggregated**:

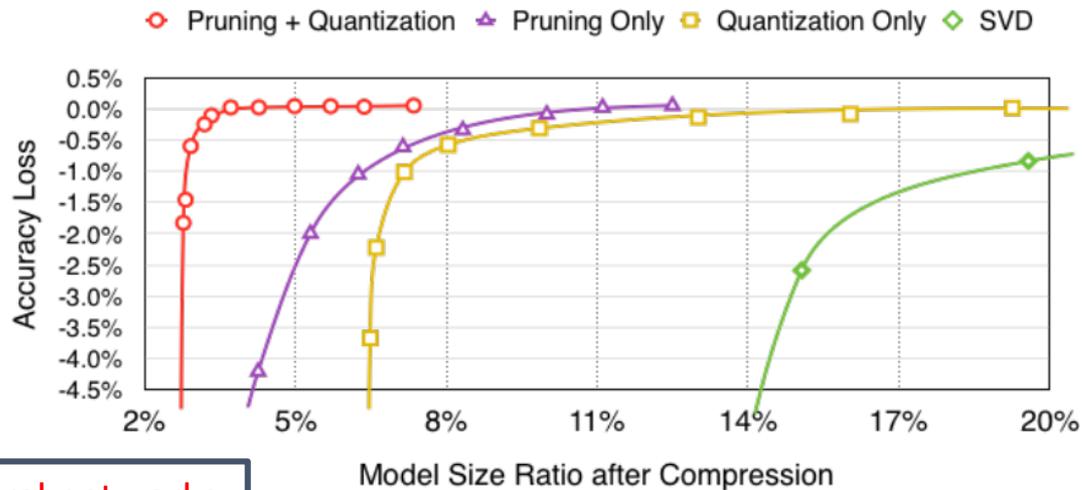
$$\begin{aligned} \frac{\partial \mathcal{L}}{\partial C_k} &= \sum_{i,j} \frac{\partial \mathcal{L}}{\partial W_{ij}} \frac{\partial W_{ij}}{\partial C_k} \\ &= \sum_{i,j} \frac{\partial \mathcal{L}}{\partial W_{ij}} \mathbf{1}(W_{ij} \in C_k) \end{aligned}$$



*source : Han et al., "Deep Compression - Compressing Deep Neural Networks with Pruning, Trained Quantization and Huffman Coding", ICLR 2016

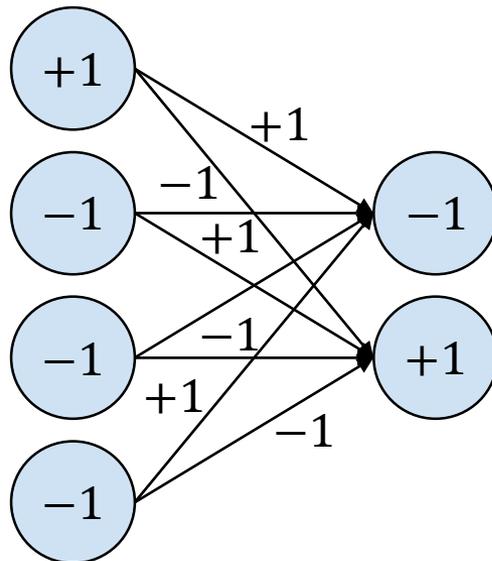
- **Deep compression** reduces the model size significantly

Network	Original Size	Compressed Size	Compression Ratio	Original Accuracy (%)	Compressed Accuracy (%)
LeNet-300	1070KB →	27KB	40x	98.36 →	98.42
LeNet-5	1720KB →	44KB	39x	99.20 →	99.26
AlexNet	240MB →	6.9MB	35x	80.27 →	80.30
VGGNet	550MB →	11.3MB	49x	88.68 →	89.09
GoogLeNet	28MB →	2.8MB	10x	88.90 →	88.92
SqueezeNet	4.8MB →	0.47MB	10x	80.32 →	80.35

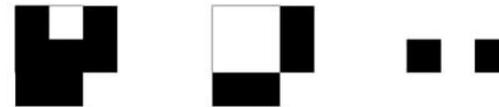


Next: Binarized neural networks

- Neural networks can be even **binarized** (+1 or -1)
 - DNNs trained to use **binary** weights and **binary** activations
- Expensive **32-bit MAC (Multiply-ACcumulate)** \Rightarrow Cheap **1-bit XNOR-Count**
 - “MAC == XNOR-Count”: when the weights and activations are ± 1 ↖
1s in bits



Binarized weights



Binarized feature maps

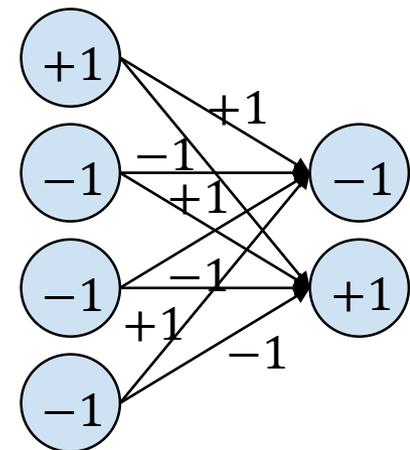


- **Idea:** Training real-valued nets (W_r) treating binarization (W_b) **as noise**
 - Training W_r is done by **stochastic gradient descent**
- **Binarization** ($W_r \rightarrow W_b$) occurs for each forward propagation
 - On each of **weights**: $W_b = \text{sign}(W_r)$
 - ... also on each **activation**: $a_b = \text{sign}(a_r)$
- Gradients for W_r is estimated from $\frac{\partial L}{\partial W_b}$ [Bengio et al., 2013]
 - “Straight-through estimator”: **ignore** the binarization during backward!

$$\frac{\partial L}{\partial W_r} = \frac{\partial L}{\partial W_b} \mathbf{1}_{|W_r| \leq 1}$$

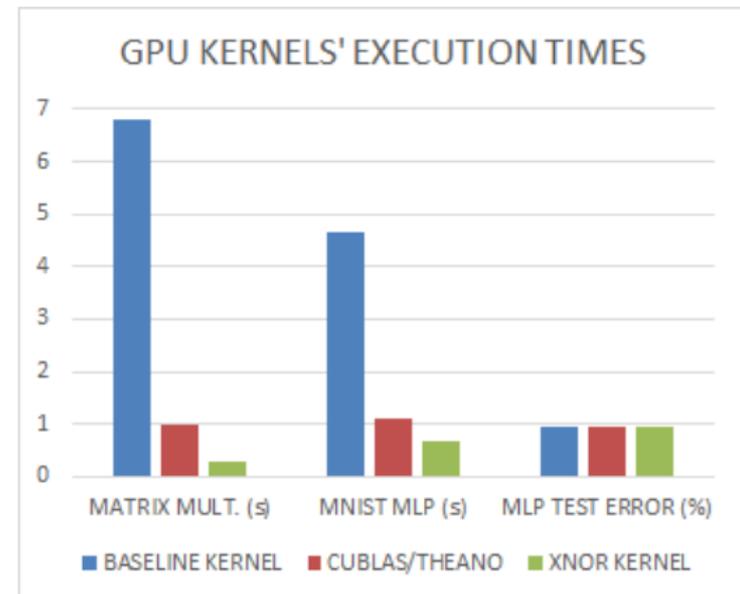
$$\frac{\partial L}{\partial a_r} = \frac{\partial L}{\partial a_b} \mathbf{1}_{|a_r| \leq 1}$$

- Cancelling gradients for better performance
 - When the value is too large



- Neural networks can be even **binarized (+1 or -1)**
 - DNNs trained to use **binary** weights and **binary** activations
- BNN yields **32x less memory** compared to the baseline 32-bit DNNs
 - ... also expected to reduce energy consumption drastically
- **23x faster** on kernel execution times
 - BNN allows us to use XNOR kernels
 - **3.4x** faster than cuBLAS

Operation	MUL	ADD
8bit Integer	0.2pJ	0.03pJ
32bit Integer	3.1pJ	0.1pJ
16bit Floating Point	1.1pJ	0.4pJ
32bit Floating Point	3.7pJ	0.9pJ



Binarized Neural Networks [Hubara et al., 2016]

- Neural networks can be even **binarized** (+1 or -1)
 - DNNs trained to use **binary** weights and **binary** activations
- **BNN** achieves comparable error rates over existing DNNs

Data set	MNIST	SVHN	CIFAR-10
Binarized activations+weights, during training and test			
BNN (Torch7)	1.40%	2.53%	10.15%
BNN (Theano)	0.96%	2.80%	11.40%
Committee Machines' Array (Baldassi et al., 2015)	1.35%	-	-
Binarized weights, during training and test			
BinaryConnect (Courbariaux et al., 2015)	1.29 ± 0.08%	2.30%	9.90%
Binarized activations+weights, during test			
EBP (Cheng et al., 2015)	2.2 ± 0.1%	-	-
Bitwise DNNs (Kim & Smaragdis, 2016)	1.33%	-	-
Ternary weights, binary activations, during test			
(Hwang & Sung, 2014)	1.45%	-	-
No binarization (standard results)			
Maxout Networks (Goodfellow et al.)	0.94%	2.47%	11.68%
Network in Network (Lin et al.)	-	2.35%	10.41%
Gated pooling (Lee et al., 2015)	-	1.69%	7.62%

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4. Summary

- **Broad economic viability requires energy efficient AI** [Welling, 2018]
 - “Energy efficiency of a brain is **100x better** than current hardware”
 - “AI algorithms will be measured by **the amount of intelligence per kWh**”
- **Network pruning and re-wiring**
 - A **simple but effective** way to compress DNNs
 - Allow us to find **better optimum** that the current training cannot
- **Sparse network learning**
 - Which training scheme will **maximize** the pruning performance?
 - It has gained significant attention recently
- **Various other techniques have been also proposed**
 - Weight quantization
 - Anytime/adaptive networks [Huang et al., 2018]
 - ...

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